



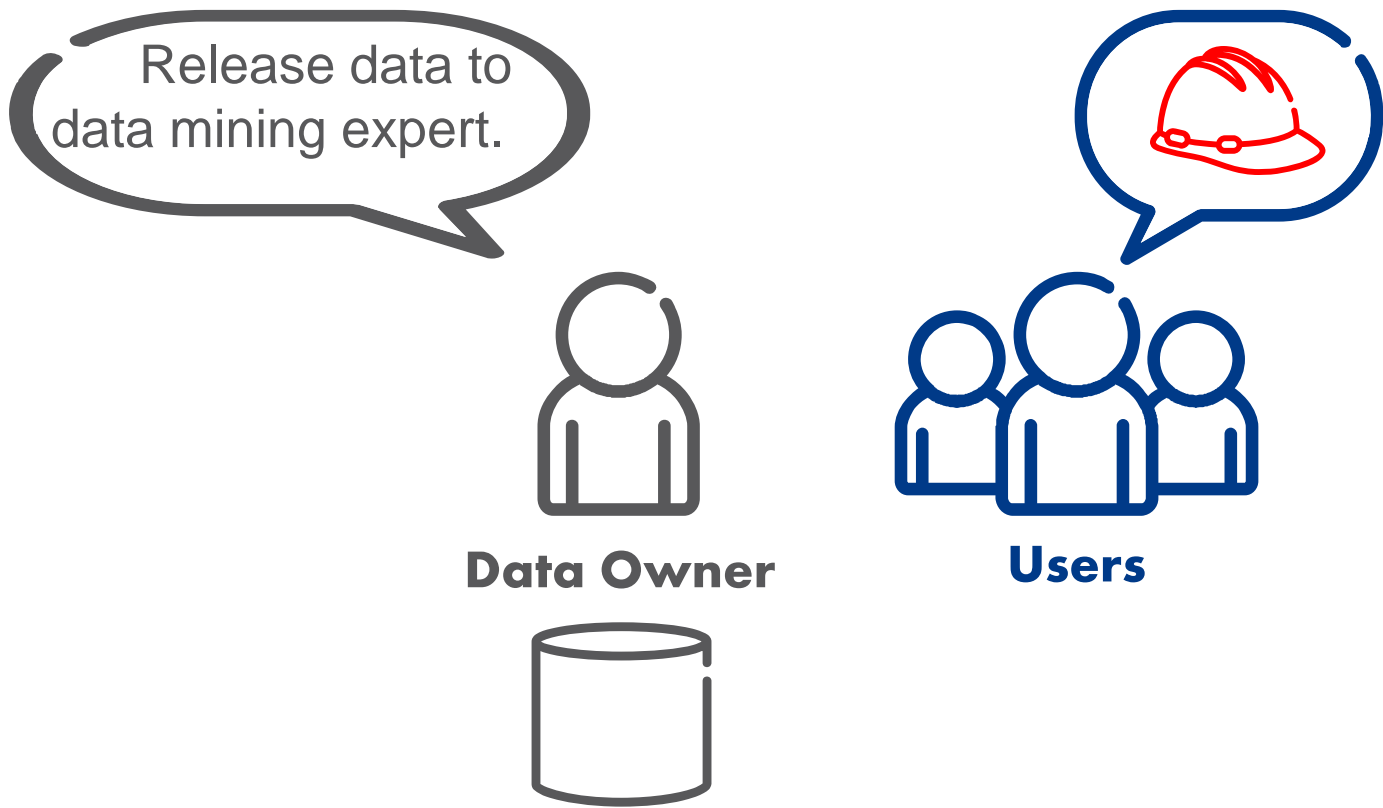
PRIVACY PRESERVING DATA PUBLISHING FOR RECOMMENDER SYSTEM

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OUTLINE

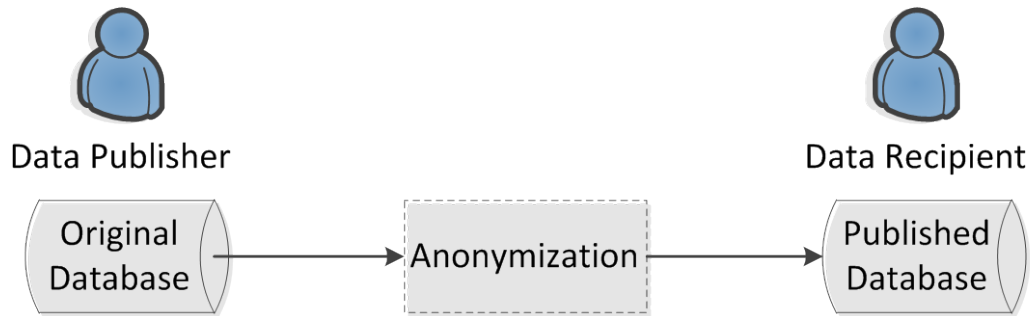
- › Motivation
- › Related Work
- › Proposed Approach
- › Bisecting K-Gather (BKG) Algorithm
- › BKG Algorithm Evaluation
- › Bisecting One-K-Gather (BOKG) Algorithm
- › BOKG Evaluation
- › Conclusions

MOTIVATION



PROBLEM STATEMENT

› Privacy Preserving Data Publishing



› Recommender system:

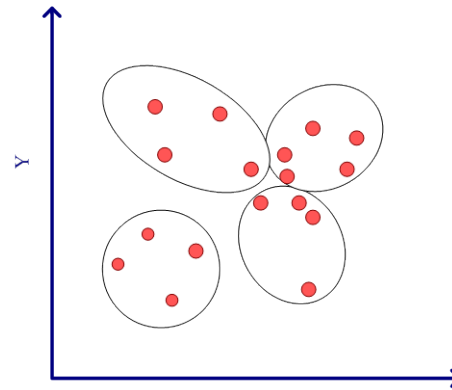
- Ordinal data
- High dimensionality
- Sparsity

	Movie 1	Movie 2	Movie 3	Movie 4	Movie 5	Movie 6	Movie 7	Movie 8	Movie 9	...
User 1	1	0	2	0	0	5	5	0	0	...
User 2	2	0	0	0	0	4	5	0	0	...
User 3	5	4	0	4	0	0	0	0	0	...
User 4	5	4	0	0	0	3	0	0	0	...
User 5	4	5	0	4	0	0	0	0	0	...

BACKGROUND

› K-anonymity

- intuitively, hide each individual among k-1 others
- K-gather clustering



A possible solution for 4 member clustering

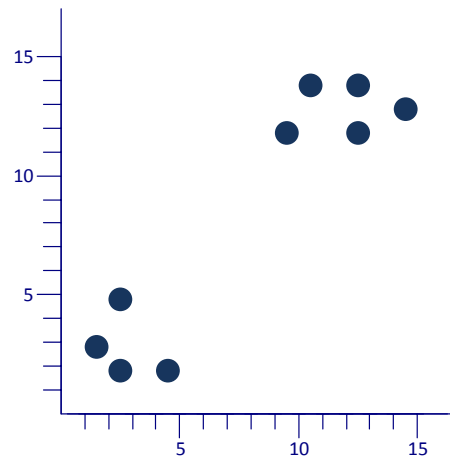
	Movie 1	Movie 2	Movie 3	Movie 4	Movie 5	Movie 6	Movie 7
User 1	1		2			5	5
User 2	2					4	5
User 3	5	4		4			
User 4	5	4				3	
User 5	4	5		4			

homogenized
→

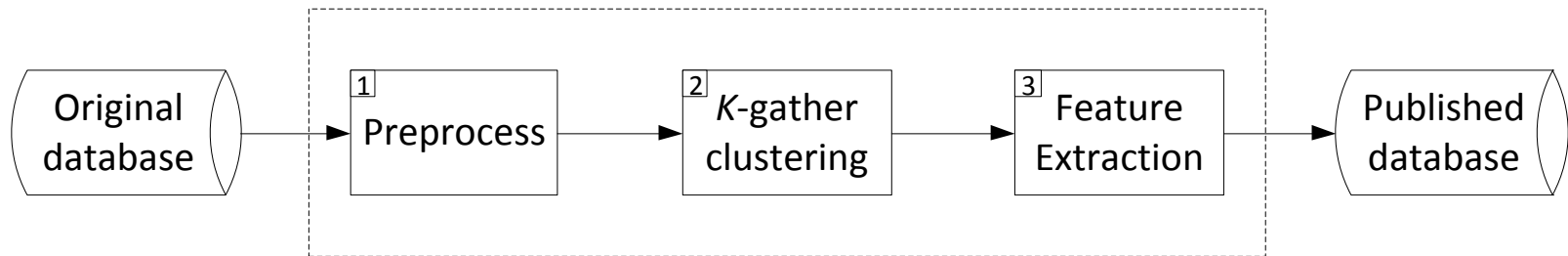
	Movie 1	Movie 2	Movie 3	Movie 4	Movie 5	Movie 6	Movie 7	#
Group 1	1.5		2			4.5	5	2
Group 2	4.67	4.33		4		3		3

CHALLENGES

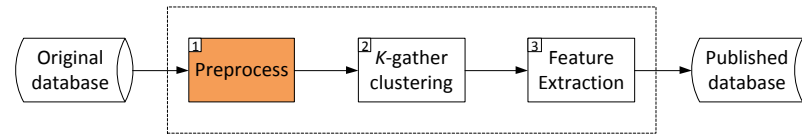
- › Inherent features of recommender system
 - High dimensionality
 - Sparsity
- › Drawback of fixed k-gather algorithms
 - $\lfloor \frac{n}{k} \rfloor$ clusters all of size k.



SOLUTION



SOLUTION

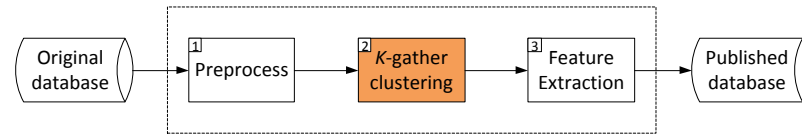


	Action	Animation	Comedy	Crime	Romance	Sci-Fi	Thriller	..
User 1	3	-0.3	0.1	2.1	-3	1.5	1	

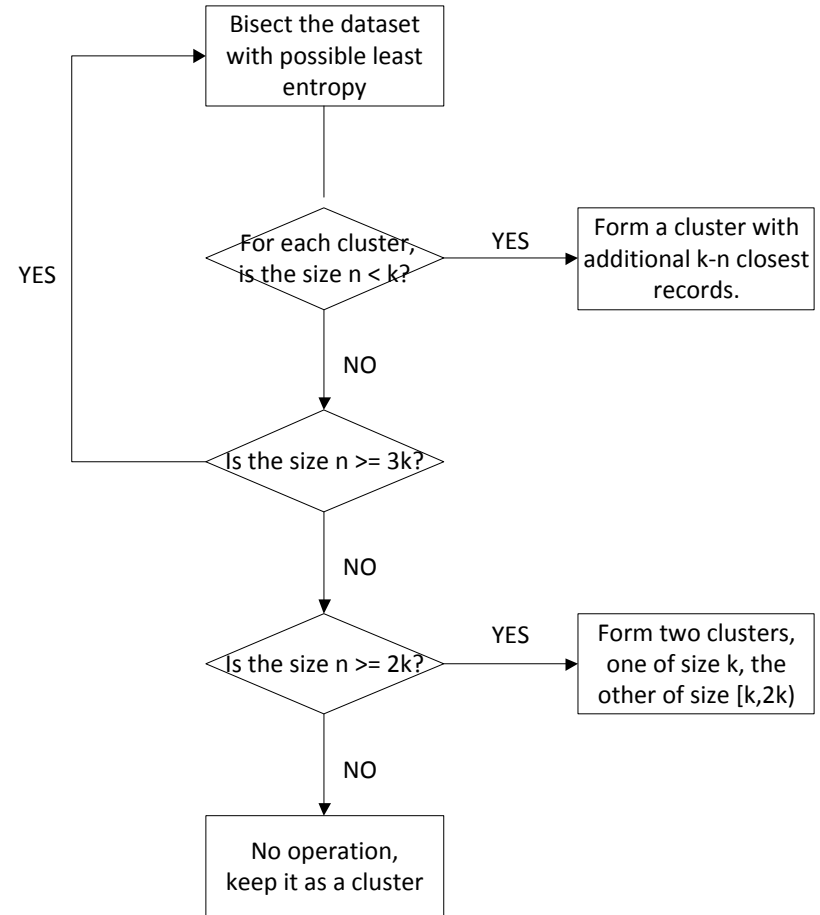
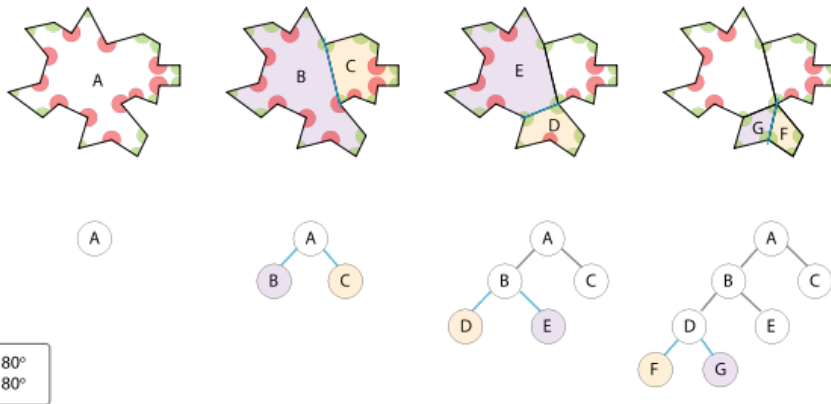
	Action	Animation	Comedy	Crime	Romance	Sci-Fi	Thriller	..
Movie 1	1	0.1	1.4	-2	2	-0.2	-0.2	

$$R_{11} = 3 * 1 + (-0.3) * 0.1 + \dots$$

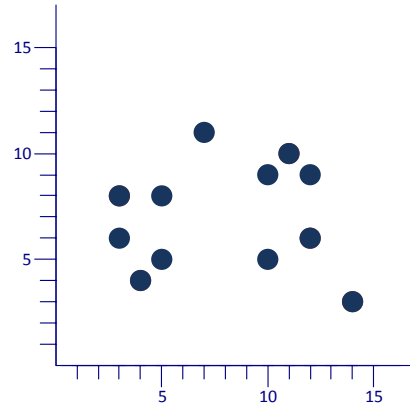
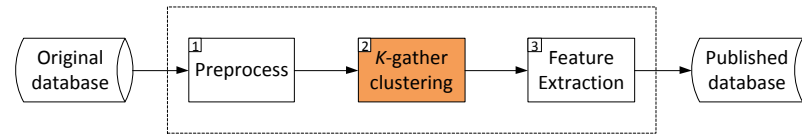
SOLUTION



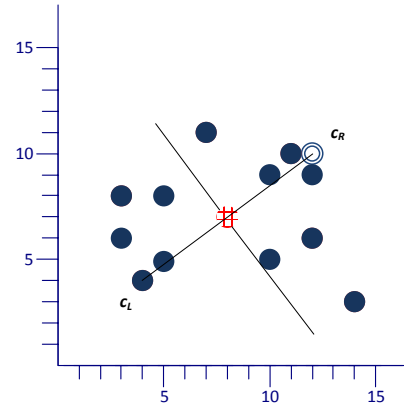
- > K-gather clustering
 - Bisecting K-Gather
 - Non-fixed approach
 - V.S. fixed approach
 - > Bounded T-Means



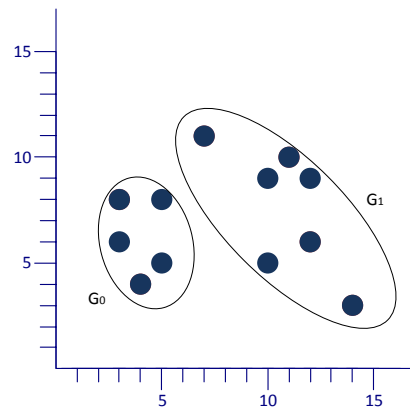
SOLUTION



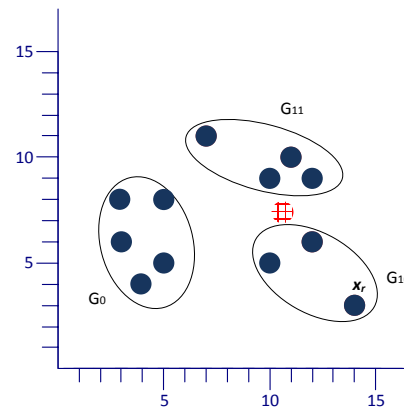
(a). Initial dataset



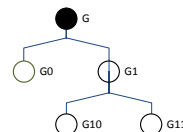
(b). Compute the centroid (in grid), bisect dataset based on two chosen points (c_L, c_R)



(c). Two clusters G_0 and G_1 generated after first bisection

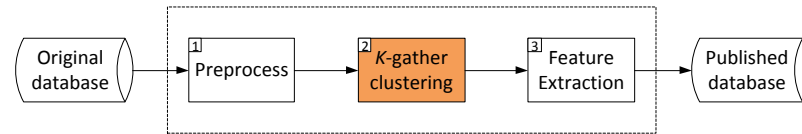


(d). G_0 satisfies criteria, while G_1 is of $[2k, 3k]$, further divide G_1 to two clusters, x_r is the most distant point to centroid of G_1 (in grid)

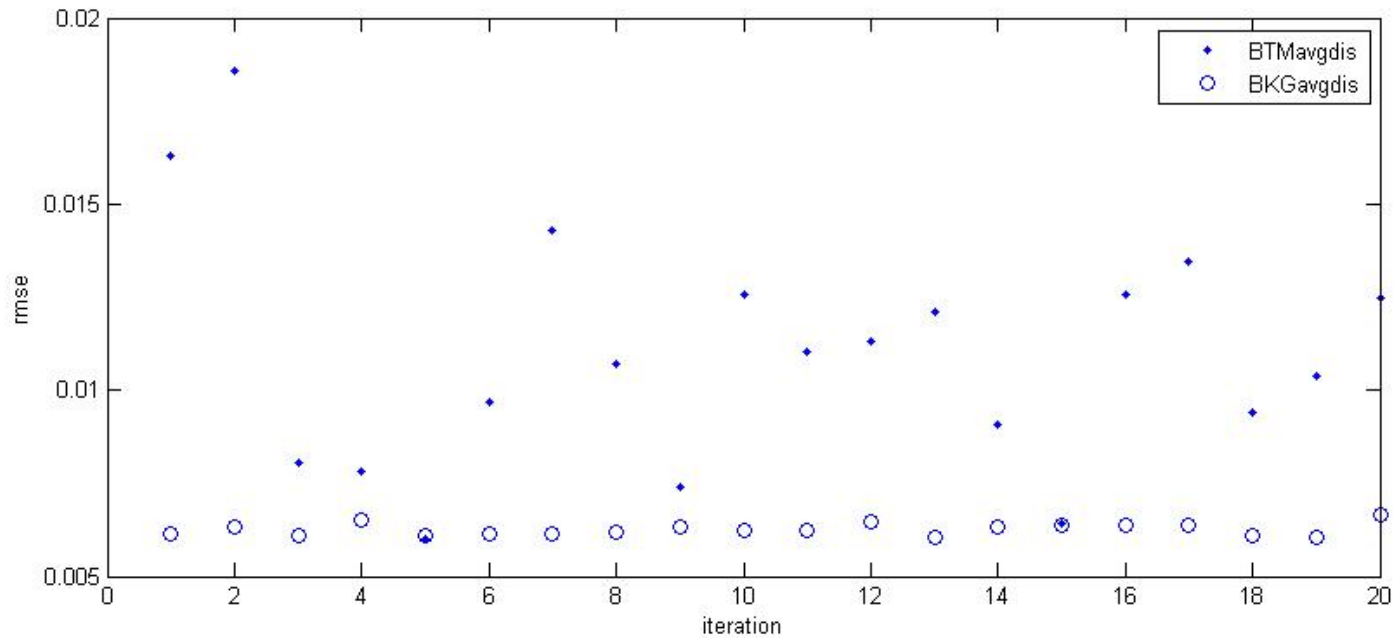


(e). A tree construction representation

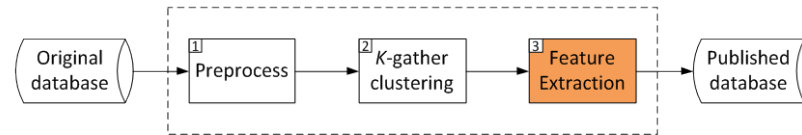
SOLUTION



› Comparison with BTM.

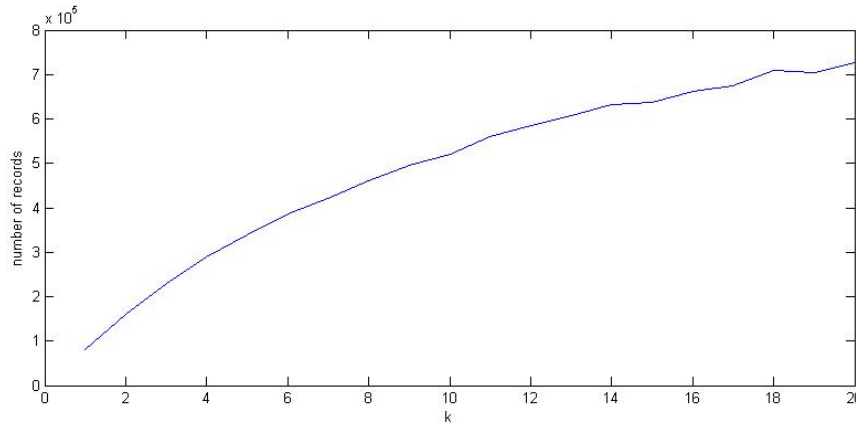


SOLUTION



› Feature Extraction

- Compute average ratings over only users who rated that movie.
- Anonymize the ratings within each cluster.
- So, some unrated entries will get values after anonymization. the total number of entries increases with k.



	Movie 1	Movie 2	Movie 3	Movie 4	Movie 5	Movie 6	Movie 7
User 1	1					5	5
User 2	2					4	5
User 3	5	4		4			
User 4	5	4				3	
User 5	4	5		4			

homogenized →

	Movie 1	Movie 2	Movie 3	Movie 4	Movie 5	Movie 6	Movie 7	#
Group 1	1.5		2			4.5	5	2
Group 2	4.674.33		4		3			3

UTILITY EVALUATION

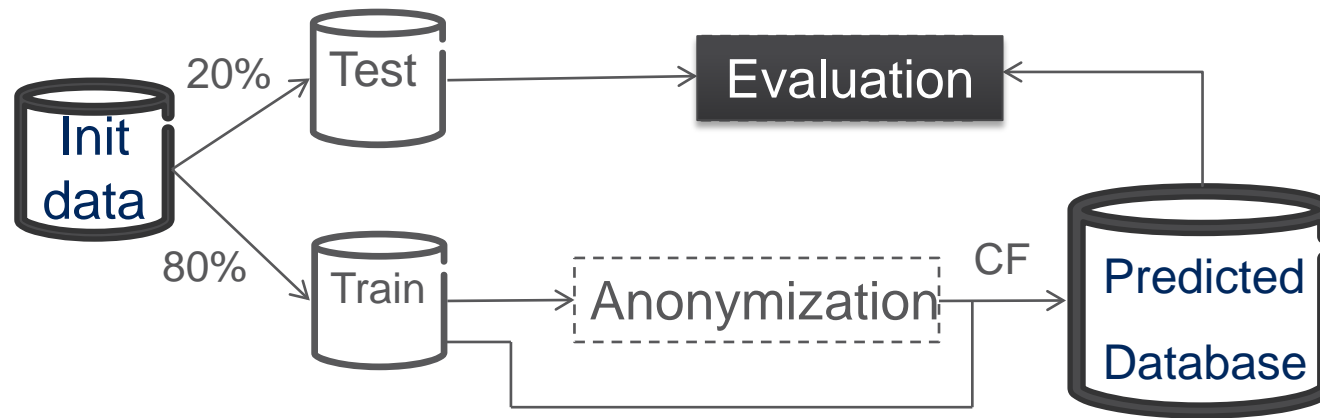
› Method

– Database: MovieLens

- › 100K ratings of 1682 movies by 943 users.
- › Ratings follow the 1 (bad) to 5 (excellent) numerical scales.
- › The sparsity of the data set is high, at a value of 93.7%.

– Measure of Prediction Accuracy: MAE

$$\text{MAE} = \frac{1}{T} \sum_{t=1}^T |x_p - \hat{x}|$$

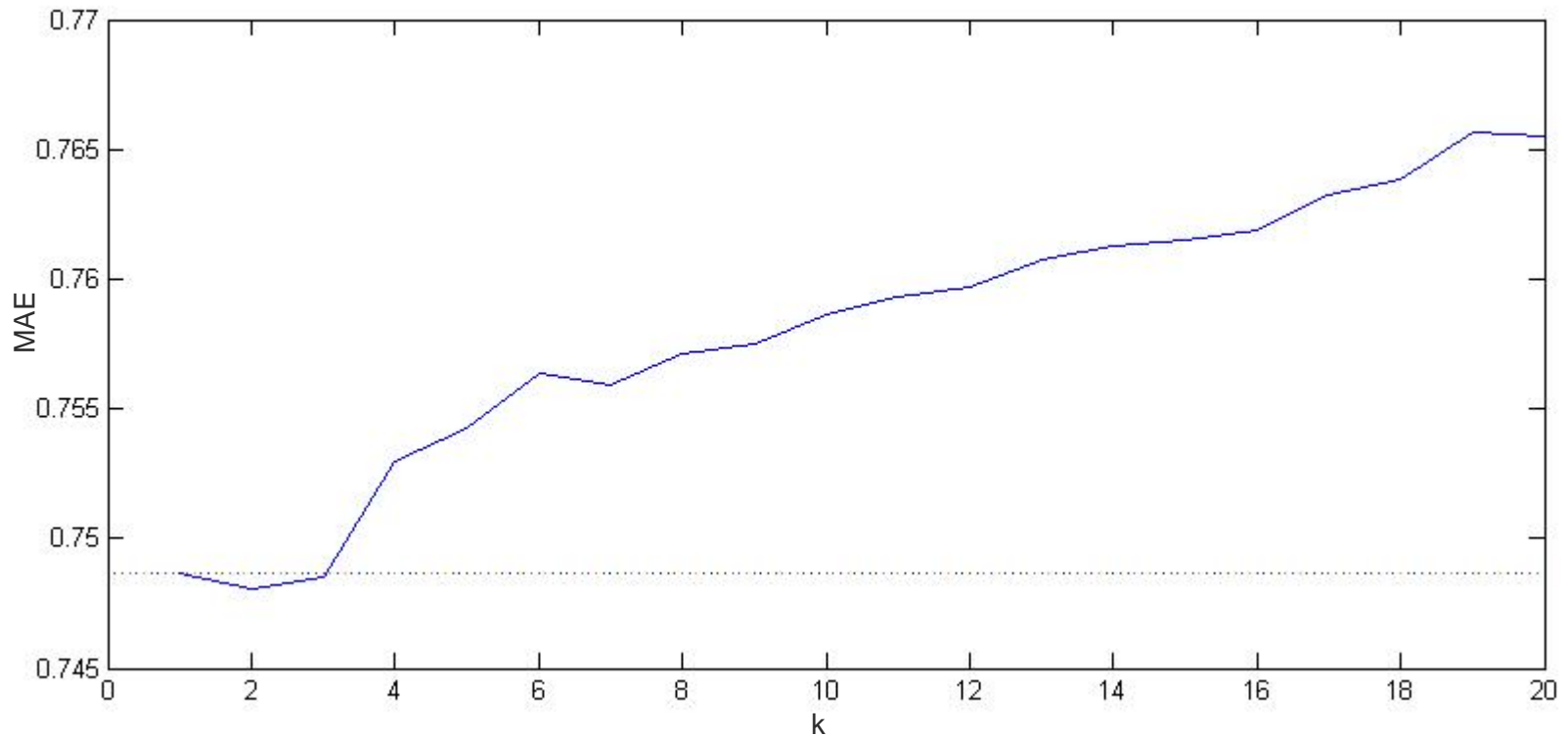


UTILITY EVALUATION

› Results

– $K=1$, 0.748

– $K=943$, 0.815



CUSTOMIZED K-ANONYMITY

› Motivation

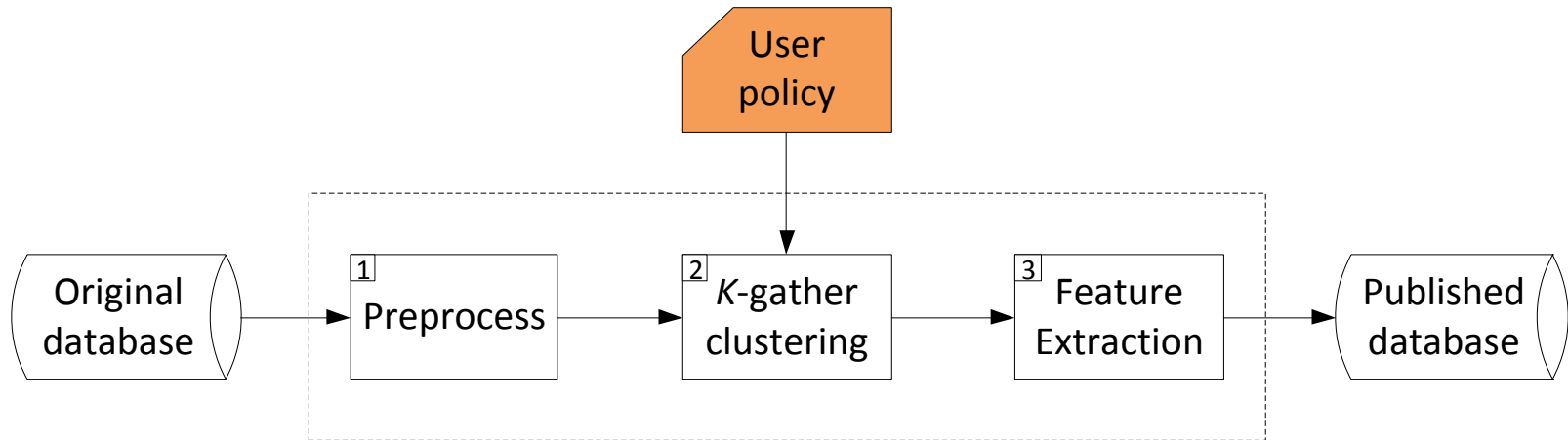


› Hypothesis

- **User of lower privacy level can get better recommendation.**

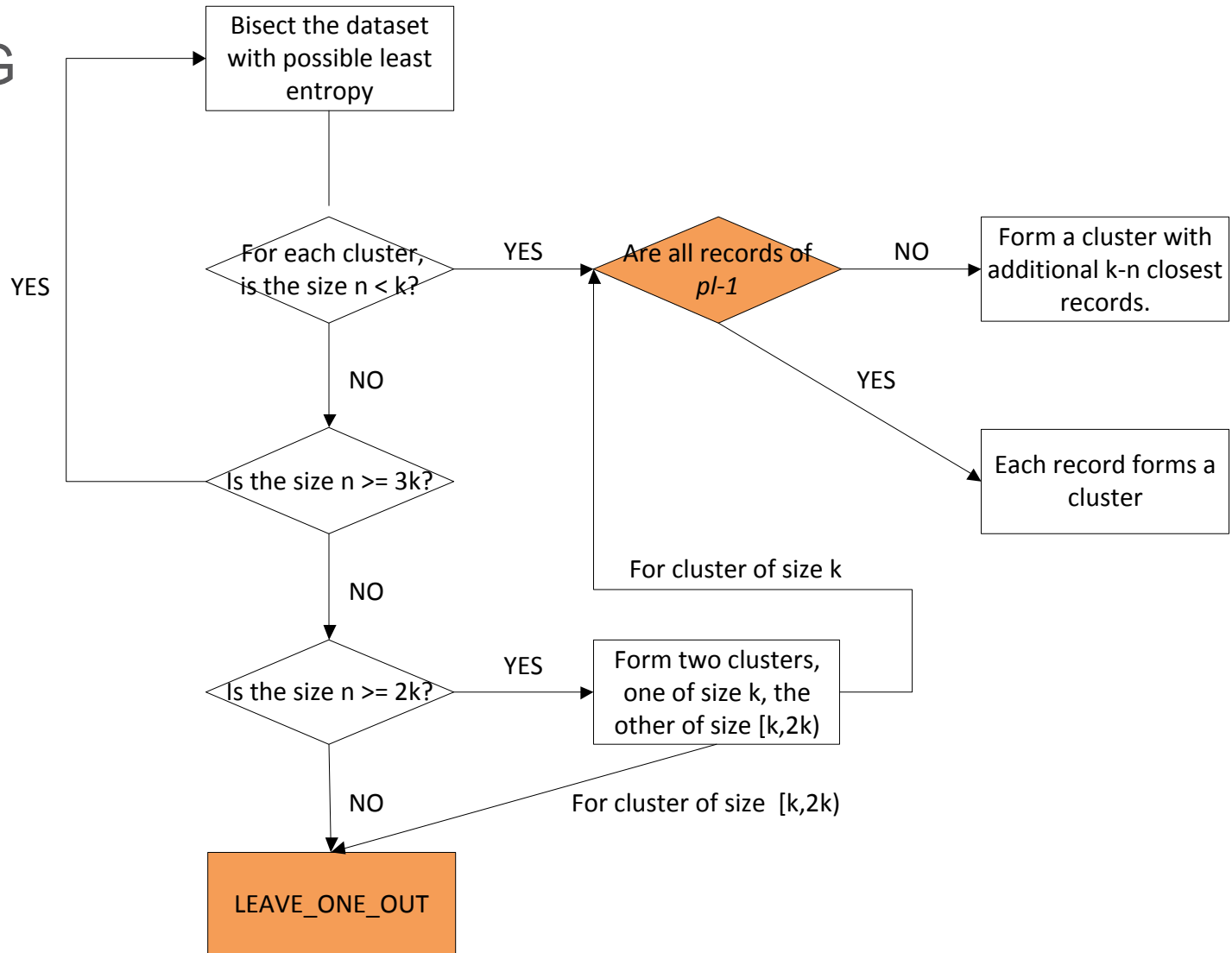
CUSTOMIZED K-ANONYMITY

› User policy

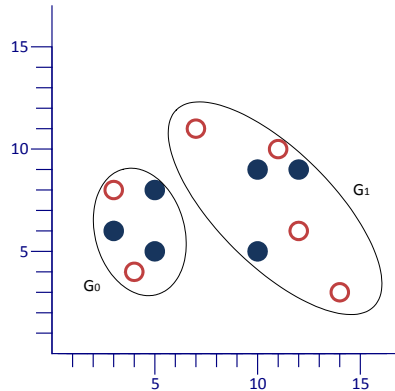


CUSTOMIZED K-ANONYMITY

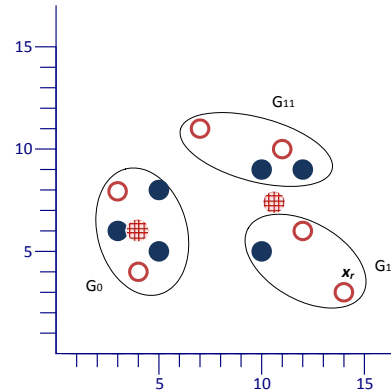
> BOKG



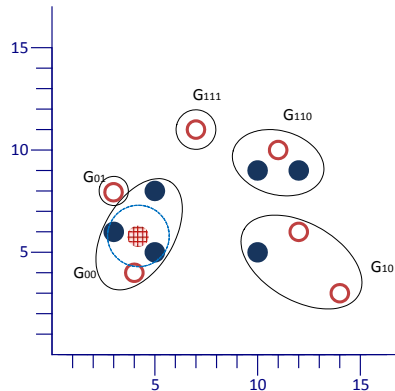
CUSTOMIZED K-ANONYMITY



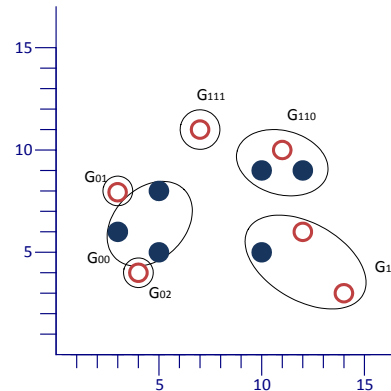
(c). Two clusters G_0 and G_1 generated after first bisection



(d). G_0 is of $[k, 2k]$, compute the centroid (in grid) and standard deviation s (dashed circle); G_1 is of $[2k, 3k]$, further divide G_1 to two clusters, x_r is the most distant point to centroid of G_1 (in grid)



(e). Form a separate cluster of point (3,8) of $p-1$ which is most distant from centroid and out of the s circle, recompute centroid and s ; same as cluster of point (7,11)

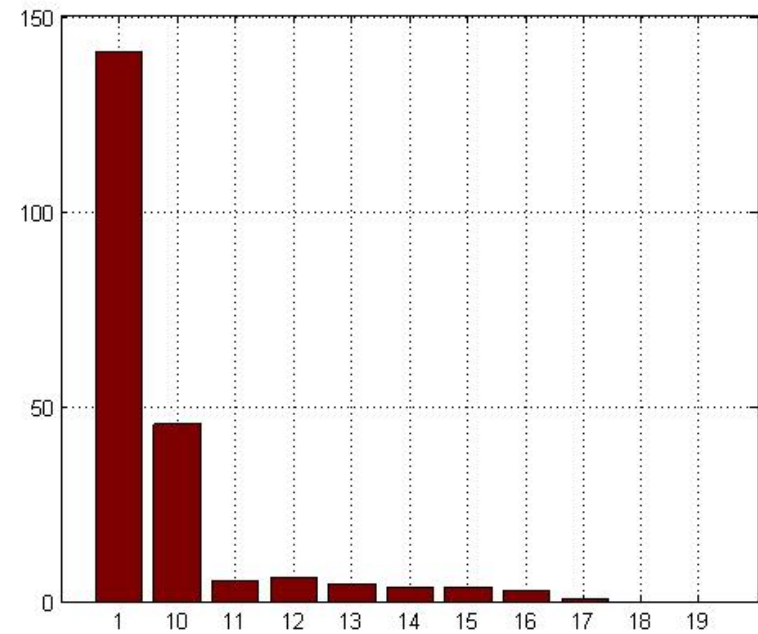
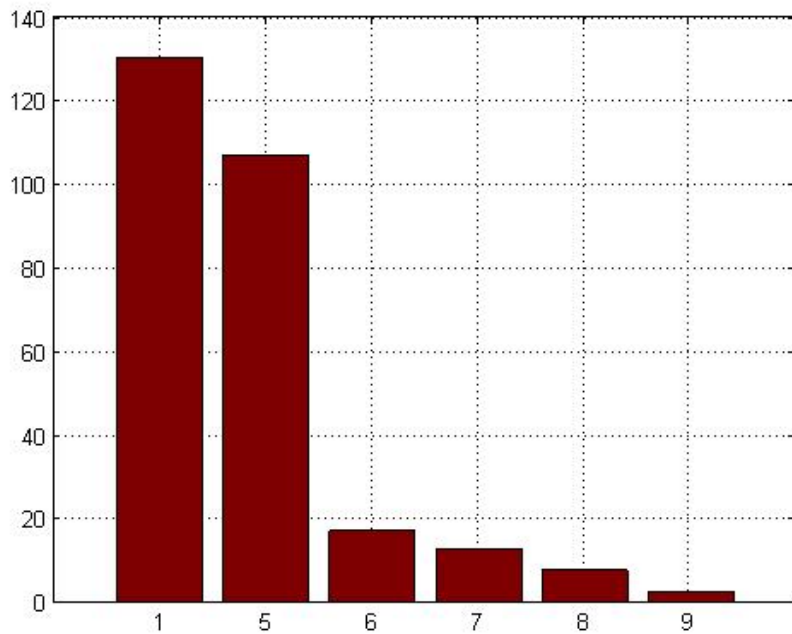


(f). Point (4,4) stands alone, eventually, we have six clusters, three of which are one-record clusters

EXPERIMENTAL RESULTS

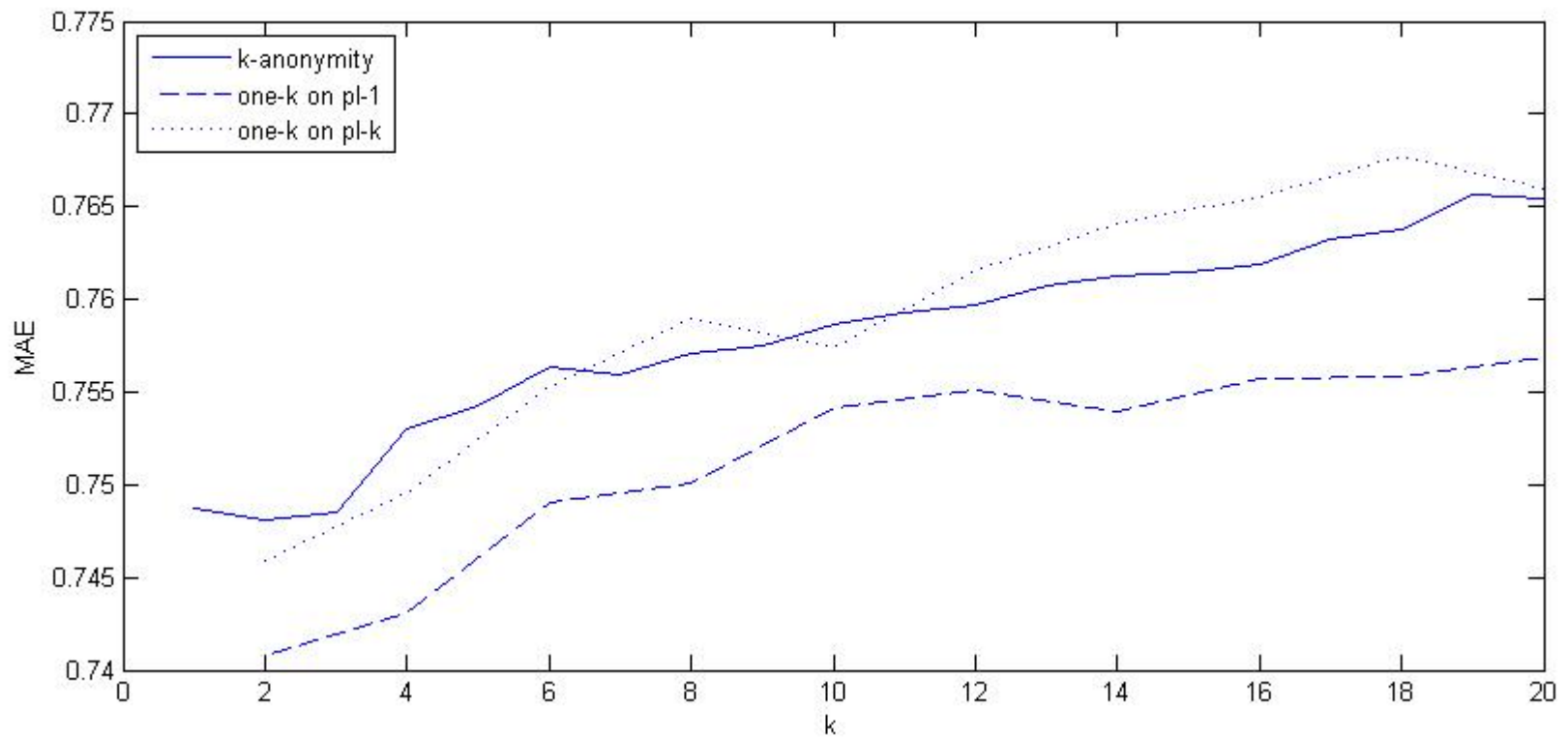
› Distributions

- 471 pl-1 users
- 472 pl-k users



EXPERIMENTAL RESULTS

› Results



CONCLUSIONS

- › SVD solves high dimensionality and sparsity
- › BKG is an efficient anonymization algorithm and preserves data utility
- › BOKG supports customized privacy policies
- › Better performance with less privacy requirements in mixed situations





ERICSSON