

## Reminder: Eigenvalues and eigenvectors

- Suppose  $\mathbb{F} = \mathbb{R}$  or  $\mathbb{F} = \mathbb{C}$  and  $A \in \mathbb{F}^{n \times n}$  is a matrix.
- $\lambda \in \mathbb{F}$  is called an *eigenvalue* of  $A$  if there exists an *eigenvector*  $v \in \mathbb{F}^n, v \neq 0$  such that  $Av = \lambda v$ .
- *Characteristic polynomial*

$$\chi_A(\lambda) = \det(A - \lambda I) = \begin{vmatrix} a_{11} - \lambda & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} - \lambda & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} - \lambda \end{vmatrix}$$

$\rightsquigarrow$  polynomial of degree  $n$

- **Lemma.**  $\lambda$  is an eigenvalue of  $A$  if and only if  $\chi_A(\lambda) = 0$ .

## Stability analysis of two-dimensional linear systems

- $\dot{y} = Ay$  with  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  non-singular

- Characteristic equation:

$$\det(A - \lambda I) = \lambda^2 - \underbrace{(a+d)}_S \lambda + \underbrace{(ad-bc)}_P = 0$$

- Eigenvalues

$$\lambda_{1,2} = \frac{1}{2}(S \pm \sqrt{S^2 - 4P})$$

- Different cases depending on whether or not

- $\lambda_1, \lambda_2$  are real or complex,
- $\lambda_1, \lambda_2$  (resp. their real part) are positive or negative.

## Possible cases

- $S^2 - 4P \geq 0$ : Real roots  $\lambda_1, \lambda_2$ 
  - $\lambda_1 \cdot \lambda_2 > 0$ : Node
  - $\lambda_1 \cdot \lambda_2 < 0$ : Saddle point
- $S^2 - 4P < 0$ : Complex conjugate roots  $\lambda_{1,2} = \alpha \pm i\beta, \beta \neq 0$ 
  - $\alpha \neq 0$ : Focus
  - $\alpha = 0$ : Center

## Real eigenvalues $\lambda_1 \neq \lambda_2$

- Diagonalization  $\dot{z} = Dz$ , with  $D = T^{-1}AT = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$
- Solutions:  $z(t) = \begin{pmatrix} z_1(t) \\ z_2(t) \end{pmatrix} = \begin{pmatrix} c_1 e^{\lambda_1 t} \\ c_2 e^{\lambda_2 t} \end{pmatrix}$
- In phase plane:  $|z_2| = c|z_1|^{\lambda_2/\lambda_1}$

- Case  $\lambda_2/\lambda_1 > 0$ : parabolic orbits *Node*
  - $\lambda_1, \lambda_2 < 0$ : *stable*
  - $\lambda_1, \lambda_2 > 0$ : *unstable*
- Case  $\lambda_2/\lambda_1 < 0$ : hyperbolic orbits *Saddle point*

### Real eigenvalues $\lambda_1 = \lambda_2$

- $\lambda_1 = \lambda_2 < 0$ :
  - Two linearly independent eigenvectors  $v^1, v^2$ : the orbits are half-lines towards the origin *star node*
  - Only one eigenvector  $v$ : the orbits become parallel to the half-line defined by  $v$  *degenerate node*
- $\lambda_1 = \lambda_2 > 0$ : Analogous, but orbits running in the opposite direction.

### Complex eigenvalues

- $\lambda_{1,2}$  complex conjugate:  $\lambda_{1,2} = \alpha \pm i\beta, \beta \neq 0$
- Complex solutions:  $e^{(\alpha \pm i\beta)t}$
- Real solutions: Linear combinations of  $e^{\alpha t} \cos \beta t$  and  $e^{\alpha t} \sin \beta t$
- Three cases:
  - $\alpha = 0$ : Circle *Center*
  - $\alpha < 0$ : Inward spiral *Stable focus*
  - $\alpha > 0$ : Outward spiral *Unstable focus*