## Petri nets

- proposed by Carl Adam Petri in the 60s
- simple graphical and mathematical formalism for modeling and analyzing distributed systems
- originally for qualitative models, but many extensions exist
- variety of applications, in particular molecular networks

**Definition** A Petri Net is a quadruple  $\mathcal{N} = (P, T, g, m_0)$ , where *P* and *T* are finite, non-empty, disjoint sets, and  $g : (P \times T) \cup (T \times P) \rightarrow \mathbb{N}_0$  and  $m_0 : P \rightarrow \mathbb{N}_0$  are functions.

### Structure and state space

#### Structure

- N can be visualized as a bipartite graph, with vertex set P ∪ T and weighted directed arcs derived from g (network structure)
- vertices in P are called places, vertices in T transitions

#### State space

- places are marked with *tokens*, number of tokens in a place constitutes its component value
- a marking m : P → N₀ assigns each place a token count (states), can be written as vector of length |P|
- $m_0$  gives an initial marking (initial state)
- ► a priori: state space N<sub>0</sub><sup>|P|</sup>, but initial marking generally restricts the state space (e.g. boundedness)

Informally, places represent resources of the system, while transitions correspond to events influencing the resources

# **Dynamics**

Firing given a marking  $m \in \mathbb{N}_0^{|P|}$ 

- a transition *t* is *enabled* if  $m(p) \ge g((p, t))$  for all places *p* with  $g((p, t)) \ne 0$  (input places of *t*)
- enabled transitions may *fire* resulting in a new marking obtained by consuming tokens from input places and producing tokens according to arc weights in places *p* with g((t, p)) ≠ 0 (output places of t)

### Algebraic description

- arc weights expressed in *pre- and postcondition matrix*:  $Pre, Post \in \mathbb{N}_{0}^{|P| \times |T|}$ , where  $Pre_{pt} := g((p, t))$  and  $Post_{pt} := g((t, p))$  for all  $p \in P, t \in T$
- ► *incidence matrix C* := *Post* − *Pre* describes token balance of firings
- ► state equation  $m' = m + C\sigma$ , where entries of  $\sigma \in \mathbb{N}_0^{|T|}$  represent number of transition occurrences:

m' represents the marking resulting from firing a single transition t once, if  $\sigma$  is the t-th unit vector

Remark: in general  $\sigma$  represents multiple transition firings, solvability of the state equation is limited (non-negativity of markings, non-determinism) and yields no information on sequence of events

# Marking graph

Given a marking  $m \in \mathbb{N}_0^{|P|}$ 

- any enabled transition *t* may fire: state transition from *m* to  $m' := m + C\sigma$  with  $\sigma$  the *t*-th unit vector
- firing is non-deterministic
- marking graph  $\mathcal{R}(m_0)$  of  $\mathcal{N}$ : vertices are markings *m* such that there exists a sequence of state transitions leading from initial marking  $m_0$  to *m*, edges represent state transitions (state transition graph)

### Properties

▶ Boundedness: number of tokens in each place is bounded (regardless of initial marking), 𝒩 is k-bounded if no marking in 𝔅(m₀) has more than k tokens in a place,

boundedness results in finite marking graphs

- ► Reachability: marking m is reachable from m<sub>0</sub> if there is a path from m<sub>0</sub> to m in R(m<sub>0</sub>) (that is if m belongs to the vertex set of R(m<sub>0</sub>))
- Liveness: every transition is in some state of the marking graph enabled
  Remark: analysis using temporal logic and model checking techniques

## Invariants

### P-invariants

- solutions  $x \in \mathbb{N}_0^{|P|}$  of  $C^T x = 0$
- support of x: non-zero components of x
- satisfy m<sup>T</sup>x = m<sub>0</sub><sup>T</sup>x for all markings m in 𝔅(m<sub>0</sub>), i.e., represent sets of places (support of x) with constant weighted sum for all markings in 𝔅(m<sub>0</sub>) (conservation relations)

#### **T-invariants**

- ► solutions  $y \in \mathbb{N}_0^{|T|}$  of Cy = 0, i.e., firing sequences that reproduce a marking *m*
- correspondence to elementary modes in metabolic networks

### **Biological modeling**

- models of metabolic, regulatory and signal transduction networks
- very different interpretation of places, transitions, tokens ...

# Metabolic networks

### Modeling

- places represent reactants, products, enzymes
- transitions represent biochemical reactions
- arc weights correspond to stoichiometric coefficients

 $\rightarrow$  topology of metabolic network and petri net model match

markings represent distribution of species molecules in the network

#### Analysis

- dynamic model (other than flux cone analysis)
  - simulation
  - reachability, liveness etc. (model checking techniques)
- stoichiometric matrix of the metabolic network corresponds to incidence matrix of the petri net, T-invariants correspond to elementary modes

# **Regulatory networks**

Modeling Given a Boolean network  $f : \{0,1\}^n \rightarrow \{0,1\}^n$ 

- places represent components
- transitions represent interactions
- tokens represent activity levels (on/off), markings represent states
  but translation is not straight forward
  - for each component α<sub>i</sub> introduce complementary places α<sub>i</sub> (component active) and α<sub>i</sub> (component inactive), state in {0,1}<sup>n</sup> corresponds to marking restricted to places α<sub>i</sub>

 $\rightarrow$  guarantee sum of tokens in  $\alpha_i$  and  $\overline{\alpha_i}$  is 1

- ► for each  $\alpha_i$  let  $Pred(\alpha_i)$  denote the predecessors of  $\alpha_i$  in G(f), i.e.  $f_i$  only depends on components in  $Pred(\alpha_i)$ , represent all states defining  $f_i$  by the states  $x^R$ , where  $R \subseteq Pred(\alpha_i)$  and  $x_j^R = 1$  for all  $j \in R$ ,  $x_j^R = 0$  for all  $j \in \{1, ..., n\} \setminus R$
- For each *i* ∈ {1,...,*n*} introduce transitions *t<sub>i,x<sup>R</sup></sub>* = *t<sub>i,R</sub>* representing update of α<sub>i</sub> to *f<sub>i</sub>(x)* in a state *x* coinciding with *x<sup>R</sup>* in components of *Pred*(α<sub>i</sub>)

## Mathematical description

Petri net model Given a Boolean network  $f : \{0,1\}^n \rightarrow \{0,1\}^n$ 

- set of places  $P := \{\alpha_1, \overline{\alpha_1}, \dots, \alpha_n, \overline{\alpha_n}\}$
- ► set of transitions  $T := \{t_{i,R} \mid i \in \{1,...,n\}, R \subseteq Pred(\alpha_i)\}$
- define  $g: (P \times T) \cup (T \times P) \rightarrow \{0,1\}$  as follows

In case  $\alpha_i \notin Pred(\alpha_i)$ , with  $x^R \in \{0,1\}^n$ ,  $x_j^R = 1$  for  $j \in R$ ,  $x_j^R = 0$  for  $j \in \{1, \dots, n\} \setminus R$ 

g(α<sub>i</sub>, t<sub>i,R</sub>) = g(t<sub>i,R</sub>, α<sub>i</sub>) = 1 − f<sub>i</sub>(x<sup>R</sup>) and g(α<sub>i</sub>, t<sub>i,R</sub>) = g(t<sub>i,R</sub>, α<sub>i</sub>) = f<sub>i</sub>(x<sup>R</sup>)
 → responsible for activity level change of component α<sub>i</sub>, ensures token sum of α<sub>i</sub> and α<sub>i</sub> remains 1

 g(α<sub>j</sub>, t<sub>i,R</sub>) = g(t<sub>i,R</sub>, α<sub>j</sub>) = 1 for all α<sub>j</sub> ∈ R g(α<sub>j</sub>, t<sub>i,R</sub>) = g(t<sub>i,R</sub>, α<sub>j</sub>) = 1 for all α<sub>j</sub> ∈ Pred(α<sub>i</sub>) \ R → enabling of t<sub>i,R</sub>, if current marking corresponds to x<sup>R</sup>, conservation of component markings

in all other cases g is set to zero

# Mathematical description

In case  $\alpha_i \in Pred(\alpha_i)$ , with  $x^R \in \{0,1\}^n$ ,  $x_j^R = 1$  for  $j \in R$ ,  $x_j^R = 0$  for  $j \in \{1, \dots, n\} \setminus R$ 

If  $\alpha_i \in R$ 

• 
$$g(\alpha_i, t_{i,R}) = g(t_{i,R}, \overline{\alpha_i}) = 1 - f_i(x^R),$$
  
 $\alpha_i \in R$  implies  $\alpha_i$  carries a token, moving it to  $\overline{\alpha_i}$  is only necessary if  $f_i(x^R) = 0$ 

► 
$$g(\alpha_j, t_{i,R}) = g(t_{i,R}, \alpha_j) = 1$$
 for all  $\alpha_j \in R \setminus \{\alpha_i\}$   
 $g(\overline{\alpha_j}, t_{i,R}) = g(t_{i,R}, \overline{\alpha_j}) = 1$  for all  $\alpha_j \in Pred(\alpha_i) \setminus R$   
 $\rightarrow$  corresponds to case  $\alpha_i \notin R$ 

If  $\alpha_i \notin R$ 

► 
$$g(\overline{\alpha_i}, t_{i,R}) = g(t_{i,R}, \alpha_i) = f_i(x^R),$$
  
 $\alpha_i \notin R$  implies  $\overline{\alpha_i}$  carries a token, moving it to  $\alpha_i$  is only necessary if  $f_i(x^R) = 1$ 

► 
$$g(\alpha_j, t_{i,R}) = g(t_{i,R}, \alpha_j) = 1$$
 for all  $\alpha_j \in R$   
 $g(\overline{\alpha_j}, t_{i,R}) = g(t_{i,R}, \overline{\alpha_j}) = 1$  for all  $\alpha_j \in Pred(\alpha_i) \setminus (R \cup \{\alpha_i\})$   
 $\rightarrow$  corresponds to case  $\alpha_i \notin R$ 

in all other cases g is set to zero

# Remarks

- mathematical description yields automated procedure for translating network description by Boolean function into petri nets
- similar translation for multi-valued models possible
- petri net topology carries information on structure and dynamics
- counting transitions, petri net model is exponential in size (simplifications possible)
- non-determinism of petri net dynamics results in asynchronous update for the regulatory network, it is possible to construct petri net models yielding synchronous dynamics
- simulation, algebraic methods and model checking techniques can be used for analysis
- treatment of signalling networks similar