

Segment Match Refinement

The function $\text{refine}(\mathcal{M})$ will make a k -partite graph with node sets $V^0 \dots V^{k-1}$ and edges E , which defines boundaries of the minimal resolved refinement of \mathcal{M} .

```
def cut( $a$ ):  
     $\mathcal{L} = \{M^k = (S_{u,v}^i, S_{x,y}^j) \mid u < a < v \vee x < a < y\}$   
    for  $M^k \in \mathcal{L}$ :  
         $b =$  match position of  $a$  in sequence  $l$  given by  $M^k$   
        if  $b \notin V^l$ :  
            insert  $b$  into  $V^l$   
            insert edge  $(k, a, b)$  into  $E$   
            cut( $b$ )  
  
def refine( $\mathcal{M}$ ):  
     $V^i =$  boundary positions of segments in sequence  $i$   
    for  $M^k = (S_{u,v}^i, S_{x,y}^j) \in \mathcal{M}$ :  
        insert edge  $(k, u, x)$  and  $(k, v, y)$  into  $E$   
        for boundary position  $w$  of  $M^k$ :  
            cut( $w$ )  
    lexicographically order  $E$ 
```

A pair of consecutive edges (k, u, v) and (l, x, y) in E , with $k = l$ defines a new segment match $M = (S_{u,x}^i, S_{v,y}^j)$ between sequences i and j . If you did not note the sequences the positions are from, you just have to look between which sequences the segment match i was defined.