# On the Stability of the Index of Unbounded Nonlocal Operators in Sobolev Spaces 

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#### Abstract

Unbounded operators corresponding to nonlocal elliptic problems on a bounded region $G \subset \mathbb{R}^{2}$ are considered. The domain of these operators consists of functions in the Sobolev space $W_{2}^{m}(G)$ that are generalized solutions of the corresponding elliptic equation of order $2 m$ with the right-hand side in $L_{2}(G)$ and satisfy homogeneous nonlocal boundary conditions. It is known that such unbounded operators have the Fredholm property. It is proved that lower order terms in the differential equation do not affect the index of the operator. Conditions under which nonlocal perturbations on the boundary do not change the index are also formulated.


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## INTRODUCTION

In the one-dimensional case, nonlocal problems were studied by A. Sommerfeld [20], Ya.D. Tamarkin [13], and M. Picone [17]. T. Carleman [14] considered the problem of finding a function harmonic on a two-dimensional bounded domain and subject to a nonlocal condition connecting the values of this function at different points of the boundary. A.V. Bitsadze and A.A. Samarskii [1] suggested another nonlocal problem arising in plasma theory: find a function harmonic on a bounded domain and satisfying nonlocal conditions on shifts of the boundary that can take points of the boundary inside the domain. Different generalizations of the above nonlocal problems were investigated by many authors (see [19] and references therein).

It turns out that the most difficult situation occurs if the support of nonlocal terms intersects the boundary. In this case, solutions of nonlocal problems may have power-law singularities near some points even if the boundary and the right-hand sides are infinitely smooth [10]. For this reason, such problems are naturally studied in weighted spaces (introduced by V.A. Kondrat'ev for boundary-value problems in nonsmooth domains [7]). The most complete theory of nonlocal problems in weighted spaces is developed by A.L. Skubachevskii $[10-12,18,19]$ and his students.

Note that the study of nonlocal problems is motivated both by significant theoretical progress in this field and important applications arising in biophysics, theory of diffusion processes, plasma theory, and so on.

In this paper, we investigate the influence of lower order terms in an elliptic equation and the influence of nonlocal perturbations in boundary conditions upon the index of the unbounded nonlocal operator in $L_{2}(G)$. This issue was earlier studied by A.L. Skubachevskii [18] for bounded operators in weighted spaces. It is proved in [18] that nonlocal perturbations supported outside the points of conjugation of the boundary conditions do not change the index of the corresponding bounded operator. A similar assertion was later established in Sobolev spaces in the two-dimensional case [16]. In both cases, one can either use the method of continuation with respect to a parameter or reduce the original problem to that where nonlocal perturbations have compact square. As for lower order terms in the elliptic equation, they are simply compact perturbations.

[^0]The situation is quite different in the case of unbounded operators. The difficulty is that the lower order terms in elliptic equations are not compact or relatively compact (see Definition A. 2 in the Appendix); moreover, if the order of the elliptic equation is greater than two, they are not even relatively bounded, and therefore, they may change the domain of definition of the operator. As for nonlocal perturbations in the boundary conditions, they explicitly change the domain of definition, and therefore, they cannot be regarded as compact perturbations (in any sense).

To overcome the above difficulties, we consider an auxiliary operator (whose index equals the index of the original operator) acting on weighted spaces. In Section 2, we prove that lower order terms in elliptic equations are relatively compact perturbations of the auxiliary operator and, therefore, do not affect the index. In Section 3, we consider nonlocal perturbations in boundary conditions, which explicitly change the domain of definition. We make use of the notion of a gap between unbounded operators (see Definition A.3). We show that if the nonlocal perturbations in boundary conditions satisfy some regularity conditions at the conjugation points, then multiplying the perturbations by a small parameter leads to a small gap between the corresponding operators. Combining this fact with the method of continuation with respect to a parameter, we prove the index stability theorem.

Finally, we note that the Fredholm property of unbounded nonlocal operators on $L_{2}(G)$ was earlier studied either in the case when nonlocal conditions were set on shifts of the boundary [19] or in the case of a nonlocal perturbation of the Dirichlet problem for a second-order elliptic equation [5, 4]. For elliptic equations of order $2 m$ with general nonlocal conditions, this question is being investigated for the first time.

## 1. SETTING OF NONLOCAL PROBLEMS IN BOUNDED DOMAINS

1.1. Setting of nonlocal problems. Let $G \subset \mathbb{R}^{2}$ be a bounded domain with boundary $\partial G$. We introduce a set $\mathcal{K} \subset \partial G$ consisting of finitely many points and assume that $\partial G \backslash \mathcal{K}=\bigcup_{i=1}^{N} \Gamma_{i}$, where $\Gamma_{i}$ are open (in the topology of $\partial G$ ) $C^{\infty}$ curves. In a neighborhood of each point $g \in \mathcal{K}$, the domain $G$ is supposed to coincide with some plane angle.

For any domain $Q$ and for integer $k \geq 0$, we denote by $W^{k}(Q)=W_{2}^{k}(Q)$ the Sobolev space with the norm

$$
\|u\|_{W^{k}(Q)}=\left(\sum_{|\alpha| \leq k} \int_{Q}\left|D^{\alpha} u\right|^{2} d y\right)^{1 / 2}
$$

(we set $W^{0}(Q)=L_{2}(Q)$ for $k=0$ ). For an integer $k \geq 1$, we introduce the space $W^{k-1 / 2}(\Gamma)$ of traces on a smooth curve $\Gamma \subset \bar{Q}$, with the norm

$$
\begin{equation*}
\|\psi\|_{W^{k-1 / 2}(\Gamma)}=\inf \|u\|_{W^{k}(Q)}, \quad u \in W^{k}(Q):\left.u\right|_{\Gamma}=\psi . \tag{1.1}
\end{equation*}
$$

For any set $X \subset \mathbb{R}^{2}$ with nonempty interior, we denote by $C_{0}^{\infty}(X)$ the set of functions that are infinitely differentiable on $\mathbb{R}^{2}$ and compactly supported on $X$.

Now we introduce different weighted spaces for different domains $Q$. Consider the following cases:
(1) $Q=G$; denote $\mathcal{M}=\mathcal{K}$;
(2) $Q$ is a plane angle, $Q=\left\{y \in \mathbb{R}^{2}:|\omega|<\omega_{0}\right\}$, where $0<\omega_{0}<\pi$; denote $\mathcal{M}=\{0\}$;
(3) $Q=\left\{y \in \mathbb{R}^{2}:|\omega|<\omega_{0}, 0<r<\varepsilon\right\}$ for some $\varepsilon>0$; denote $\mathcal{M}=\{0\}$;
here $(\omega, r)$ are polar coordinates of the point $y$.

Introduce the weighted Kondrat'ev space $H_{a}^{k}(Q)=H_{a}^{k}(Q, \mathcal{M})$ as the completion of the set $C_{0}^{\infty}(\bar{Q} \backslash \mathcal{M})$ with respect to the norm

$$
\|u\|_{H_{a}^{k}(Q)}=\left(\sum_{|\alpha| \leq k} \int_{Q} \rho^{2(a+|\alpha|-k)}\left|D^{\alpha} u\right|^{2} d x\right)^{1 / 2}
$$

where $k \geq 0, a \in \mathbb{R}$, and $\rho(y)=\operatorname{dist}(y, \mathcal{M})$; clearly, $\rho(y)=r$ in cases (2) and (3).
Denote by $H_{a}^{k-1 / 2}(\Gamma)(k \geq 1$ is an integer $)$ the space of traces on a smooth curve $\Gamma \subset \bar{Q}$, with the norm

$$
\|\psi\|_{H_{a}^{k-1 / 2}(\Gamma)}=\inf \|v\|_{H_{a}^{k}(Q)}, \quad v \in H_{a}^{k}(Q):\left.v\right|_{\Gamma}=\psi
$$

We denote by $\mathbf{A}\left(y, D_{y}\right)$ and $B_{i \mu s}\left(y, D_{y}\right)$ linear differential operators of orders $2 m$ and $m_{i \mu}$ (with $\left.m_{i \mu} \leq m-1\right)$, respectively, with complex-valued $C^{\infty}$ coefficients ( $i=1, \ldots, N ; \mu=1, \ldots, m$; $\left.s=0, \ldots, S_{i}\right)$. Set $\mathbf{B}_{i \mu}^{0} u=\left.B_{i \mu 0}\left(y, D_{y}\right) u\right|_{\Gamma_{i}}$.

Condition 1.1 (see, e.g., [9]). The operator $\mathbf{A}\left(y, D_{y}\right)$ is properly elliptic for all $y \in \bar{G}$, and the system of operators $\left\{\mathbf{B}_{i \mu}^{0}\right\}_{\mu=1}^{m}$ covers $\mathbf{A}\left(y, D_{y}\right)$ for all $i=1, \ldots, N$ and $y \in \bar{\Gamma}_{i}$.

The operators $\mathbf{A}\left(y, D_{y}\right)$ and $\mathbf{B}_{i \mu}^{0}$ will correspond to a "local" boundary-value problem.
Now we define operators corresponding to nonlocal conditions near the set $\mathcal{K}$. For $\varepsilon>0$ and any closed set $\mathcal{N}$, denote by $\mathcal{O}_{\varepsilon}(\mathcal{N})=\left\{y \in \mathbb{R}^{2}: \operatorname{dist}(y, \mathcal{N})<\varepsilon\right\}$ its $\varepsilon$-neighborhood.

Let $\Omega_{i s}\left(i=1, \ldots, N ; s=1, \ldots, S_{i}\right)$ be $C^{\infty}$ diffeomorphisms taking some neighborhood $\mathcal{O}_{i}$ of the curve $\overline{\Gamma_{i} \cap \mathcal{O}_{\varepsilon}(\mathcal{K})}$ to the set $\Omega_{i s}\left(\mathcal{O}_{i}\right)$ in such a way that $\Omega_{i s}\left(\Gamma_{i} \cap \mathcal{O}_{\varepsilon}(\mathcal{K})\right) \subset G$ and $\Omega_{i s}(g) \in \mathcal{K}$ for $g \in \bar{\Gamma}_{i} \cap \mathcal{K}$. Thus, under the transformations $\Omega_{i s}$, the curves $\Gamma_{i} \cap \mathcal{O}_{\varepsilon}(\mathcal{K})$ are mapped strictly inside the domain $G$, whereas the set of end points $\bar{\Gamma}_{i} \cap \mathcal{K}$ is mapped to itself.

Let us specify the structure of the transformations $\Omega_{i s}$ near the set $\mathcal{K}$. Denote by the symbol $\Omega_{i s}^{+1}$ the transformation $\Omega_{i s}: \mathcal{O}_{i} \rightarrow \Omega_{i s}\left(\mathcal{O}_{i}\right)$ and by $\Omega_{i s}^{-1}$ the inverse transformation. The set of all points $\Omega_{i_{q} s_{q}}^{ \pm 1}\left(\ldots \Omega_{i_{1} s_{1}}^{ \pm 1}(g)\right) \in \mathcal{K}\left(1 \leq s_{j} \leq S_{i_{j}}, j=1, \ldots, q\right)$, i.e., the set of all points that can be obtained by consecutively applying the transformations $\Omega_{i_{j} s_{j}}^{+1}$ or $\Omega_{i_{j} s_{j}}^{-1}$ (taking the points of $\mathcal{K}$ to $\mathcal{K}$ ) to the point $g \in \mathcal{K}$, is called the orbit of the point $g$ and is denoted by $\operatorname{Orb}(g)$.

Clearly, for any $g, g^{\prime} \in \mathcal{K}$, either $\operatorname{Orb}(g)=\operatorname{Orb}\left(g^{\prime}\right)$ or $\operatorname{Orb}(g) \cap \operatorname{Orb}\left(g^{\prime}\right)=\varnothing$. In what follows, we assume that the set $\mathcal{K}$ consists of one orbit and the number of points in the orbit is equal to the number $N$ of the curves $\Gamma_{i}$. Denote the points of the set (orbit) $\mathcal{K}$ by $g_{j}, j=1, \ldots, N$.

Take a small number $\varepsilon>0$ such that there exist neighborhoods $\mathcal{O}_{\varepsilon_{1}}\left(g_{j}\right)$ of the points $g_{j} \in \mathcal{K}$ satisfying the following conditions:
(1) $\mathcal{O}_{\varepsilon_{1}}\left(g_{j}\right) \supset \mathcal{O}_{\varepsilon}\left(g_{j}\right)$;
(2) the boundary $\partial G$ coincides with some plane angle in the neighborhood $\mathcal{O}_{\varepsilon_{1}}\left(g_{j}\right)$;
(3) $\overline{\mathcal{O}_{\varepsilon_{1}}\left(g_{j}\right)} \cap \overline{\mathcal{O}_{\varepsilon_{1}}\left(g_{k}\right)}=\varnothing$ for any $g_{j}, g_{k} \in \mathcal{K}, j \neq k$;
(4) if $g_{j} \in \bar{\Gamma}_{i}$ and $\Omega_{i s}\left(g_{j}\right)=g_{k}$, then $\mathcal{O}_{\varepsilon}\left(g_{j}\right) \subset \mathcal{O}_{i}$ and $\Omega_{i s}\left(\mathcal{O}_{\varepsilon}\left(g_{j}\right)\right) \subset \mathcal{O}_{\varepsilon_{1}}\left(g_{k}\right)$.

For each point $g_{j} \in \bar{\Gamma}_{i} \cap \mathcal{K}$, we fix a transformation $Y_{j}: y \mapsto y^{\prime}\left(g_{j}\right)$ that is the composition of the shift by the vector $-\overrightarrow{O g_{j}}$ and the rotation through some angle so that

$$
\begin{gathered}
Y_{j}\left(\mathcal{O}_{\varepsilon_{1}}\left(g_{j}\right)\right)=\mathcal{O}_{\varepsilon_{1}}(0), \quad Y_{j}\left(G \cap \mathcal{O}_{\varepsilon_{1}}\left(g_{j}\right)\right)=K_{j} \cap \mathcal{O}_{\varepsilon_{1}}(0), \\
Y_{j}\left(\Gamma_{i} \cap \mathcal{O}_{\varepsilon_{1}}\left(g_{j}\right)\right)=\gamma_{j \sigma} \cap \mathcal{O}_{\varepsilon_{1}}(0), \quad \sigma=1 \text { or } 2,
\end{gathered}
$$

where $K_{j}=\left\{y \in \mathbb{R}^{2}: r>0,|\omega|<\omega_{j}\right\}, \gamma_{j \sigma}=\left\{y \in \mathbb{R}^{2}: r>0, \omega=(-1)^{\sigma} \omega_{j}\right\},(\omega, r)$ are polar coordinates, and $0<\omega_{j}<\pi$.

Condition 1.2. Let $g_{j} \in \bar{\Gamma}_{i} \cap \mathcal{K}$ and $\Omega_{i s}\left(g_{j}\right)=g_{k} \in \mathcal{K}$. Then the transformation $Y_{k} \circ \Omega_{i s} \circ$ $Y_{j}^{-1}: \mathcal{O}_{\varepsilon}(0) \rightarrow \mathcal{O}_{\varepsilon_{1}}(0)$ is the composition of a rotation and a homothety.

Remark 1.1. Condition 1.2, being combined with the assumption $\Omega_{i s}\left(\Gamma_{i} \cap \mathcal{O}_{\varepsilon}(\mathcal{K})\right) \subset G$, means, in particular, that if $g \in \Omega_{i s}\left(\bar{\Gamma}_{i} \cap \mathcal{K}\right) \cap \bar{\Gamma}_{j} \cap \mathcal{K} \neq \varnothing$, then the curves $\Omega_{i s}\left(\bar{\Gamma}_{i}\right)$ and $\bar{\Gamma}_{j}$ are not tangent to each other at the point $g$.

Consider a number $\varepsilon_{0}, 0<\varepsilon_{0} \leq \varepsilon$, satisfying the following condition: if $g_{j} \in \bar{\Gamma}_{i}$ and $\Omega_{i s}\left(g_{j}\right)=g_{k}$, then $\mathcal{O}_{\varepsilon_{0}}\left(g_{k}\right) \subset \Omega_{i s}\left(\mathcal{O}_{\varepsilon}\left(g_{j}\right)\right)$. Introduce a function $\zeta \in C^{\infty}\left(\mathbb{R}^{2}\right)$ such that $\zeta(y)=1$ for $y \in \mathcal{O}_{\varepsilon_{0} / 2}(\mathcal{K})$ and $\operatorname{supp} \zeta \subset \mathcal{O}_{\varepsilon_{0}}(\mathcal{K})$.

Now we define nonlocal operators $\mathbf{B}_{i \mu}^{1}$ by the formula

$$
\mathbf{B}_{i \mu}^{1} u=\sum_{s=1}^{S_{i}}\left(B_{i \mu s}\left(y, D_{y}\right)(\zeta u)\right)\left(\Omega_{i s}(y)\right), \quad y \in \Gamma_{i} \cap \mathcal{O}_{\varepsilon}(\mathcal{K}), \quad \mathbf{B}_{i \mu}^{1} u=0, \quad y \in \Gamma_{i} \backslash \mathcal{O}_{\varepsilon}(\mathcal{K}),
$$

where $\left(B_{i \mu s}\left(y, D_{y}\right) u\right)\left(\Omega_{i s}(y)\right)=\left.B_{i \mu s}\left(x, D_{x}\right) u(x)\right|_{x=\Omega_{i s}(y)}$. Since $\mathbf{B}_{i \mu}^{1} u=0$ if $\operatorname{supp} u \subset \bar{G} \backslash \overline{\mathcal{O}_{\varepsilon_{0}}(\mathcal{K})}$, we say that the operators $\mathbf{B}_{i \mu}^{1}$ correspond to nonlocal terms supported near the set $\mathcal{K}$.

For any $\rho>0$, we denote $G_{\rho}=\{y \in G$ : $\operatorname{dist}(y, \partial G)>\rho\}$. Consider linear operators $\mathbf{B}_{i \mu}^{2}$ satisfying the following condition (cf. [10, 18, 15]).

Condition 1.3. There exist numbers $\varkappa_{1}>\varkappa_{2}>0$ and $\rho>0$ such that the following inequalities hold:

$$
\begin{align*}
& \left\|\mathbf{B}_{i \mu}^{2} u\right\|_{W^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)} \leq c_{1}\|u\|_{W^{2 m}\left(G \backslash \overline{\mathcal{O}_{1}(\mathcal{K})}\right)}  \tag{1.2}\\
& \left\|\mathbf{B}_{i \mu}^{2} u\right\|_{W^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i} \backslash \overline{\left.\mathcal{O}_{\varkappa_{2}}(\mathcal{K})\right)}\right.} \leq c_{2}\|u\|_{W^{2 m}\left(G_{\rho}\right)} \tag{1.3}
\end{align*}
$$

Remark 1.2. In (1.2), (1.3) and throughout the paper, we denote by $c, c_{1}, c_{2}, \ldots$ and $k_{1}, k_{2}, \ldots$ positive constants that do not depend on the functions involved in the corresponding inequality.

We assume that Conditions 1.1-1.3 hold throughout, including the formulation of lemmas.
It follows from (1.2) that $\mathbf{B}_{i \mu}^{2} u=0$ whenever $\operatorname{supp} u \subset \mathcal{O}_{\varkappa_{1}}(\mathcal{K})$. For this reason, we say that the operators $\mathbf{B}_{i \mu}^{2}$ correspond to nonlocal terms supported outside the set $\mathcal{K}$.

We study the following nonlocal elliptic problem:

$$
\begin{gather*}
\mathbf{A}\left(y, D_{y}\right) u=f(y), \quad y \in G,  \tag{1.4}\\
\mathbf{B}_{i \mu} u \equiv \mathbf{B}_{i \mu}^{0} u+\mathbf{B}_{i \mu}^{1} u+\mathbf{B}_{i \mu}^{2} u=0, \quad y \in \Gamma_{i}, \quad i=1, \ldots, N, \quad \mu=1, \ldots, m, \tag{1.5}
\end{gather*}
$$

where $f \in L_{2}(G)$. Introduce a space $W^{m}(G, \mathbf{B})$ consisting of functions $u \in W^{m}(G)$ that satisfy the homogeneous nonlocal conditions (1.5). Consider the unbounded operator $\mathbf{P}: \mathrm{D}(\mathbf{P}) \subset L_{2}(G) \rightarrow$ $L_{2}(G)$ given by

$$
\mathbf{P} u=\mathbf{A}\left(y, D_{y}\right) u, \quad u \in \mathrm{D}(\mathbf{P})=\left\{u \in W^{m}(G, \mathbf{B}): \mathbf{A}\left(y, D_{y}\right) u \in L_{2}(G)\right\} .
$$

Definition 1.1. A function $u$ is called a generalized solution of problem (1.4), (1.5) with righthand side $f \in L_{2}(G)$ if $u \in \mathrm{D}(\mathbf{P})$ and $\mathbf{P} u=f$.

An equivalent definition of a generalized solution can be given in terms of an integral identity [3].
Note that generalized solutions a priori belong to the space $W^{m}(G)$, whereas Condition 1.3 is formulated for functions that belong to the space $W^{2 m}$ outside the set $\mathcal{K}$. Such a formulation can be justified by the following result (see Lemma 2.1 in [3] and Lemma 5.1 in [16]).

Lemma 1.1. Let $u \in W^{m}(G)$ be a generalized solution of problem (1.4), (1.5) with right-hand side $f \in W^{k}(G)$. Then

$$
\|u\|_{W^{k+2 m}\left(G \backslash \overline{\mathcal{O}_{\delta}(\mathcal{K})}\right)} \leq c_{\delta}\left(\|f\|_{W^{k}\left(G \backslash \overline{\mathcal{O}_{\delta_{1}}(\mathcal{K})}\right)}+\|u\|_{L_{2}(G)}\right) \quad \forall \delta>0,
$$

where $\delta_{1}=\delta_{1}(\delta)>0$ and $c_{\delta}>0$ do not depend on $u$.
Theorem 1.1 (see Theorem 2.1 in [3]). Let Conditions 1.1-1.3 hold. Then the operator $\mathbf{P}$ has the Fredholm property. ${ }^{1}$

The aim of this paper is to investigate the influence of lower order terms in (1.4) and nonlocal operators $\mathbf{B}_{i \mu}^{1}$ and $\mathbf{B}_{i \mu}^{2}$ in (1.5) upon the index of the operator $\mathbf{P}$.
1.2. Nonlocal problems near the set $\mathcal{K}$. When studying problem (1.4), (1.5), one must pay particular attention to the behavior of solutions near the set $\mathcal{K}$ of conjugation points. Let us consider the corresponding model problems. Denote by $u_{j}(y)$ the function $u(y)$ for $y \in \mathcal{O}_{\varepsilon_{1}}\left(g_{j}\right)$. If $g_{j} \in \bar{\Gamma}_{i}, y \in \mathcal{O}_{\varepsilon}\left(g_{j}\right)$, and $\Omega_{i s}(y) \in \mathcal{O}_{\varepsilon_{1}}\left(g_{k}\right)$, then we denote the function $u\left(\Omega_{i s}(y)\right)$ by $u_{k}\left(\Omega_{i s}(y)\right)$. Using this notation, we rewrite the nonlocal problem (1.4), (1.5) in the $\varepsilon$-neighborhood of the set (orbit) $\mathcal{K}$ as follows:

$$
\begin{gathered}
\mathbf{A}\left(y, D_{y}\right) u_{j}=f(y), \quad y \in \mathcal{O}_{\varepsilon}\left(g_{j}\right) \cap G, \\
\left.B_{i \mu 0}\left(y, D_{y}\right) u_{j}(y)\right|_{\mathcal{O}_{\varepsilon}\left(g_{j}\right) \cap \Gamma_{i}}+\left.\sum_{s=1}^{S_{i}}\left(B_{i \mu s}\left(y, D_{y}\right)\left(\zeta u_{k}\right)\right)\left(\Omega_{i s}(y)\right)\right|_{\mathcal{O}_{\varepsilon}\left(g_{j}\right) \cap \Gamma_{i}}=f_{i \mu}(y), \quad y \in \mathcal{O}_{\varepsilon}\left(g_{j}\right) \cap \Gamma_{i}, \\
i \in\left\{1 \leq i \leq N: g_{j} \in \bar{\Gamma}_{i}\right\}, \quad j=1, \ldots, N, \quad \mu=1, \ldots, m,
\end{gathered}
$$

where $f_{i \mu}=-\mathbf{B}_{i \mu}^{2} u$.
Let $y \mapsto y^{\prime}\left(g_{j}\right)$ be the change of variables described in Subsection 1.1. Denote $K_{j}^{\varepsilon}=K_{j} \cap \mathcal{O}_{\varepsilon}(0)$ and $\gamma_{j \sigma}^{\varepsilon}=\gamma_{j \sigma} \cap \mathcal{O}_{\varepsilon}(0)$. Introduce the functions

$$
U_{j}\left(y^{\prime}\right)=u_{j}\left(y\left(y^{\prime}\right)\right), \quad f_{j}\left(y^{\prime}\right)=f\left(y\left(y^{\prime}\right)\right), \quad y^{\prime} \in K_{j}^{\varepsilon}
$$

and

$$
f_{j \sigma \mu}\left(y^{\prime}\right)=f_{i \mu}\left(y\left(y^{\prime}\right)\right), \quad y^{\prime} \in \gamma_{j \sigma}^{\varepsilon},
$$

where $\sigma=1(\sigma=2)$ if, under the transformation $y \mapsto y^{\prime}\left(g_{j}\right)$, the curve $\Gamma_{i}$ is mapped to the side $\gamma_{j 1}\left(\gamma_{j 2}\right)$ of the angle $K_{j}$. Denote $y^{\prime}$ by $y$ again. Then, by virtue of Condition 1.2, problem (1.4), (1.5) acquires the form

$$
\begin{align*}
\quad \mathbf{A}_{j}\left(y, D_{y}\right) U_{j}=f_{j}(y), \quad y \in K_{j}^{\varepsilon},  \tag{1.6}\\
\sum_{k, s}\left(B_{j \sigma \mu k s}\left(y, D_{y}\right) U_{k}\right)\left(\mathcal{G}_{j \sigma k s} y\right)=f_{j \sigma \mu}(y), \quad y \in \gamma_{j \sigma}^{\varepsilon} ; \tag{1.7}
\end{align*}
$$

here $j, k=1, \ldots, N ; \sigma=1,2 ; \mu=1, \ldots, m ; s=0, \ldots, S_{j \sigma k} ; \mathbf{A}_{j}\left(y, D_{y}\right)$ and $B_{j \sigma \mu k s}\left(y, D_{y}\right)$ are differential operators of orders $2 m$ and $m_{j \sigma \mu}\left(m_{j \sigma \mu} \leq m-1\right)$, respectively, with $C^{\infty}$ complex-valued coefficients; and $\mathcal{G}_{j \sigma k s}$ is the operator of rotation through an angle $\omega_{j \sigma k s}$ and the homothety with a coefficient $\chi_{j \sigma k s}\left(\chi_{j \sigma k s}>0\right)$. Moreover, $\left|(-1)^{\sigma} b_{j}+\omega_{j \sigma k s}\right|<b_{k}$ for $(k, s) \neq(j, 0)$ (cf. Remark 1.1), $\omega_{j \sigma j 0}=0$, and $\chi_{j \sigma j 0}=1$ (i.e., $\mathcal{G}_{j \sigma j 0} y \equiv y$ ).

Set $D_{\chi}=2 \max \left\{\chi_{j \sigma k s}\right\}$. The following lemma establishes the regularity property for the solutions of nonlocal problems near the set $\mathcal{K}$.

[^1]Lemma $1.2\left(\mathrm{see}^{2}\right.$ Lemma 2.3 in [3]). Let $\left(U_{1}, \ldots, U_{N}\right)$ be a solution of problem (1.6), (1.7) such that

$$
U_{j} \in W^{2 m}\left(K_{j}^{D_{\chi} \varepsilon} \cap\{|y|>\delta\}\right) \quad \forall \delta>0, \quad U_{j} \in H_{a-2 m}^{0}\left(K_{j}^{D_{\chi} \varepsilon}\right),
$$

where $a \in \mathbb{R}$. Suppose that $f_{j} \in H_{a}^{0}\left(K_{j}^{\varepsilon}\right)$ and $f_{j \sigma \mu} \in H_{a}^{2 m-m_{j \sigma \mu}-1 / 2}\left(\gamma_{j \sigma}^{\varepsilon}\right)$. Then

$$
\sum_{j}\left\|U_{j}\right\|_{H_{a}^{2 m}\left(K_{j}^{\left.\varepsilon / D_{\chi}^{3}\right)}\right.} \leq c \sum_{j}\left(\left\|f_{j}\right\|_{H_{a}^{0}\left(K_{j}^{\varepsilon}\right)}+\sum_{\sigma, \mu}\left\|f_{j \sigma \mu}\right\|_{H_{a}^{2 m-m_{j \sigma \mu}-1 / 2}\left(\gamma_{j \sigma}^{\varepsilon}\right)}+\left\|U_{j}\right\|_{H_{a-2 m}^{0}\left(K_{j}^{\varepsilon}\right)}\right) .
$$

We write the principal homogeneous parts of the operators $\mathbf{A}_{j}\left(0, D_{y}\right)$ and $B_{j \sigma \mu k s}\left(0, D_{y}\right)$ in the polar coordinates as $r^{-2 m} \widetilde{\mathcal{A}}_{j}\left(\omega, D_{\omega}, r D_{r}\right)$ and $r^{-m_{j \sigma \mu}} \widetilde{B}_{j \sigma \mu k s}\left(\omega, D_{\omega}, r D_{r}\right)$, respectively, and consider the analytic operator-valued function

$$
\begin{gathered}
\widetilde{\mathcal{L}}(\lambda): \prod_{j=1}^{N} W^{l+2 m}\left(-\omega_{j}, \omega_{j}\right) \rightarrow \prod_{j=1}^{N}\left(W^{l}\left(-\omega_{j}, \omega_{j}\right) \times \mathbb{C}^{2 m}\right), \\
\widetilde{\mathcal{L}}(\lambda) \varphi=\left\{\widetilde{\mathcal{A}}_{j}\left(\omega, D_{\omega}, \lambda\right) \varphi_{j},\left.\sum_{k, s}\left(\chi_{j \sigma k s}\right)^{i \lambda-m_{j \sigma \mu}} \widetilde{B}_{j \sigma \mu k s}\left(\omega, D_{\omega}, \lambda\right) \varphi_{k}\left(\omega+\omega_{j \sigma k s}\right)\right|_{\omega=(-1)^{\sigma} \omega_{j}}\right\} .
\end{gathered}
$$

The basic definitions and facts concerning eigenvalues, eigenvectors, and associate vectors of analytic operator-valued functions can be found in [2]. In the sequel, it is essential that the spectrum of the operator $\widetilde{\mathcal{L}}(\lambda)$ is discrete (see Lemma 2.1 in [11]).

## 2. PERTURBATIONS BY LOWER ORDER TERMS

2.1. Reduction to weighted spaces. Introduce the lower order terms operator

$$
\begin{equation*}
A^{\prime}\left(y, D_{y}\right)=\sum_{|\alpha| \leq 2 m-1} a_{\alpha}(y) D^{\alpha}, \tag{2.1}
\end{equation*}
$$

where $a_{\alpha} \in C^{\infty}\left(\mathbb{R}^{2}\right)$. Consider the perturbed operator $\mathbf{P}^{\prime}: \mathrm{D}\left(\mathbf{P}^{\prime}\right) \subset L_{2}(G) \rightarrow L_{2}(G)$ given by

$$
\begin{gathered}
\mathbf{P}^{\prime} u=\mathbf{A}\left(y, D_{y}\right) u+A^{\prime}\left(y, D_{y}\right) u \\
u \in \mathrm{D}\left(\mathbf{P}^{\prime}\right)=\left\{u \in W^{m}(G, \mathbf{B}): \mathbf{A}\left(y, D_{y}\right) u+A^{\prime}\left(y, D_{y}\right) u \in L_{2}(G)\right\} .
\end{gathered}
$$

By Theorem 1.1, the unbounded operator $\mathbf{P}^{\prime}$ has the Fredholm property (just as $\mathbf{P}$ does). The main result of this section (to be proved in Subsection 2.2) is as follows.

Theorem 2.1. Let Conditions 1.1-1.3 hold. Then ind $\mathbf{P}^{\prime}=\operatorname{ind} \mathbf{P}$.
This theorem shows that the lower order terms in (1.4) do not affect the index of the unbounded operator $\mathbf{P}$. The difficulty is that the above perturbations are, in general, neither compact nor $\mathbf{P}$-compact in the sense of Definition A.2. If $m=1$, then $u \in \mathrm{D}(\mathbf{P})$ implies only $u \in W^{1}(G)$, which ensures the $\mathbf{P}$-boundedness of the perturbation but not its $\mathbf{P}$-compactness. However, if $m \geq 2$, then $u \in \mathrm{D}(\mathbf{P})$ does not imply $u \in W^{2 m-1}(G)$, and the perturbation is not even $\mathbf{P}$-bounded. Moreover, $\mathrm{D}\left(\mathbf{P}^{\prime}\right) \neq \mathrm{D}(\mathbf{P})$ in the latter case.

To overcome this difficulty, we introduce the operator $\mathbf{Q}: \mathrm{D}(\mathbf{Q}) \subset L_{2}(G) \rightarrow H_{a}^{0}(G)$ given by

$$
\begin{equation*}
\mathbf{Q} u=\mathbf{A}\left(y, D_{y}\right) u, \quad u \in \mathrm{D}(\mathbf{Q})=\left\{u \in W^{m}(G, \mathbf{B}): \mathbf{A}\left(y, D_{y}\right) u \in H_{a}^{0}(G)\right\} . \tag{2.2}
\end{equation*}
$$

[^2]In this definition and further (unless otherwise stated), we assume that

$$
m-1<a<m
$$

We will prove that ind $\mathbf{Q}=$ ind $\mathbf{P}$. On the other hand, we will show that the operator $A^{\prime}\left(y, D_{y}\right)$ is a $\mathbf{Q}$-compact perturbation and, therefore, does not change the index of $\mathbf{Q}$ and hence of $\mathbf{P}$.

Lemma 2.1. Let the line $\operatorname{Im} \lambda=a+1-2 m$ contain no eigenvalues of the operator $\widetilde{\mathcal{L}}(\lambda)$. Then the operator $\mathbf{Q}$ has the Fredholm property and ind $\mathbf{Q}=$ ind $\mathbf{P}$.

Proof. 1. It is shown in [16, Section 6] that $\mathbf{B}_{i \mu} u \in H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right) \dot{+} R_{a}^{i \mu}\left(\Gamma_{i}\right)$ for $u \in H_{a}^{2 m}(G)$, where $R_{a}^{i \mu}\left(\Gamma_{i}\right)$ is a finite-dimensional subspace in $H_{a^{\prime}}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)$ for any $a^{\prime}>2 m-1$. Set

$$
\mathcal{H}_{a}^{0}(G, \Gamma)=H_{a}^{0}(G) \times \prod_{i=1}^{N} \prod_{\mu=1}^{m} H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right), \quad \mathcal{R}_{a}^{0}(G, \Gamma)=\{0\} \times \prod_{i=1}^{N} \prod_{\mu=1}^{m} R_{a}^{i \mu}\left(\Gamma_{i}\right)
$$

By Theorem 6.1 in [16], the bounded operator

$$
\begin{equation*}
\mathbf{L}=\left\{\mathbf{A}\left(y, D_{y}\right), \mathbf{B}_{i \mu}\right\}: H_{a}^{2 m}(G) \rightarrow \mathcal{H}_{a}^{0}(G, \Gamma) \dot{+} \mathcal{R}_{a}^{0}(G, \Gamma) \tag{2.3}
\end{equation*}
$$

has the Fredholm property. Therefore, by virtue of the compactness of the embedding $H_{a}^{2 m}(G) \subset$ $L_{2}(G)$ (see Lemma A.1) and by Theorem A.1, we have

$$
\begin{equation*}
\|u\|_{H_{a}^{2 m}(G)} \leq k_{1}\left(\|\mathbf{L} u\|_{\mathcal{H}_{a}^{0}(G, \Gamma) \dot{+} \mathcal{R}_{a}^{0}(G, \Gamma)}+\|u\|_{L_{2}(G)}\right) \tag{2.4}
\end{equation*}
$$

2. Introduce an unbounded operator $\dot{\mathbf{Q}}: \mathrm{D}(\dot{\mathbf{Q}}) \subset L_{2}(G) \rightarrow H_{a}^{0}(G)$ given by

$$
\begin{equation*}
\dot{\mathbf{Q}} u=\mathbf{A}\left(y, D_{y}\right) u, \quad u \in \mathrm{D}(\dot{\mathbf{Q}})=\left\{u \in H_{a}^{2 m}(G): \mathbf{B}_{i \mu} u=0\right\} \tag{2.5}
\end{equation*}
$$

Since $H_{a}^{2 m}(G) \subset W^{m}(G)$, it follows that $\dot{\mathbf{Q}}$ is a restriction of $\mathbf{Q}$, i.e., $\dot{\mathbf{Q}} \subset \mathbf{Q}$.
First, we prove that $\dot{\mathbf{Q}}$ has the Fredholm property. Let $u \in \mathrm{D}(\dot{\mathbf{Q}})$; then $u \in \mathrm{D}(\mathbf{L})=H_{a}^{2 m}(G)$ and $\mathbf{A}\left(y, D_{y}\right) u \in H_{a}^{0}(G), \mathbf{B}_{i \mu} u=0$. Therefore, estimate (2.4) acquires the form

$$
\begin{equation*}
\|u\|_{H_{a}^{2 m}(G)} \leq k_{1}\left(\|\dot{\mathbf{Q}} u\|_{H_{a}^{0}(G)}+\|u\|_{L_{2}(G)}\right) \quad \forall u \in \mathrm{D}(\dot{\mathbf{Q}}) \tag{2.6}
\end{equation*}
$$

It follows from (2.6) that the operator $\dot{\mathbf{Q}}$ is closed, $\operatorname{dim} \operatorname{ker} \dot{\mathbf{Q}}<\infty$, and $\mathcal{R}(\dot{\mathbf{Q}})=\overline{\mathcal{R}(\dot{\mathbf{Q}})}$ (to obtain the latter two properties, one must apply Theorem A.1).

Let us prove that $\operatorname{codim} \mathcal{R}(\dot{\mathbf{Q}})<\infty$. Since $\mathbf{L}$ has the Fredholm property, there exist finitely many linearly independent functions $F_{1}, \ldots, F_{d} \in H_{a}^{0}(G)$ such that a function $f \in H_{a}^{0}(G)$ belongs to the image of $\dot{\mathbf{Q}}$ if and only if $\left(f, F_{j}\right)_{H_{a}^{0}(G)}=0, j=1, \ldots, d$. Thus, $\dot{\mathbf{Q}}$ has the Fredholm property.
3. Now we prove that $\mathbf{Q}$ has the Fredholm property. Since $\operatorname{ker} \mathbf{Q}=\operatorname{ker} \mathbf{P}$ and $\mathbf{P}$ has the Fredholm property, it follows that

$$
\begin{equation*}
\operatorname{dim} \operatorname{ker} \mathbf{Q}=\operatorname{dim} \operatorname{ker} \mathbf{P}<\infty \tag{2.7}
\end{equation*}
$$

On the other hand, $\mathbf{Q}$ is an extension of the Fredholm operator $\dot{\mathbf{Q}}$; therefore,

$$
\begin{equation*}
\mathcal{R}(\mathbf{Q})=\overline{\mathcal{R}(\mathbf{Q})}, \quad \operatorname{codim} \mathcal{R}(\mathbf{Q})<\infty \tag{2.8}
\end{equation*}
$$

Thus, $\mathbf{Q}$ is an extension of the Fredholm operator $\dot{\mathbf{Q}}$ and possesses properties (2.7) and (2.8). Applying Theorem A.2, we see that $\mathbf{Q}$ has the Fredholm property.
4. By virtue of (2.7), it remains to be proved that $\operatorname{codim} \mathcal{R}(\mathbf{Q})=\operatorname{codim} \mathcal{R}(\mathbf{P})$.

Let $\operatorname{codim} \mathcal{R}(\mathbf{Q})=d_{1}$, where $d_{1} \leq d$. Take an arbitrary function $f \in L_{2}(G)$. Then $f \in \mathcal{R}(\mathbf{P})$ if and only if $f \in \mathcal{R}(\mathbf{Q})$ because $L_{2}(G) \subset H_{a}^{0}(G)$. However, the inclusion $f \in \mathcal{R}(\mathbf{Q})$ is equivalent to the relations $\left(f, F_{j}\right)_{H_{a}^{0}(G)}=0, j=1, \ldots, d_{1}$, where $F_{1}, \ldots, F_{d_{1}} \in H_{a}^{0}(G)$ are linearly independent functions. Using Schwarz' inequality, the boundedness of the embedding $L_{2}(G) \subset H_{a}^{0}(G)$, and Riesz' theorem, we see that these relations are equivalent to the following ones: $\left(f, f_{j}\right)_{L_{2}(G)}=0$, $j=1, \ldots, d_{1}$, where $f_{j} \in L_{2}(G)$. Moreover, the functions $f_{1}, \ldots, f_{d_{1}}$ are linearly independent. (Otherwise, some linear combination of the functions $F_{1}, \ldots, F_{d_{1}}$ would be orthogonal in $H_{a}^{0}(G)$ to any function that lies in $L_{2}(G)$. This is impossible because $F_{1}, \ldots, F_{d_{1}}$ are linearly independent, while $L_{2}(G)$ is dense in $H_{a}^{0}(G)$.) Thus, we have proved that $\operatorname{codim} \mathcal{R}(\mathbf{P})=d_{1}$.

Introduce a perturbed operator $\mathbf{Q}^{\prime}: \mathrm{D}\left(\mathbf{Q}^{\prime}\right) \subset L_{2}(G) \rightarrow H_{a}^{0}(G)$ given by

$$
\begin{gathered}
\mathbf{Q}^{\prime} u=\mathbf{A}\left(y, D_{y}\right) u+A^{\prime}\left(y, D_{y}\right) u \\
u \in \mathrm{D}\left(\mathbf{Q}^{\prime}\right)=\left\{u \in W^{m}(G, \mathbf{B}): \mathbf{A}\left(y, D_{y}\right) u+A^{\prime}\left(y, D_{y}\right) u \in H_{a}^{0}(G)\right\} .
\end{gathered}
$$

In the following subsection, we prove that ind $\mathbf{Q}^{\prime}=\operatorname{ind} \mathbf{Q}$, provided that the line $\operatorname{Im} \lambda=a+1-2 m$ contains no eigenvalues of the operator $\widetilde{\mathcal{L}}(\lambda)$. Then, using the discreteness of the spectrum of $\widetilde{\mathcal{L}}(\lambda)$ and Lemma 2.1, we will prove Theorem 2.1.

### 2.2. Compactness of lower order terms in weighted spaces.

Lemma 2.2. Let the line $\operatorname{Im} \lambda=a+1-2 m$ contain no eigenvalues of the operator $\widetilde{\mathcal{L}}(\lambda)$. Then

$$
\|u\|_{W^{m}(G)} \leq c\left(\|\mathbf{Q} u\|_{H_{a}^{0}(G)}+\|u\|_{L_{2}(G)}\right) \quad \forall u \in \mathrm{D}(\mathbf{Q})
$$

Proof. Consider the unbounded operator $\widehat{\mathbf{Q}}: \mathrm{D}(\widehat{\mathbf{Q}}) \subset W^{m}(G) \rightarrow H_{a}^{0}(G)$ given by $\widehat{\mathbf{Q}} u=$ $\mathbf{A}\left(y, D_{y}\right) u, u \in \mathrm{D}(\widehat{\mathbf{Q}})=\mathrm{D}(\mathbf{Q})$. Since $\mathbf{Q}$ has the Fredholm property, the same is true for $\widehat{\mathbf{Q}}$. Therefore, the desired estimate follows from the compactness of the embedding $W^{m}(G) \subset L_{2}(G)$ and from Theorem A.1.

Take a number $b$ such that

$$
\begin{equation*}
m-1<b<a<m \tag{2.9}
\end{equation*}
$$

Consider a function $\psi_{j} \in C_{0}^{\infty}\left(\mathbb{R}^{2}\right)$ equal to 1 in a small neighborhood of the point $g_{j} \in \mathcal{K}$ and vanishing outside a larger neighborhood of $g_{j}$. The following lemma describes the behavior of $u \in \mathrm{D}(\mathbf{Q})$ near the set $\mathcal{K}$.

Lemma 2.3. For any $u \in \mathrm{D}(\mathbf{Q})$, we have

$$
\begin{equation*}
u(y)=\sum_{j=1}^{N} P_{j}(y)+v(y) \tag{2.10}
\end{equation*}
$$

where

$$
\begin{equation*}
P_{j}(y)=\psi_{j}(y) \sum_{|\alpha| \leq m-2} p_{j \alpha}\left(y-g_{j}\right)^{\alpha}, \quad p_{j \alpha} \in \mathbb{C} \tag{2.11}
\end{equation*}
$$

and $v \in H_{b+1}^{2 m}(G)\left(\right.$ if $m=1$, we set $\left.P_{j}(y) \equiv 0\right)$; moreover,

$$
\begin{equation*}
\sum_{j, \alpha}\left|p_{j \alpha}\right|+\|v\|_{H_{b+1}^{2 m}(G)} \leq c\left(\|\mathbf{Q} u\|_{H_{a}^{0}(G)}+\|u\|_{L_{2}(G)}\right) \tag{2.12}
\end{equation*}
$$

Proof. 1. It follows from Lemma 1.1 that $u \in W^{2 m}\left(G \backslash \overline{\mathcal{O}_{\delta}(\mathcal{K})}\right)$ for any $\delta>0$ and

$$
\begin{equation*}
\|u\|_{W^{2 m}\left(G \backslash \overline{\left.\mathcal{O}_{\delta}(\mathcal{K})\right)}\right.} \leq k_{1 \delta}\left(\|\mathbf{Q} u\|_{H_{a}^{0}(G)}+\|u\|_{L_{2}(G)}\right) \tag{2.13}
\end{equation*}
$$

where $k_{1 \delta}$ does not depend on $u$. Therefore, it suffices to consider the behavior of $u$ near the set $\mathcal{K}$.
By Lemma A.2, $u \in W^{m}(G)$ can be represented in the form (2.10), where $P_{j}(y)$ is given by (2.11), $v \in H_{b-m+1}^{m}(G)$, and

$$
\begin{equation*}
\sum_{j, \alpha}\left|p_{j \alpha}\right|+\|v\|_{H_{b-m+1}^{m}(G)} \leq k_{2}\left(\|\mathbf{Q} u\|_{H_{a}^{0}(G)}+\|u\|_{L_{2}(G)}\right) \tag{2.14}
\end{equation*}
$$

(to obtain (2.14), we have also applied Lemma 2.2).
Moreover, relations (2.10), (2.13), and (2.14) imply that

$$
\begin{equation*}
\|v\|_{W^{2 m}\left(G \backslash \overline{\left.\mathcal{O}_{\delta}(\mathcal{K})\right)}\right.} \leq k_{2 \delta}\left(\|\mathbf{Q} u\|_{H_{a}^{0}(G)}+\|u\|_{L_{2}(G)}\right) \quad \forall \delta>0, \tag{2.15}
\end{equation*}
$$

where $k_{2 \delta}$ does not depend on $u$. It remains to be proved that $v \in H_{b+1}^{2 m}(G)$.
2. By using (1.4) and (1.5), we see that $v$ is a solution of the problem

$$
\begin{equation*}
\mathbf{A}\left(y, D_{y}\right) v=f-\mathbf{A}\left(y, D_{y}\right) P \equiv f^{\prime}, \quad \mathbf{B}_{i \mu}^{0} v+\mathbf{B}_{i \mu}^{1} v=-\mathbf{B}_{i \mu} P-\mathbf{B}_{i \mu}^{2} v \equiv f_{i \mu}^{\prime}, \tag{2.16}
\end{equation*}
$$

where $P(y)=\sum_{j=1}^{N} P_{j}(y)$ and $f=\mathbf{Q} u \in H_{a}^{0}(G)$. It follows from the boundedness of the embedding $H_{a}^{0}(G) \subset H_{b+1}^{0}(G)$ (see (2.9)) and from the estimate of the coefficients $p_{j \alpha}$ (see (2.14)) that

$$
\begin{equation*}
\left\|f^{\prime}\right\|_{H_{b+1}^{0}(G)} \leq k_{3}\left(\|\mathbf{Q} u\|_{H_{a}^{0}(G)}+\|u\|_{L_{2}(G)}\right) . \tag{2.17}
\end{equation*}
$$

Similarly, using additionally inequalities (1.2) and (2.15), we obtain $f_{i \mu}^{\prime}=-\mathbf{B}_{i \mu} P-\mathbf{B}_{i \mu}^{2} v \in$ $W^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)$ and

$$
\begin{equation*}
\left\|f_{i \mu}^{\prime}\right\|_{W^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)} \leq k_{4}\left(\|\mathbf{Q} u\|_{H_{a}^{0}(G)}+\|u\|_{L_{2}(G)}\right) \tag{2.18}
\end{equation*}
$$

On the other hand, $v \in H_{b-m+1}^{m}(G)$; hence, $f_{i \mu}^{\prime}=\mathbf{B}_{i \mu}^{0} v+\mathbf{B}_{i \mu}^{1} v \in H_{b-m+1}^{m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)$. We claim that

$$
\begin{equation*}
\left\|f_{i \mu}^{\prime}\right\|_{H_{b+1}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)} \leq k_{5}\left(\|\mathbf{Q} u\|_{H_{a}^{0}(G)}+\|u\|_{L_{2}(G)}\right) \tag{2.19}
\end{equation*}
$$

To prove this assertion, we fix $i$ and $\mu$ and set $\Gamma=\Gamma_{i}$. Let $g \in \bar{\Gamma} \backslash \Gamma$. Assume, without loss of generality, that $g=0$ and $\Gamma$ coincides with the axis $O y_{1}$ in a sufficiently small neighborhood $\mathcal{O}_{\varepsilon}(0)$ of the origin. Denote

$$
G^{\varepsilon}=G \cap \mathcal{O}_{\varepsilon}(0), \quad \Gamma^{\varepsilon}=\Gamma \cap \mathcal{O}_{\varepsilon}(0)
$$

in which case $H_{a}^{k}\left(G^{\varepsilon}\right)=H_{a}^{k}\left(G^{\varepsilon},\{0\}\right)$.
Using Lemma A.3(1), we represent $f_{i \mu}^{\prime} \in W^{2 m-m_{i \mu}-1 / 2}\left(\Gamma^{\varepsilon}\right)$ near the origin as follows:

$$
f_{i \mu}^{\prime}(r)=P_{1}(r)+f_{i \mu}^{\prime \prime}(r), \quad 0<r<\varepsilon,
$$

where $P_{1}(r)$ is a polynomial of order $2 m-m_{i \mu}-2$, whereas $f_{i \mu}^{\prime \prime} \in H_{b+1}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma^{\varepsilon}\right)$ (in fact, we can replace $b+1$ by any positive number in the last relation). Now we have $f_{i \mu}^{\prime}, f_{i \mu}^{\prime \prime} \in H_{b-m+1}^{m-m_{i \mu}-1 / 2}\left(\Gamma^{\varepsilon}\right)$; therefore, $P_{1} \in H_{b-m+1}^{m-m_{i \mu}-1 / 2}\left(\Gamma^{\varepsilon}\right)$; i.e., $P_{1}$ consists of monomials of order greater than or equal to $m-m_{i \mu}-1$. This implies that $P_{1} \in H_{b+1}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma^{\varepsilon}\right)$. Using Lemma A.3(3), we obtain

$$
\left\|f_{i \mu}^{\prime}\right\|_{H_{b+1}^{2 m-m_{i \mu}-1 / 2}{ }_{\left(\Gamma^{\varepsilon}\right)}} \leq\left\|P_{1}\right\|_{H_{b+1}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma^{\varepsilon}\right)}+\left\|f_{i \mu}^{\prime \prime}\right\|_{H_{b+1}^{2 m-m_{i \mu}-1 / 2}{ }_{\left(\Gamma^{\varepsilon}\right)}} \leq k_{6}\left\|f_{i \mu}^{\prime}\right\|_{W^{2 m-m_{i \mu}-1 / 2}\left(\Gamma^{\varepsilon}\right)} .
$$

Combining this estimate with (2.18) yields (2.19).
3. Applying Lemma 1.2 to problem (2.16) and taking into account (2.15), (2.17), (2.19), and (2.14), we obtain

$$
\begin{aligned}
\|v\|_{H_{b+1}^{2 m}(G)} & \leq k_{7}\left(\left\|f^{\prime}\right\|_{H_{b+1}^{0}(G)}+\sum_{i, \mu}\left\|f_{i \mu}^{\prime}\right\|_{H_{b+1}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)}+\|v\|_{H_{b-2 m+1}^{0}(G)}\right) \\
& \leq k_{8}\left(\|\mathbf{Q} u\|_{H_{a}^{0}(G)}+\|u\|_{L_{2}(G)}\right) .
\end{aligned}
$$

Combining this inequality with (2.14) yields (2.12).
The following corollary results from Lemma 2.3.
Corollary 2.1. Let $A^{\prime}\left(y, D_{y}\right)$ be the differential operator of order $2 m-1$ given by (2.1). Then

$$
\begin{equation*}
\left\|A^{\prime}\left(y, D_{y}\right) u\right\|_{H_{b+1}^{1}(G)} \leq c\left(\|\mathbf{Q} u\|_{H_{a}^{0}(G)}+\|u\|_{L_{2}(G)}\right) \quad \forall u \in \mathrm{D}(\mathbf{Q}) \tag{2.20}
\end{equation*}
$$

Now we can prove that lower order perturbations in (1.4) do not change the index of $\mathbf{Q}$.
Lemma 2.4. Let the line $\operatorname{Im} \lambda=a+1-2 m$ contain no eigenvalues of the operator $\widetilde{\mathcal{L}}(\lambda)$. Then the operators $\mathbf{Q}$ and $\mathbf{Q}^{\prime}$ have the Fredholm property and $\operatorname{ind} \mathbf{Q}^{\prime}=\operatorname{ind} \mathbf{Q}$.

Proof. By Lemma 2.1, $\mathbf{Q}$ and $\mathbf{Q}^{\prime}$ have the Fredholm property.
Introduce an operator $\mathbf{A}^{\prime}: \mathrm{D}\left(\mathbf{A}^{\prime}\right) \subset L_{2}(G) \rightarrow H_{a}^{0}(G)$ given by $\mathbf{A}^{\prime} u=\mathbf{A}^{\prime}\left(y, D_{y}\right) u, u \in \mathrm{D}\left(\mathbf{A}^{\prime}\right)=$ $\mathrm{D}(\mathbf{Q})$. It follows from Corollary 2.1 and from the compactness of the embedding $H_{b+1}^{1}(G) \subset H_{a}^{0}(G)$ (see (2.9) and Lemma A.1) that $\mathbf{Q}^{\prime}=\mathbf{Q}+\mathbf{A}^{\prime}$ and $\mathbf{A}^{\prime}$ is a $\mathbf{Q}$-compact operator. Therefore, by Theorem A.4, we have ind $\mathbf{Q}^{\prime}=\operatorname{ind} \mathbf{Q}$.

Proof of Theorem 2.1. It follows from Lemma 2.1 in [11] that the spectrum of $\widetilde{\mathcal{L}}(\lambda)$ is discrete. Therefore, one can find a number $a$ such that $m-1<a<m$ and the $\operatorname{line} \operatorname{Im} \lambda=a+1-2 m$ contains no eigenvalues of $\widetilde{\mathcal{L}}(\lambda)$. In this case, Lemmas 2.1 and 2.4 imply ind $\mathbf{P}^{\prime}=\operatorname{ind} \mathbf{Q}^{\prime}=\operatorname{ind} \mathbf{Q}=$ ind $\mathbf{P}$.

## 3. PERTURBATIONS IN NONLOCAL CONDITIONS

3.1. Formulation of the main result. In this section, we study the stability of the index for nonlocal operators under the perturbation of nonlocal conditions by operators of the same form as $\mathbf{B}_{i \mu}^{1}$ and $\mathbf{B}_{i \mu}^{2}$. This situation is more difficult than that in Section 2 because the above perturbations explicitly change the domain of the corresponding unbounded operators. Therefore, these perturbations cannot be treated as relatively compact ones, and we make use of another approach based on the notion of a gap between closed operators.

We consider differential operators $C_{i \mu s}\left(y, D_{y}\right), i=1, \ldots, N, \mu=1, \ldots, m, s=1, \ldots, S_{i}^{\prime}$, of the same order $m_{i \mu}$ as $B_{i \mu s}$ in Subsection 1.1, given by

$$
C_{i \mu s}\left(y, D_{y}\right) u=\sum_{|\alpha| \leq m_{i \mu}} c_{i \mu s \alpha}(y) D^{\alpha} u
$$

where $c_{i \mu s \alpha} \in C^{\infty}\left(\mathbb{R}^{2}\right)$. Introduce an operator $\mathbf{C}_{i \mu}^{1}$ by the formula

$$
\mathbf{C}_{i \mu}^{1} u=\sum_{s=1}^{S_{i}^{\prime}}\left(C_{i \mu s}\left(y, D_{y}\right)(\zeta u)\right)\left(\Omega_{i s}^{\prime}(y)\right), \quad y \in \Gamma_{i} \cap \mathcal{O}_{\varepsilon}(\mathcal{K}), \quad \mathbf{C}_{i \mu}^{1} u=0, \quad y \in \Gamma_{i} \backslash \mathcal{O}_{\varepsilon}(\mathcal{K})
$$

where $\zeta$ and $\varepsilon$ are the same as in the definition of $\mathbf{B}_{i \mu}^{1}$, whereas $\Omega_{i s}^{\prime}$ are $C^{\infty}$ diffeomorphisms possessing the same properties as $\Omega_{i s}$ (in particular, they satisfy Condition 1.2 with $S_{i}$ and $\Omega_{i s}$ replaced by $S_{i}^{\prime}$ and $\Omega_{i s}^{\prime}$ ).

We also consider operators $\mathbf{C}_{i \mu}^{2}$ satisfying Condition 1.3 with $\mathbf{B}_{i \mu}^{2}$ replaced by $\mathbf{C}_{i \mu}^{2}$. Set

$$
\mathbf{C}_{i \mu}=\mathbf{C}_{i \mu}^{1}+\mathbf{C}_{i \mu}^{2}
$$

We prove an index stability theorem under the following conditions (which are assumed to hold along with Conditions 1.1-1.3 throughout this section, including the formulation of lemmas).

Condition 3.1 (see, e.g., [9]). The system $\left\{\mathbf{B}_{i \mu}^{0}\right\}_{\mu=1}^{m}$ is normal on $\bar{\Gamma}_{i}, i=1, \ldots, N$.
Condition 3.2. $D^{\sigma} c_{i \mu s \alpha}\left(g_{i 1}\right)=D^{\sigma} c_{i \mu s \alpha}\left(g_{i 2}\right)=0$ for $|\sigma|=0, \ldots,(m-1)-\left(m_{i \mu}-|\alpha|\right)$.
Denote by $g_{i 1}$ and $g_{i 2}$ the end points of $\bar{\Gamma}_{i}$. Let $\tau_{i 1}\left(\tau_{i 2}\right)$ be a unit vector tangent to $\bar{\Gamma}_{i}$ at the point $g_{i 1}\left(g_{i 2}\right)$.

## Condition 3.3.

$$
\left.\frac{\partial^{\beta} \mathbf{C}_{i \mu}^{2} u}{\partial \tau_{i 1}^{\beta}}\right|_{y=g_{i 1}}=\left.\frac{\partial^{\beta} \mathbf{C}_{i \mu}^{2} u}{\partial \tau_{i 2}^{\beta}}\right|_{y=g_{i 2}}=0, \quad \beta=0, \ldots, m-1-m_{i \mu}, \quad \forall u \in W^{2 m}\left(G \backslash \overline{\mathcal{O}_{\varkappa_{1}}(\mathcal{K})}\right) .
$$

The following lemma is a consequence of Conditions 3.2 and 3.3 (recall that $m-1<a<m$ throughout).

Lemma 3.1. The following inequalities hold:

$$
\begin{align*}
& \left\|\mathbf{C}_{i \mu}^{1} u\right\|_{H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)} \leq c_{1}\|u\|_{H_{a+m}^{2 m}(G)},  \tag{3.1}\\
& \left\|\mathbf{C}_{i \mu}^{2} u\right\|_{H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)} \leq c_{2}\|u\|_{W^{2 m}\left(G \backslash \overline{\mathcal{O}_{\varkappa_{1}}(\mathcal{K})}\right)} . \tag{3.2}
\end{align*}
$$

Proof. 1. For any $u \in H_{a+m}^{2 m}(G)$, we have

$$
\left.\left(D^{\alpha} u\right)\left(\Omega_{i s}^{\prime}(y)\right)\right|_{\Gamma_{i}} \in H_{a+m}^{2 m-|\alpha|-1 / 2}\left(\Gamma_{i}\right) \subset H_{a+m-\left(m_{i \mu}-|\alpha|\right)}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right) .
$$

Therefore, by Condition 3.2 and Lemma A.5, we have $\left.\left(c_{i \mu s \alpha} D^{\alpha} u\right)\left(\Omega_{i s}^{\prime}(y)\right)\right|_{\Gamma_{i}} \in H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)$. Estimate (3.1) follows from the boundedness of the above embedding and from inequality (A.5).
2. It follows from Condition 1.3 (applied to $\mathbf{C}_{i \mu}^{2}$ ) that $\mathbf{C}_{i \mu}^{2} u \in W^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)$ for any $u \in W^{2 m}\left(G \backslash \overline{\mathcal{O}_{\varkappa_{1}}(\mathcal{K})}\right)$. Now, by Condition 3.3 and Lemma A.4, $\mathbf{C}_{i \mu}^{2} u \in H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)$. Estimate (3.2) follows from inequality (1.2) (applied to $\mathbf{C}_{i \mu}^{2}$ ) and from (A.2).

In this section, we write $\mathbf{A}=\mathbf{A}\left(y, D_{y}\right)$. Consider the operators $\mathbf{P}_{t}: \mathrm{D}\left(\mathbf{P}_{t}\right) \subset L_{2}(G) \rightarrow L_{2}(G)$, $t \in \mathbb{C}$, given by

$$
\mathbf{P}_{t} u=\mathbf{A} u, \quad u \in \mathrm{D}\left(\mathbf{P}_{t}\right)=\left\{u \in W^{m}(G, \mathbf{B}+t \mathbf{C}): \mathbf{A} u \in L_{2}(G)\right\}
$$

where $W^{m}(G, \mathbf{B}+t \mathbf{C})$ is the space of functions $u \in W^{m}(G)$ that satisfy the nonlocal conditions $\left(\mathbf{B}_{i \mu}^{0}+\mathbf{B}_{i \mu}^{1}+t \mathbf{C}_{i \mu}\right) u=0$. The main result of this section (to be proved in Subsection 3.2) is as follows.

Theorem 3.1. Let Conditions 1.1-1.3 and 3.1-3.3 hold. Then ind $\mathbf{P}_{t}=$ const $\forall t \in \mathbb{C}$.
3.2. The gap between nonlocal operators in weighted spaces. As in Section 2, we preliminarily study the operators $\mathbf{Q}_{t}: \mathrm{D}\left(\mathbf{Q}_{t}\right) \subset L_{2}(G) \rightarrow H_{a}^{0}(G)$ given by

$$
\mathbf{Q}_{t} u=\mathbf{A} u, \quad u \in \mathrm{D}\left(\mathbf{Q}_{t}\right)=\left\{u \in W^{m}(G, \mathbf{B}+t \mathbf{C}): \mathbf{A} u \in H_{a}^{0}(G)\right\}
$$

where $t \in \mathbb{C}$ and $W^{m}(G, \mathbf{B}+t \mathbf{C})$ is the same as in the definition of the operator $\mathbf{P}_{t}$. The operators $\mathbf{P}_{t}$ and $\mathbf{Q}_{t}$ correspond to the problem

$$
\begin{gather*}
\mathbf{A} u=f(y), \quad y \in G  \tag{3.3}\\
\left(\mathbf{B}_{i \mu}^{0}+\mathbf{B}_{i \mu}^{1}+t \mathbf{C}_{i \mu}\right) u=0, \quad y \in \Gamma_{i}, \quad i=1, \ldots, N, \quad \mu=1, \ldots, m \tag{3.4}
\end{gather*}
$$

Remark 3.1. The operator $\widetilde{\mathcal{L}}(\lambda)$ was constructed in Subsection 1.2 by means of the principal homogeneous parts of the operators $\mathbf{A}$ and $B_{i \mu s}\left(y, D_{y}\right)$ at the points of the set $\mathcal{K}$. Due to Condition 3.2, the principal homogeneous parts of the operators $C_{i \mu s}\left(y, D_{y}\right)$ are equal to zero at these points. Therefore, the same operator $\widetilde{\mathcal{L}}(\lambda)$ corresponds to problem (3.3), (3.4) for any $t$.

Fix a number $a$ such that $m-1<a<m$ and the line $\operatorname{Im} \lambda=a+1-\underset{\mathcal{L}}{2} m$ contains no eigenvalues of $\widetilde{\mathcal{L}}(\lambda)$ (which is possible due to the discreteness of the spectrum of $\widetilde{\mathcal{L}}(\lambda)$ ). It follows from Remark 3.1 and Lemma 2.1 that $\mathbf{Q}_{t}$ has the Fredholm property. Therefore, its graph $\operatorname{Gr} \mathbf{Q}_{t}$ is a closed subspace in the Hilbert space $L_{2}(G) \times H_{a}^{0}(G)$; this space is endowed with the norm

$$
\|(u, f)\|=\left(\|u\|_{L_{2}(G)}^{2}+\|f\|_{H_{a}^{0}(G)}^{2}\right)^{1 / 2} \quad \forall(u, f) \in L_{2}(G) \times H_{a}^{0}(G)
$$

Denote

$$
\begin{equation*}
\delta\left(\mathbf{Q}_{t}, \mathbf{Q}_{t+s}\right)=\sup _{u \in \mathrm{D}\left(\mathbf{Q}_{t}\right):\left\|\left(u, \mathbf{Q}_{t} u\right)\right\|=1} \operatorname{dist}\left(\left(u, \mathbf{Q}_{t} u\right), \operatorname{Gr} \mathbf{Q}_{t+s}\right) \tag{3.5}
\end{equation*}
$$

By Definition A.3, the number $\widehat{\delta}\left(\mathbf{Q}_{t}, \mathbf{Q}_{t+s}\right)=\max \left\{\delta\left(\mathbf{Q}_{t}, \mathbf{Q}_{t+s}\right), \delta\left(\mathbf{Q}_{t+s}, \mathbf{Q}_{t}\right)\right\}$ is the gap between the operators $\mathbf{Q}_{t}$ and $\mathbf{Q}_{t+s}$.

The main tool that enables us to prove the index stability theorem is Theorem A. 5 and the following result (to be proved later on).

Theorem 3.2. Let Conditions 1.1-1.3 and 3.1-3.3 hold. Suppose that the lines $\operatorname{Im} \lambda=a+$ $1-2 m$ and $\operatorname{Im} \lambda=a+1-m$ contain no eigenvalues of $\widetilde{\mathcal{L}}(\lambda)$. Then

$$
\begin{equation*}
\widehat{\delta}\left(\mathbf{Q}_{t}, \mathbf{Q}_{t+s}\right) \leq c_{t} s, \quad|s| \leq s_{t} \tag{3.6}
\end{equation*}
$$

where $s_{t}>0$ is sufficiently small, while $c_{t}>0$ does not depend on $s$.
First, we prove several auxiliary results.
Lemma 3.2. Let the line $\operatorname{Im} \lambda=a+1-m$ contain no eigenvalues of $\widetilde{\mathcal{L}}(\lambda)$. Then, for all sufficiently small $|s|$, we have

$$
\begin{equation*}
\|u\|_{H_{a+m}^{2 m}(G)} \leq c_{t}\|(u, \mathbf{A} u)\| \quad \forall u \in \mathrm{D}\left(\mathbf{Q}_{t+s}\right) \tag{3.7}
\end{equation*}
$$

where $c_{t}>0$ does not depend on $s$ and $u$.
Proof. 1. Consider the bounded operator

$$
\begin{equation*}
\mathbf{M}_{t}=\left\{\mathbf{A}, \mathbf{B}_{i \mu}^{0}+\mathbf{B}_{i \mu}^{1}+t \mathbf{C}_{i \mu}\right\}: H_{a+m}^{2 m}(G) \rightarrow \mathcal{H}_{a+m}^{0}(G, \Gamma) \tag{3.8}
\end{equation*}
$$

If $v \in H_{a+m}^{2 m}(G)$, then $\left(\mathbf{B}_{i \mu}^{0}+\mathbf{B}_{i \mu}^{1}+t \mathbf{C}_{i \mu}^{1}\right) v \in H_{a+m}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)$ and $\mathbf{C}_{i \mu}^{2} v \in W^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right) \subset$ $H_{a+m}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)$ (the latter relations are due to Condition 1.3 and Lemma A.3(1)); thus, the operator $\mathbf{M}_{t}$ is well defined.

By Theorem 6.1 in [16] and by Remark 3.1, the operator $\mathbf{M}_{t}$ has the Fredholm property for any $t \in \mathbb{C}$. Therefore, applying Theorem A. 1 and noting that the embedding $H_{a+m}^{2 m} \subset L_{2}(G)$ is compact for $a<m$ (see Lemma A.1), we obtain

$$
\begin{equation*}
\|u\|_{H_{a+m}^{2 m}(G)} \leq k_{1}\left(\left\|\mathbf{M}_{t} u\right\|_{\mathcal{H}_{a+m}^{0}(G, \Gamma)}+\|u\|_{L_{2}(G)}\right) \quad \forall u \in H_{a+m}^{2 m}(G) \tag{3.9}
\end{equation*}
$$

where $k_{1}>0$ may depend on $t$ but does not depend on $s$ and $u$.
2. Now take a function $u \in \mathrm{D}\left(\mathbf{Q}_{t+s}\right)$. By Lemma 2.3, $u \in H_{a+m}^{2 m}(G)$. Inequality (3.9), estimate (1.2) (for $\mathbf{C}_{i \mu}^{2}$ ), and the boundedness of the embedding $W^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right) \subset H_{a+m}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)$ (see Lemma A.3(1)) yield

$$
\|u\|_{H_{a+m}^{2 m}(G)} \leq k_{1}\left(\|\mathbf{A} u\|_{H_{a+m}^{0}(G)}+\|u\|_{L_{2}(G)}\right)+k_{2}|s| \cdot\|u\|_{H_{a+m}^{2 m}(G)} \quad \forall u \in \mathrm{D}\left(\mathbf{Q}_{t+s}\right)
$$

where $k_{2}>0$ may depend on $t$ but does not depend on $s$ and $u$. Choosing $|s| \leq 1 /\left(2 k_{2}\right)$ and noting that the embedding $H_{a}^{0}(G) \subset H_{a+m}^{0}(G)$ is bounded, we obtain (3.7).

Lemmas 3.1 and 3.2 imply
Corollary 3.1. Let the line $\operatorname{Im} \lambda=a+1-m$ contain no eigenvalues of $\widetilde{\mathcal{L}}(\lambda)$. Then

$$
\begin{equation*}
\left\|\mathbf{C}_{i \mu} u\right\|_{H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)} \leq c_{t}\|(u, \mathbf{A} u)\| \quad \forall u \in \mathrm{D}\left(\mathbf{Q}_{t+s}\right) \tag{3.10}
\end{equation*}
$$

where $c_{t}>0$ does not depend on $s$ and $u$, provided that $|s|$ is sufficiently small.
The following two lemmas enable us to reduce nonlocal problems with nonhomogeneous nonlocal conditions to nonlocal problems with homogeneous ones. This is the place where Condition 3.1 is needed.

Lemma 3.3 (see Lemma 8.1 in [16]). Let $a \in \mathbb{R}$. Then, for any right-hand sides $f_{j \sigma \mu} \in$ $H_{a}^{2 m-m_{j \sigma \mu}-1 / 2}\left(\gamma_{j \sigma}\right)$ in (1.7) such that $\operatorname{supp} f_{j \sigma \mu} \subset \gamma_{j \sigma}^{\varepsilon / 2}$, there exist functions $U_{j} \in H_{a}^{2 m}\left(K_{j}\right)$ such that $\operatorname{supp} U_{j} \subset \overline{K_{j}^{\varepsilon}}$,

$$
\begin{aligned}
B_{j \sigma \mu j 0}\left(y, D_{y}\right) U_{j}(y)= & f_{j \sigma \mu}(y), \quad\left(B_{j \sigma \mu k s}\left(y, D_{y}\right) U_{k}\right)\left(\mathcal{G}_{j \sigma k s} y\right)=0, \quad y \in \gamma_{j \sigma}, \quad(k, s) \neq(j, 0), \\
& \sum_{j}\left\|U_{j}\right\|_{H_{a}^{2 m}\left(K_{j}\right)} \leq c \sum_{j, \sigma, \mu}\left\|f_{j \sigma \mu}\right\|_{H_{a}^{2 m-m_{j \sigma \mu}-1 / 2}\left(\gamma_{j \sigma}\right)}
\end{aligned}
$$

Lemma 3.4. Let $f_{i \mu} \in H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)$. Then, for $t \in \mathbb{C}$ and $|s| \leq 1$, there is a function $u \in H_{a}^{2 m}(G)$ such that

$$
\begin{gather*}
\left(\mathbf{B}_{i \mu}^{0}+\mathbf{B}_{i \mu}^{1}+(t+s) \mathbf{C}_{i \mu}\right) u=f_{i \mu},  \tag{3.11}\\
\|u\|_{H_{a}^{2 m}(G)} \leq c_{t} \sum_{i, \mu}\left\|f_{i \mu}\right\|_{H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)}, \tag{3.12}
\end{gather*}
$$

where $c_{t}>0$ does not depend on $f_{i \mu}$ and $s$.
Proof. Using Lemma 3.3 and a partition of unity, we construct a function $v \in H_{a}^{2 m}(G)$ such that

$$
\begin{gather*}
\operatorname{supp} v \subset \bar{G} \backslash \bar{G}_{\rho},  \tag{3.13}\\
\mathbf{B}_{i \mu}^{0} v=f_{i \mu}, \quad \mathbf{B}_{i \mu}^{1} v=0, \quad \mathbf{C}_{i \mu}^{1} v=0  \tag{3.14}\\
\|v\|_{H_{a}^{2 m}(G)} \leq k_{1} \sum_{i, \mu}\left\|f_{i \mu}\right\|_{H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)} \tag{3.15}
\end{gather*}
$$

where $k_{1}>0$ does not depend on $f_{i \mu}, t$, and $s$.
By (3.13) and (1.3), we have supp $\mathbf{C}_{i \mu}^{2} v \subset \mathcal{O}_{\varkappa_{2}}(\mathcal{K})$. Moreover, by virtue of Lemma 3.1, $\mathbf{C}_{i \mu}^{2} v \in$ $H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)$. Therefore, using Lemma 3.3 and a partition of unity again, we construct a function $w \in H_{a}^{2 m}(G)$ such that

$$
\begin{equation*}
\operatorname{supp} w \subset \mathcal{O}_{\varkappa_{1}}(\mathcal{K}) \tag{3.16}
\end{equation*}
$$

$$
\begin{gather*}
\mathbf{B}_{i \mu}^{0} w=-(t+s) \mathbf{C}_{i \mu}^{2} v, \quad \mathbf{B}_{i \mu}^{1} w=0, \quad \mathbf{C}_{i \mu}^{1} w=0  \tag{3.17}\\
\|w\|_{H_{a}^{2 m}(G)} \leq k_{1} \sum_{i, \mu}\left\|(t+s) \mathbf{C}_{i \mu}^{2} v\right\|_{H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)}
\end{gather*}
$$

Using the relation $|s| \leq 1$ and inequalities (3.2) and (3.15), from the last inequality we infer

$$
\begin{equation*}
\|w\|_{H_{a}^{2 m}(G)} \leq k_{1} \sum_{i, \mu}(|t|+1)\left\|\mathbf{C}_{i \mu}^{2} v\right\|_{H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)} \leq k_{2}\|v\|_{H_{a}^{2 m}(G)} \leq k_{2} k_{1} \sum_{i, \mu}\left\|f_{i \mu}\right\|_{H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)}, \tag{3.18}
\end{equation*}
$$

where $k_{2}>0$ may depend on $t$ but does not depend on $f_{i \mu}$ and $s$.
By (3.16) and (3.2), we have $\mathbf{C}_{i \mu}^{2} w=0$. It follows from this relation, (3.14), and (3.17) that $u=v+w$ satisfies (3.11). Inequality (3.12) follows from inequalities (3.15) and (3.18).

Remark 3.2. One can easily see that if $\left(\mathbf{C}_{i \mu}^{2} v\right)(y)=0$ in $\mathcal{O}_{\varkappa}(\mathcal{K})$ for some $\varkappa>0$ and for any $v \in W^{2 m}\left(G \backslash \overline{\mathcal{O}_{\varkappa_{1}}(\mathcal{K})}\right)$, then Lemma 3.4 is true for any $a \in \mathbb{R}$.

Proof of Theorem 3.2. 1. We must prove inequality (3.6) for the quantity $\widehat{\delta}\left(\mathbf{Q}_{t}, \mathbf{Q}_{t+s}\right)$ replaced by $\delta\left(\mathbf{Q}_{t}, \mathbf{Q}_{t+s}\right)$ and $\delta\left(\mathbf{Q}_{t+s}, \mathbf{Q}_{t}\right)$. Let us prove the inequality

$$
\begin{equation*}
\delta\left(\mathbf{Q}_{t}, \mathbf{Q}_{t+s}\right) \leq c_{t}|s|, \quad|s| \leq s_{t} \tag{3.19}
\end{equation*}
$$

(The corresponding inequality for $\delta\left(\mathbf{Q}_{t+s}, \mathbf{Q}_{t}\right)$ is proved in a similar way.)
Fix an arbitrary number $t$ and take a function $u \in \mathrm{D}\left(\mathbf{Q}_{t}\right)$. According to the definition (3.5), it suffices to find a function $v_{s} \in \mathrm{D}\left(\mathbf{Q}_{t+s}\right)$ (which depends on $\left.u\right)$ such that

$$
\begin{equation*}
\left\|u-v_{s}\right\|_{L_{2}(G)}+\left\|\mathbf{A} u-\mathbf{A} v_{s}\right\|_{H_{a}^{0}(G)} \leq k_{1}|s| \cdot\|(u, \mathbf{A} u)\|, \tag{3.20}
\end{equation*}
$$

where $|s|$ is sufficiently small and $k_{1}, k_{2}, \ldots>0$ may depend on $t$ but do not depend on $u$ and $s$.
Let us seek $v_{s} \in \mathrm{D}\left(\mathbf{Q}_{t+s}\right)$ in the form

$$
\begin{equation*}
v_{s}=u+w_{s} \tag{3.21}
\end{equation*}
$$

where $w_{s} \in H_{a}^{2 m}(G)$ is a solution of the problem

$$
\begin{equation*}
\mathbf{A} w_{s}=\sum_{j=1}^{J_{s}} \beta_{j}^{s} f_{j}^{s}, \quad\left(\mathbf{B}_{i \mu}^{0}+\mathbf{B}_{i \mu}^{1}+(t+s) \mathbf{C}_{i \mu}\right) w_{s}=-s \mathbf{C}_{i \mu} u ; \tag{3.22}
\end{equation*}
$$

the numbers $J_{s}$ and $\beta_{j}^{s}$, as well as the functions $f_{j}^{s} \in H_{a}^{0}(G)$, will be defined later in such a way that the solution $w_{s} \in H_{a}^{2 m}(G)$ exists.
2. To solve problem (3.22), we first note that $\mathbf{C}_{i \mu} u \in H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)$ due to Corollary 3.1. Hence, we can apply Lemma 3.4 and construct a function $W_{s} \in H_{a}^{2 m}(G)$ such that

$$
\begin{gather*}
\left(\mathbf{B}_{i \mu}^{0}+\mathbf{B}_{i \mu}^{1}+(t+s) \mathbf{C}_{i \mu}\right) W_{s}=-s \mathbf{C}_{i \mu} u,  \tag{3.23}\\
\left\|W_{s}\right\|_{H_{a}^{2 m}(G)} \leq k_{2}|s| \sum_{i, \mu}\left\|\mathbf{C}_{i \mu} u\right\|_{H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)} . \tag{3.24}
\end{gather*}
$$

Combining (3.24) with (3.10), we obtain

$$
\begin{equation*}
\left\|W_{s}\right\|_{H_{a}^{2 m}(G)} \leq k_{3}|s| \cdot\|(u, \mathbf{A} u)\| . \tag{3.25}
\end{equation*}
$$

Clearly, problem (3.22) is equivalent to the following one:

$$
\begin{equation*}
\mathbf{A} Y_{s}=-\mathbf{A} W_{s}+\sum_{j=1}^{J_{s}} \beta_{j}^{s} f_{j}^{s}, \quad\left(\mathbf{B}_{i \mu}^{0}+\mathbf{B}_{i \mu}^{1}+(t+s) \mathbf{C}_{i \mu}\right) Y_{s}=0 \tag{3.26}
\end{equation*}
$$

where

$$
\begin{equation*}
Y_{s}=w_{s}-W_{s} \in H_{a}^{2 m}(G) \tag{3.27}
\end{equation*}
$$

3. To solve problem (3.26), we consider the bounded operator

$$
\begin{equation*}
\mathbf{L}_{t}=\left\{\mathbf{A}, \mathbf{B}_{i \mu}^{0}+\mathbf{B}_{i \mu}^{1}+t \mathbf{C}_{i \mu}\right\}: H_{a}^{2 m}(G) \rightarrow \mathcal{H}_{a}^{0}(G, \Gamma) \tag{3.28}
\end{equation*}
$$

Note that $\mathbf{C}_{i \mu}^{2} v \in H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)$ for any $v \in H_{a}^{2 m}(G)$ due to Lemma 3.1; for this reason, we can write $\mathcal{H}_{a}^{0}(G, \Gamma)$ instead of $\mathcal{H}_{a}^{0}(G, \Gamma) \dot{+} \mathcal{R}_{a}^{0}(G, \Gamma)$ in the definition of the operator $\mathbf{L}_{t}$ (cf. (2.3)). It follows from Theorem 6.1 in [16] and from Remark 3.1 that the operator $\mathbf{L}_{t}$ has the Fredholm property for any $t \in \mathbb{C}$.

Let us expand the space $H_{a}^{2 m}(G)$ in the orthogonal sum $H_{a}^{2 m}(G)=\operatorname{ker} \mathbf{L}_{t} \oplus E_{t}$, where $E_{t}$ is a closed subspace in $H_{a}^{2 m}(G)$. Clearly, the operator

$$
\begin{equation*}
\mathbf{L}_{t}^{\prime}=\left\{\mathbf{A}, \mathbf{B}_{i \mu}^{0}+\mathbf{B}_{i \mu}^{1}+t \mathbf{C}_{i \mu}\right\}: E_{t} \rightarrow \mathcal{H}_{a}^{0}(G, \Gamma) \tag{3.29}
\end{equation*}
$$

has the Fredholm property and its kernel is trivial. In particular, this means that

$$
\begin{equation*}
\|u\|_{H_{a}^{2 m}(G)} \leq k_{4}\left\|\mathbf{L}_{t}^{\prime} u\right\|_{\mathcal{H}_{a}^{0}(G, \Gamma)} \quad \forall u \in E_{t} \tag{3.30}
\end{equation*}
$$

Let $J=\operatorname{codim} \mathcal{R}\left(\mathbf{L}_{t}^{\prime}\right)$. It follows from Lemma 3.1 and Theorem A. 3 that the operator

$$
\mathbf{L}_{t s}^{\prime}=\left\{\mathbf{A}, \mathbf{B}_{i \mu}^{0}+\mathbf{B}_{i \mu}^{1}+(t+s) \mathbf{C}_{i \mu}\right\}: E_{t} \rightarrow \mathcal{H}_{a}^{0}(G, \Gamma)
$$

also has the Fredholm property, its kernel is trivial, and $\operatorname{codim} \mathcal{R}\left(\mathbf{L}_{t s}^{\prime}\right)=J$, provided that $|s| \leq s_{t}$, where $s_{t}>0$ is sufficiently small. Moreover, using estimates (3.30), (3.1), and (3.2), we obtain

$$
\|u\|_{H_{a}^{2 m}(G)} \leq k_{4}\left(\left\|\mathbf{L}_{t s}^{\prime} u\right\|_{\mathcal{H}_{a}^{0}(G, \Gamma)}+s_{t} \sum_{i, \mu}\left\|\mathbf{C}_{i \mu} u\right\|_{H_{a}^{2 m-m_{i \mu}-1 / 2}\left(\Gamma_{i}\right)}\right) \leq k_{5}\left(\left\|\mathbf{L}_{t s}^{\prime} u\right\|_{\mathcal{H}_{a}^{0}(G, \Gamma)}+s_{t}\|u\|_{H_{a}^{2 m}(G)}\right)
$$

for all $u \in E_{t}$. Taking $s_{t} \leq 1 /\left(2 k_{6}\right)$, we arrive at

$$
\begin{equation*}
\|u\|_{H_{a}^{2 m}(G)} \leq k_{6}\left\|\mathbf{L}_{t s}^{\prime} u\right\|_{\mathcal{H}_{a}^{0}(G, \Gamma)} \quad \forall u \in E_{t} . \tag{3.31}
\end{equation*}
$$

Since $\mathbf{L}_{t s}^{\prime}$ has the Fredholm property, the set $\left\{f \in H_{a}^{0}(G):(f, 0) \in \mathcal{R}\left(\mathbf{L}_{t s}^{\prime}\right)\right\}$ is closed and is of finite codimension $J_{s}$ in $H_{a}^{0}(G)$. It is easy to see that $J_{s} \leq J$.

Let $f_{1}^{s}, \ldots, f_{J_{s}}^{s}$ be an orthogonal normalized basis for the space

$$
H_{a}^{0}(G) \ominus\left\{f \in H_{a}^{0}(G):(f, 0) \in \mathcal{R}\left(\mathbf{L}_{t s}^{\prime}\right)\right\}
$$

Set $\beta_{j}^{s}=\left(\mathbf{A} W_{s}, f_{j}^{s}\right)_{H_{a}^{0}(G)}$. In this case, problem (3.26) admits a unique solution $Y_{s} \in E_{t}$, and, by virtue of (3.31) and (3.25), we have

$$
\begin{equation*}
\left\|Y_{s}\right\|_{H_{a}^{2 m}(G)} \leq k_{6}\left(\left\|\mathbf{A} W_{s}\right\|_{H_{a}^{0}(G)}+\sum_{j=1}^{J_{s}}\left|\beta_{j}^{s}\right|\right) \leq k_{7}|s| \cdot\|(u, \mathbf{A} u)\|+k_{6} J \max \left\{\beta_{1}^{s}, \ldots, \beta_{J_{s}}^{s}\right\} \tag{3.32}
\end{equation*}
$$

Estimating $\beta_{j}^{s}=\left(\mathbf{A} W_{s}, f_{j}^{s}\right)_{H_{a}^{0}(G)}$ by Schwarz' inequality and using (3.25), we obtain

$$
\left|\beta_{j}^{s}\right| \leq\left\|\mathbf{A} W_{s}\right\|_{H_{a}^{0}(G)} \leq k_{8}|s| \cdot\|(u, \mathbf{A} u)\|
$$

Combining this inequality with (3.32) yields

$$
\begin{equation*}
\left\|Y_{s}\right\|_{H_{a}^{2 m}(G)} \leq k_{9}|s| \cdot\|(u, \mathbf{A} u)\| \tag{3.33}
\end{equation*}
$$

4. Taking into account equality (3.27), from estimates (3.25) and (3.33) we deduce

$$
\begin{align*}
\left\|w_{s}\right\|_{L_{2}(G)} & \leq k_{10}\left\|w_{s}\right\|_{H_{a}^{2 m}(G)} \tag{3.34}
\end{align*} \leq k_{11}|s| \cdot\|(u, \mathbf{A} u)\|, ~\left\{k_{12}\left\|w_{s}\right\|_{H_{a}^{2 m}(G)} \leq k_{12} k_{11}|s| \cdot\|(u, \mathbf{A} u)\|,\right.
$$

where $w_{s}=Y_{s}+W_{s}$ is a solution of problem (3.22).
It follows from the boundedness of the embedding $H_{a}^{2 m}(G) \subset W^{m}(G)$ that the function $v_{s}$ defined by (3.21) belongs to $W^{m}(G)$, and $v_{s} \in \mathrm{D}\left(\mathbf{Q}_{t+s}\right)$ due to the second relation in (3.22). The desired inequality (3.20) follows from (3.21), (3.34), and (3.35).

Proof of Theorem 3.1. It follows from Lemma 2.1 in [11] that the spectrum of $\widetilde{\mathcal{L}}(\lambda)$ is discrete. Therefore, one can find a number $a$ such that $m-1<a<m$ and the lines $\operatorname{Im} \lambda=a+1-2 m$ and $\operatorname{Im} \lambda=a+1-m$ contain no eigenvalues of $\widetilde{\mathcal{L}}(\lambda)$. Fix two arbitrary numbers $t_{1}, t_{2} \in \mathbb{C}$. By Lemma 2.1 and Remark 3.1, the operators $\mathbf{Q}_{t}$ have the Fredholm property for all $t$ in the interval $I_{t_{1} t_{2}} \subset \mathbb{C}$ with the end points $t_{1}$ and $t_{2}$. Covering each point of the interval $I_{t_{1} t_{2}}$ by a disk of sufficiently small radius, choosing a finite subcovering of $I_{t_{1} t_{2}}$, and applying Theorems 3.2 and A.5, we see that ind $\mathbf{Q}_{t_{1}}=$ ind $\mathbf{Q}_{t_{2}}$. It follows from this fact and from Lemma 2.1 that ind $\mathbf{P}_{t_{1}}=$ ind $\mathbf{P}_{t_{2}}$.

Remark 3.3. Theorems 2.1 and 3.1 remain true in the case where the set $\mathcal{K}$ consists of finitely many disjoint orbits. The proofs need evident modifications.

## APPENDIX

A.1. Some properties of Sobolev and weighted spaces. Let $G$ and $\Gamma_{i}$ be the same as in Section 1.

Lemma A. 1 (see Lemma 3.5 in [7]). Let $k_{2}>k_{1}$ and $k_{2}-a_{2}>k_{1}-a_{1}$. Then the space $H_{a_{2}}^{k_{2}}(G)$ is compactly embedded in $H_{a_{1}}^{k_{1}}(G)$.

Fix an arbitrary index $i$ and set $\Gamma=\Gamma_{i}$. Let $g \in \bar{\Gamma} \backslash \Gamma$. Throughout this section, we assume without loss of generality that $g=0$ and $\Gamma$ coincides with the axis $O y_{1}$ in a sufficiently small neighborhood $\mathcal{O}_{\varepsilon}(0)$ of the origin. In this appendix, we use the notation $G^{\varepsilon}=G \cap \mathcal{O}_{\varepsilon}(0)$ and $\Gamma^{\varepsilon}=\Gamma \cap \mathcal{O}_{\varepsilon}(0)$, in which case $H_{a}^{k}\left(G^{\varepsilon}\right)=H_{a}^{k}\left(G^{\varepsilon},\{0\}\right)$.

Lemma A.2. If $u \in W^{k}\left(G^{\varepsilon}\right), k \geq 1$, then the following assertions are true:
(1) $u(y)=P(y)+v(y)$ for $y \in G^{\varepsilon}$, where $P(y)=\sum_{|\alpha| \leq k-2} p_{\alpha} y^{\alpha}, v \in W^{k}\left(G^{\varepsilon}\right) \cap H_{\delta}^{k}\left(G^{\varepsilon}\right) \forall \delta>0$ (if $k=1$, we set $P(y) \equiv 0)$; in particular, $u \in H_{k-1+\delta}^{k}\left(G^{\varepsilon}\right)$;
(2) $\left.D^{\alpha} u\right|_{y=0}=\left.D^{\alpha} P\right|_{y=0}$ for $|\alpha| \leq k-2$;
(3) $\sum_{|\alpha| \leq k-2}\left|p_{\alpha}\right|+\|v\|_{H_{\delta}^{k}\left(G^{\varepsilon}\right)} \leq c_{\delta}\|u\|_{W^{k}\left(G^{\varepsilon}\right)}$, where $c_{\delta}>0$ does not depend on $u$.

Proof. The proof follows from Lemma 4.9 in [7] for $k=1$ and from Lemma 4.11 in [7] for $k \geq 2$.

Lemma A.3. If $\psi \in W^{k-1 / 2}\left(\Gamma^{\varepsilon}\right), k \geq 1$, then the following assertions are true:
(1) $\psi(r)=P_{1}(r)+\varphi(r)$ for $0<r<\varepsilon$, where $P_{1}(r)=\sum_{\beta=0}^{k-2} p_{\beta} r^{\beta}$ and $\varphi \in W^{k-1 / 2}\left(\Gamma^{\varepsilon}\right) \cap$ $H_{\delta}^{k-1 / 2}\left(\Gamma^{\varepsilon}\right) \forall \delta>0\left(\right.$ if $k=1$, we set $\left.P_{1}(r) \equiv 0\right)$; in particular, $\psi \in H_{k-1+\delta}^{k-1 / 2}\left(\Gamma^{\varepsilon}\right)$;
(2) $\left.\left(d^{\beta} \psi / d r^{\beta}\right)\right|_{r=0}=\left.\left(d^{\beta} P_{1} / d r^{\beta}\right)\right|_{r=0}$ for $\beta=0, \ldots, k-2$;
(3) $\sum_{\beta=0}^{k-2}\left|p_{\beta}\right|+\|\varphi\|_{H_{\delta}^{k-1 / 2}\left(\Gamma^{\varepsilon}\right)} \leq c_{\delta}\|\psi\|_{W^{k-1 / 2}\left(\Gamma^{\varepsilon}\right)}$, where $c_{\delta}>0$ does not depend on $\psi$.

Proof. Consider a function $u \in W^{k}\left(G^{\varepsilon}\right)$ such that $\left.u\right|_{\Gamma^{\varepsilon}}=\psi$ and $\|u\|_{W^{k}\left(G^{\varepsilon}\right)} \leq 2\|\psi\|_{W^{k-1 / 2}\left(\Gamma^{\varepsilon}\right)}$. Now it remains to apply Lemma A.2.

Lemma A.4. Let $\psi \in W^{k-1 / 2}(\Gamma), k \geq 2$, and let

$$
\begin{equation*}
\left.\frac{d^{s} \psi}{d r^{s}}\right|_{y=0}=0, \quad s=0, \ldots, l \tag{A.1}
\end{equation*}
$$

for a fixed $l \leq k-2$. Then $\psi \in H_{k-2-l+\delta}^{k-1 / 2}(\Gamma) \forall \delta>0$ and

$$
\begin{equation*}
\|\psi\|_{H_{k-2-l+\delta}^{k-1 / 2}(\Gamma)} \leq c_{\delta}\|\psi\|_{W^{k-1 / 2}(\Gamma)} \tag{A.2}
\end{equation*}
$$

where $c_{\delta}>0$ does not depend on $\psi$.
Proof. It follows from relations (A.1) and Lemma A. 3 (assertions (1) and (2)) that

$$
\begin{equation*}
\psi(r)=\sum_{\beta=l+1}^{k-2} p_{\beta} r^{\beta}+\varphi(r), \quad 0<r<\varepsilon, \tag{A.3}
\end{equation*}
$$

where

$$
\begin{equation*}
\varphi \in H_{\delta}^{k-1 / 2}\left(\Gamma^{\varepsilon}\right) \subset H_{k-2-l+\delta}^{k-1 / 2}\left(\Gamma^{\varepsilon}\right), \quad \delta>0 . \tag{A.4}
\end{equation*}
$$

If $l=k-2$, then the sum in (A.3) is absent and the lemma follows from (A.4) and Lemma A.3(3).
If $l \leq k-3$, then the sum comprises the terms $r^{\beta}$ for $\beta \geq l+1$. One can directly verify that $r^{\beta} \in H_{k-2-l+\delta}^{k-1 / 2}\left(\Gamma^{\varepsilon}\right)$ for the above $\beta$ and for all $\delta>0$. Therefore, combining (A.3) with (A.4) and with Lemma A.3(3), we complete the proof.

Lemma A.5. Let $\psi \in H_{a+l}^{k-1 / 2}(\Gamma), l, k \in \mathbb{N}, a \in \mathbb{R}$, and let $b \in C^{\infty}(\bar{\Gamma})$ be a compactly supported function satisfying the relations $\left.\frac{\partial^{s} b}{\partial r^{s}}\right|_{r=0}=0, s=0, \ldots, l-1$. Then

$$
\begin{equation*}
\|b \psi\|_{H_{a}^{k-1 / 2}(\Gamma)} \leq c\|\psi\|_{H_{a+l}^{k-1 / 2}(\Gamma)} . \tag{A.5}
\end{equation*}
$$

Proof. Clearly, it suffices to carry out the proof for compactly supported functions $\psi$ and for $G$ and $\Gamma$ replaced by $K=\left\{y \in \mathbb{R}^{2}: 0<\omega<\omega_{0}\right\}$ and $\gamma=\left\{y \in \mathbb{R}^{2}: \omega=0\right\}$, respectively.

Denote by $\widehat{b} \in C^{\infty}(\mathbb{R})$ an extension of $b\left(y_{1}\right)$ to $\mathbb{R}$ and introduce the function $B\left(y_{1}, y_{2}\right)=\widehat{b}\left(y_{1}\right)$ for $\left(y_{1}, y_{2}\right) \in \mathbb{R}^{2}$. Clearly, we have

$$
\begin{equation*}
B \in C^{\infty}(\bar{K}),\left.\quad D^{\sigma} B\right|_{y=0}=0, \quad|\sigma| \leq l-1 . \tag{A.6}
\end{equation*}
$$

Let $u \in H_{a+l}^{k}(K)$ be a compactly supported extension of $\psi$ to the angle $K$ such that

$$
\begin{equation*}
\|u\|_{H_{a+l}^{k}(K)} \leq c_{1}\|\psi\|_{H_{a+l}^{k-1 / 2}(\gamma)} . \tag{A.7}
\end{equation*}
$$

It follows from Teylor's formula and (A.6) that $\left|D^{\sigma} B\right|=O\left(r^{l-|\sigma|}\right)$ for any $\sigma$; therefore,

$$
\begin{aligned}
\|B u\|_{H_{a}^{k}(K)}^{2} & =\sum_{|\alpha| \leq k} \int_{K} r^{2(a+|\alpha|-k)}\left|D^{\alpha}(B u)\right|^{2} d y \leq c_{2} \sum_{|\sigma|+|\zeta| \leq k} \int_{K} r^{2(a+|\sigma|+|\zeta|-k)}\left|D^{\sigma} B\right|^{2}\left|D^{\zeta} u\right|^{2} d y \\
& \leq c_{3} \sum_{|\zeta| \leq k} \int_{K} r^{2(a+l+|\zeta|-k)}\left|D^{\zeta} u\right|^{2} d y=c_{3}\|u\|_{H_{a+l}^{k}(K)}^{2}
\end{aligned}
$$

(recall that $u$ is compactly supported). Combining this estimate with (A.7), we finally obtain

$$
\|b \psi\|_{H_{a}^{k-1 / 2}(\gamma)} \leq\|B u\|_{H_{a}^{k}(K)} \leq c_{3}^{1 / 2}\|u\|_{H_{a+l}^{k}(K)} \leq c_{3}^{1 / 2} c_{1}\|\psi\|_{H_{a+l}^{k-1 / 2}(\gamma)}
$$

A.2. Some properties of Fredholm operators. Let $H_{1}$ and $H_{2}$ be Hilbert spaces, and let $P: \mathrm{D}(P) \subset H_{1} \rightarrow H_{2}$ be a linear (in general, unbounded) operator.

Definition A.1. The operator $P$ is said to have the Fredholm property if it is closed, its image is closed, and the dimension of its kernel ker $P$ and the codimension of its image $\mathcal{R}(P)$ are finite. The number ind $P=\operatorname{dim} \operatorname{ker} P-\operatorname{codim} \mathcal{R}(P)$ is called the index of the Fredholm operator $P$.

Theorem A. 1 (see Theorem 7.1 in [8]). Let $H$ be a Hilbert space such that $H_{1}$ is compactly embedded in $H$, and let the operator $P$ be closed. Then $\operatorname{dim} \operatorname{ker} P<\infty$ and $\mathcal{R}(P)=\overline{\mathcal{R}(P)}$ if and only if

$$
\|u\|_{H_{1}} \leq c\left(\|P u\|_{H_{2}}+\|u\|_{H}\right) \quad \forall u \in \mathrm{D}(P)
$$

The proof of the following result is contained in part 2 of the proof of Lemma 2.5 in [3].
Theorem A.2. Let $\dot{P}: \mathrm{D}(\dot{P}) \subset H_{1} \rightarrow H_{2}$ be a Fredholm operator such that $P$ is an extension of $\dot{P}$, i.e., $\dot{P} \subset P$. Suppose that $\operatorname{dim} \operatorname{ker} P<\infty, \mathcal{R}(P)=\overline{\mathcal{R}(P)}$, and $\operatorname{codim} \mathcal{R}(P)<\infty$. Then the operator $P$ is closed (hence, it has the Fredholm property).

Let $A: \mathrm{D}(A) \subset H_{1} \rightarrow H_{2}$ be a linear operator.
Theorem A. 3 (see Section 16 in [8]). Let the operator $P$ have the Fredholm property, $A$ be bounded, and $\mathrm{D}(A)=H_{1}$. Then the operator $P+A$ has the Fredholm property, ind $(P+A)=$ ind $P$, $\operatorname{dim} \operatorname{ker}(P+A) \leq \operatorname{dim} \operatorname{ker} P$, and $\operatorname{codim} \mathcal{R}(P+A) \leq \operatorname{codim} \mathcal{R}(P)$, provided that $\|A\|$ is sufficiently small.

Definition $\mathbf{A . 2}$ (see, e.g., $[8,6]$ ). The operator $A$ is said to be relatively compact with respect to $P$ or simply $P$-compact if $\mathrm{D}(P) \subset \mathrm{D}(A)$ and, for any sequence $u_{n} \in \mathrm{D}(P)$ with both $\left\{u_{n}\right\}$ and $\left\{P u_{n}\right\}$ bounded, $\left\{A u_{n}\right\}$ contains a convergent subsequence.

Theorem A. 4 (see Theorem 5.26 in Chapter 4 of [6]). Suppose that the operator $P$ has the Fredholm property and the operator $A$ is $P$-compact. Then the operator $P+A$ also has the Fredholm property and $\operatorname{ind}(P+A)=\operatorname{ind} P$.

Finally, we introduce a concept of a gap between closed operators. Let $S: \mathrm{D}(S) \subset H_{1} \rightarrow H_{2}$ be a linear operator. In the space $H_{1} \times H_{2}$, we introduce the norm

$$
\|(u, f)\|=\left(\|u\|_{H_{1}}^{2}+\|f\|_{H_{2}}^{2}\right)^{1 / 2} \quad \forall(u, f) \in H_{1} \times H_{2}
$$

Set $\delta(P, S)=\sup _{u \in \mathrm{D}(P)}:\|(u, P u)\|=1 \operatorname{dist}((u, P u), \operatorname{Gr} S)$, where $\operatorname{Gr} S$ is the graph of the operator $S$.

Definition A.3. The number $\widehat{\delta}(P, S)=\max \{\delta(P, S), \delta(S, P)\}$ is called a gap between the operators $P$ and $S$.

Theorem A. 5 (see Theorem 5.17 in Chapter 4 of [6]). Let the operator $P$ have the Fredholm property and $S$ be closed. Then the operator $S$ has the Fredholm property, ind $S=\operatorname{ind} P$, dim ker $S \leq$ $\operatorname{dim} \operatorname{ker} P$, and $\operatorname{codim} \mathcal{R}(S) \leq \operatorname{codim} \mathcal{R}(P)$ provided that the gap $\widehat{\delta}(P, S)$ is sufficiently small.

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[^1]:    ${ }^{1}$ See Definition A.1.

[^2]:    ${ }^{2}$ Lemma 2.3 in [3] was formulated for $a>2 m-1$. However, its proof remains true for any $a \in \mathbb{R}$.

