

3. n-step transition and stationarity

3.1 Def (X_n) MC with transition matrix $P = (p_{ij})_{i,j \in E}$

The matrix $P^{(n)} = (p_{ij}^{(n)})_{i,j \in E}$ with $p_{ij}^{(n)} = \sum_{i_1, \dots, i_{n-1} \in E} p_{ii_1} \dots p_{i_{n-1}j}$ is called n-step transition matrix of (X_n) .

3.2 Proposition With $P^{(0)} := I$, I l x l identity matrix, we have

$P^{(n)} = P^n$ and $(*) P^{(n+m)} = P^{(n)} P^{(m)}$ f.a. $n, m \in \mathbb{N}_0$.

3.3 Remark

$(*)$ in 3.2 is called Chapman-Kolmogorov equation.

3.4 Ex For $P = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ we have $P^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = P^{2k}$, $P^{2k+1} = P$ f.a. $k \in \mathbb{N}$.

3.5 Theorem α initial distribution of (X_n)

Then $\alpha_n \in [0, 1]^l$ defined by $(\alpha_n)_i = P(X_n = i)$ is given by $\alpha_n^T = \alpha^T P^n$.

α_n represents the distribution after n steps.

3.6 Def

A probability distribution π satisfying $\pi^T = \pi^T P$ is called stationary distribution of P (or of the MC (X_n)).

3.7 Remark

- 1. We have $\pi^T P^n = \pi^T$ f.a. $n \in \mathbb{N}$.
- 2. Move to stationary distributions later (existence/uniqueness).

4. Communication and Reducibility

GA (X_n) MC on state space E with trans. matrix $P = (p_{ij})_{i,j \in E}$ and initial distribution α .

4.1 Def Let $i, j \in E$.

Then j is accessible from i if $p_{ij}^{(n)} > 0$ for some $n \in \mathbb{N}_0$, where $P^{(0)} = I$.

Notation $i \rightarrow j$

4.2 Remark By definition $i \rightarrow i$, even if $p_{ii}^{(n)} = 0$ f.a. $n \geq 1$.

4.3 Theorem Let $i \in E$ s.t. $P(X_0 = i) > 0$.

Then $j \in E$ is accessible from i iff $P(\tau_j < \infty | X_0 = i) > 0$,

where $\tau_j : \Omega \rightarrow \mathbb{N}_0$ is a random variable with $\tau_j := \min \{n \geq 0 | X_n = j\}$
and $\tau_j = \infty$ if $X_n \neq j$ f.a. $n \geq 0$.

4.4 Remark

τ_j is called the hitting time of j .

If we consider $n > 0$ in the def., i.e., $T_j := \min \{n > 0 | X_n = j\}$,
we call T_j return time to j .

4.5 Def Let $i, j \in E$

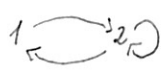
States i and j are said to communicate (notation $i \leftrightarrow j$)
if $i \rightarrow j$ and $j \rightarrow i$.

4.6 Prop./Def

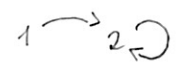
" \leftrightarrow " is an equivalence relation on the state space E .

The equivalence classes partitioning E are called communication classes.

4.7 Ex - two-state MCs



1 comm. class: $\{1, 2\}$



2 comm. classes: $\{1\}, \{2\}$

4.8 Def

If there exists only one communication class, then the MC is called
irreducible.

4.9 Ex

4.10 Def

A non-empty set $C \subseteq E$ is called closed, if $\sum_{j \in C} P_{ij} = 1$ (f.a. $i \in C$).
A state $j \in E$ is absorbing if $\{j\}$ is closed.

4.11 Remark

Closed subsets of E can be analyzed as isolated systems thus reducing complexity.

5. Periodicity

5.1 Def Let $i \in E$.

Then $d_i := \gcd \{n \geq 1 \mid P_{ii}^{(n)} > 0\}$ (with \gcd denoting the greatest common divisor) is called period of i . We set $d_i := \infty$ if $P_{ii}^{(n)} = 0$ f.a. $n \geq 1$.

If $d_i = 1$ then i is called aperiodic.

5.2 Ex - random walk

5.3 Remark - period d_i vs return to i

5.4 Theorem

Let $i, j \in E$ with $i \leftrightarrow j$. Then $d_i = d_j$.

5.5 Corollary Let (X_n) be irreducible.

Then all states of (X_n) have the same period, which is then called period of (X_n) .

5.6 Theorem Let (X_n) be irreducible

Then there exists a unique partition of E into d classes $C_0, C_1, \dots, C_{d-1} \subseteq E$ such that f.a. $k \in \{0, \dots, d-1\}$, $i \in C_k$:

$$\sum_{j \in C_{k+1}} P_{ij} = 1 \quad , \quad \text{with } C_d := C_0 \text{ by convention.}$$

and d maximal (i.e. there is no other such partition with more than d classes)
Moreover, d is the period of (X_n) .

The C_k are called cyclic classes.

5.7 Ex random walk with two cyclic classes

5.8 Remarks

1. 5.6 does not hold if (X_n) is not irreducible.
2. period of (X_n) vs return to cyclic classes