

A Sharp Interface Finite Volume Method for Variable Density Zero Mach Number Two-Phase Flow with Soluble Surfactants

Dipl.-Ing. **Stephan Gerber**¹, Dipl.-Ing. **Matthias Waidmann**²
M.Sc. **Warren O'Neill**²

Dr.-Ing. **Michael Oevermann**¹
Prof. Dr.-Ing. **Rupert Klein**²

¹ Konrad-Zuse-Zentrum
für Informationstechnik Berlin

² Freie Universität Berlin
Institut für Mathematik
AG Geophysical Fluid Dynamics



Goals of the Priority Programme:

- ▶ derive and expand **mathematical models** that describe relevant physico-chemical interface phenomena,
- ▶ improve the understanding of mechanisms and phenomena occurring at fluidic interfaces by means of rigorous **mathematical analysis** of the underlying pde-systems,
- ▶ **development** and analysis of **numerical methods** for the simulation of multiphase flow problems which **resolve the local processes at the interface**.
- ▶ **validation** of the models and numerical simulation methods by means of specifically designed **experiments**.

Our project objective within the SPP

A Sharp Interface **Finite Volume Method for Variable Density Zero Mach Number** Two-Phase Flow with Soluble Surfactants (= **Surface active agent**)

⇒

Development of a **locally second order conservative finite volume method** for immiscible two-phase flow with the following features:

- ▶ sharp resolution of discontinuities
 - ▶ cut cells
 - ▶ combined conservative **levelset** - volume of fluid approach
- ▶ **asymptotics based Poisson solver**
- ▶ variable, surfactant dependent surface tension
- ▶ conservative discretization for the surface surfactant equation

Our project objective within the SPP

Work packages

1. *Sharp interface* Finite Volume projection method
2. *Sharp interface* Poisson solver for arbitrary ratio of coefficients
3. Conservative discretization of the surface surfactant equation

plus

everything in an AMR framework

A M R framework

DNS: several million grid cells

AMR framework to be used for

- ▶ Adaptive Mesh Refinement
- ▶ Parallelization / Load Balancing
- ▶ Grid management
- ▶ Structure and handling of data

⇒ SAMRAI (Lawrence Livermore National Labs)

Scaling tests on HLRN with up to 2048 processors

(HLRN: Northern German super-computing center, Berlin/Hannover)

Work package 1:

Sharp Interface
Finite Volume Projection Method

Governing equations

Zero Mach-number variable density equations (Klein et al., 2001)

non-dimensional compressible Navier-Stokes equations

+

asymptotic expansion of primitive variables in Mach number

(e.g. $\rho = \rho^{(0)} + Ma \cdot \rho^{(1)} + Ma^2 \cdot \rho^{(2)} + \dots$)

+

separately equating only terms of same order of magnitude in Mach number due to $\lim_{Ma \rightarrow 0}$

\Rightarrow

- ▶ $\nabla \rho^{(0)} = 0 \rightarrow \rho^{(0)} = \rho^{(0)}(t)$
- ▶ $\nabla \rho^{(1)} = 0 \rightarrow \rho^{(1)} = \rho^{(1)}(t)$
- ▶ leading order system ($\rho^{(0)}, \dots$) contains $\rho^{(2)}$ in mom. eq.
- ▶ divergence constraint from energy equation
- ▶ decoupling from acoustic phenomena

Governing equations

Zero Mach-number variable density equations – leading order system

$$\text{mass : } \frac{d}{dt} \int_{\Omega} \rho dV = - \int_{\partial\Omega} \rho \mathbf{v} \cdot \mathbf{n} dS$$

$$\text{spec : } \frac{d}{dt} \int_{\Omega} \rho Y_s dV = - \int_{\partial\Omega} \rho Y_s \mathbf{v} \cdot \mathbf{n} dS - \int_{\partial\Omega} \mathbf{j}_s \cdot \mathbf{n} dS + \int_{\Omega} \dot{\sigma}_s dV$$

$$\begin{aligned} \text{mom : } \frac{d}{dt} \int_{\Omega} \rho \mathbf{v} dV = & - \int_{\partial\Omega} \rho \mathbf{v} (\mathbf{v} \cdot \mathbf{n}) dS - \int_{\partial\Omega} p^{(2)} \mathbf{n} dS + \int_{\Omega} \rho \mathbf{g} dV \\ & + \int_{\partial\Omega} \mathbf{T} \cdot \mathbf{n} dS + \int_{\partial\Omega \cap \partial\Sigma} \sigma \mathbf{t} dl \end{aligned}$$

energy (to be integrated):

$$(\nabla \cdot \mathbf{v}) = - \frac{1}{\rho c^2} \frac{dp^{(0)}}{dt} + \frac{1}{\rho c^2} \equiv \left[\nabla \cdot \mathbf{q} + \sum_s \mathbf{j}_s \cdot \nabla h_s + \sum_s \Delta h_s \dot{\sigma}_s \right]$$

Governing equations

Zero Mach-number variable density equations – leading order system

$$\text{mass : } \frac{d}{dt} \int_{\Omega} \rho dV = - \int_{\partial\Omega} \rho \mathbf{v} \cdot \mathbf{n} dS$$

$$\text{spec : } \frac{d}{dt} \int_{\Omega} \rho Y_s dV = - \int_{\partial\Omega} \rho Y_s \mathbf{v} \cdot \mathbf{n} dS - \int_{\partial\Omega} \mathbf{j}_s \cdot \mathbf{n} dS + \int_{\Omega} \dot{\sigma}_s dV$$

$$\begin{aligned} \text{mom : } \frac{d}{dt} \int_{\Omega} \rho \mathbf{v} dV = & - \int_{\partial\Omega} \rho \mathbf{v} (\mathbf{v} \cdot \mathbf{n}) dS - \int_{\partial\Omega} p^{(2)} \mathbf{n} dS + \int_{\Omega} \rho \mathbf{g} dV \\ & + \int_{\partial\Omega} \mathbf{T} \cdot \mathbf{n} dS + \int_{\partial\Omega \cap \partial\Sigma} \sigma \mathbf{t} dl \end{aligned}$$

energy (to be integrated):

$$(\nabla \cdot \mathbf{v}) = 0$$

Governing equations

Zero Mach-number variable density equations – hyperbolic part – advection

$$\text{mass : } \frac{d}{dt} \int_{\Omega} \rho dV = - \int_{\partial\Omega} \rho \mathbf{v} \cdot \mathbf{n} dS$$

$$\text{spec : } \frac{d}{dt} \int_{\Omega} \rho Y_s dV = - \int_{\partial\Omega} \rho Y_s \mathbf{v} \cdot \mathbf{n} dS - \int_{\partial\Omega} \mathbf{j}_s \cdot \mathbf{n} dS + \int_{\Omega} \dot{\sigma}_s dV$$

$$\begin{aligned} \text{mom : } \frac{d}{dt} \int_{\Omega} \rho \mathbf{v} dV = & - \int_{\partial\Omega} \rho \mathbf{v} (\mathbf{v} \cdot \mathbf{n}) dS - \int_{\partial\Omega} p^{(2)} \mathbf{n} dS + \int_{\Omega} \rho \mathbf{g} dV \\ & + \int_{\partial\Omega} \mathbf{T} \cdot \mathbf{n} dS + \int_{\partial\Omega \cap \partial\Sigma} \sigma \mathbf{t} dl \end{aligned}$$

energy (to be integrated):

$$(\nabla \cdot \mathbf{v}) = 0$$

Finite Volume Projection Method

Zero Mach-number variable density equations – predictor step (Schneider et al., JCP '99)

$$\text{mass : } \frac{d}{dt} \int_{\Omega} \rho dV = - \int_{\partial\Omega} \rho \mathbf{v} \cdot \mathbf{n} dS$$

$$\text{spec : } \frac{d}{dt} \int_{\Omega} \rho Y_s dV = - \int_{\partial\Omega} \rho Y_s \mathbf{v} \cdot \mathbf{n} dS - \int_{\partial\Omega} \mathbf{j}_s \cdot \mathbf{n} dS + \int_{\Omega} \dot{\sigma}_s dV$$

$$\begin{aligned} \text{mom : } \frac{d}{dt} \int_{\Omega} \rho \mathbf{v} dV = & - \int_{\partial\Omega} \rho \mathbf{v} (\mathbf{v} \cdot \mathbf{n}) dS - \int_{\partial\Omega} \mathbf{p}^{(2)} \mathbf{n} dS + \int_{\Omega} \rho \mathbf{g} dV \\ & + \int_{\partial\Omega} \mathbf{T} \cdot \mathbf{n} dS + \int_{\partial\Omega \cap \partial\Sigma} \sigma \mathbf{t} dl \end{aligned}$$

⇒ predicted values $\{\bar{\rho}^*, (\rho \bar{\mathbf{v}})^*, (\rho \bar{Y}_s)^*\}$ no divergence imposed!

Finite Volume Projection Method

Zero Mach-number variable density equations – predictor step (Klein, 2009)

$$\text{mass} : \quad \frac{d}{dt} \int_{\Omega} \rho dV = - \int_{\partial\Omega} \rho \mathbf{v} \cdot \mathbf{n} dS$$

$$\text{spec} : \quad \frac{d}{dt} \int_{\Omega} \rho Y_s dV = - \int_{\partial\Omega} \rho Y_s \mathbf{v} \cdot \mathbf{n} dS - \int_{\partial\Omega} \mathbf{j}_s \cdot \mathbf{n} dS + \int_{\Omega} \dot{\sigma}_s dV$$

$$\begin{aligned} \text{mom} : \quad \frac{d}{dt} \int_{\Omega} \rho \mathbf{v} dV = & - \int_{\partial\Omega} \rho \mathbf{v} (\mathbf{v} \cdot \mathbf{n}) dS - \int_{\partial\Omega} \mathbf{p}^{(2)} \mathbf{n} dS + \int_{\Omega} \rho \mathbf{g} dV \\ & + \int_{\partial\Omega} \mathbf{T} \cdot \mathbf{n} dS + \int_{\partial\Omega \cap \partial\Sigma} \sigma \mathbf{t} dl \end{aligned}$$

$$\text{energ} : \quad \frac{d}{dt} \int_{\Omega} (\rho\theta) dV = - \int_{\partial\Omega} (\rho\theta) \mathbf{v} \cdot \mathbf{n} dS$$

Finite Volume Projection Method

Zero Mach-number variable density equations – predictor step

$$P = \rho\theta = \left(p^{(0)}\right)^{\frac{1}{\gamma}} = \text{const.}$$

$$\text{energ : } \frac{d}{dt} \int_{\Omega} (\rho\theta) dV = - \int_{\partial\Omega} (\rho\theta) \mathbf{v} \cdot \mathbf{n} dS$$

$$P_t = -\nabla(P\mathbf{v})$$

$$\text{exact : } 0 = -P \nabla \mathbf{v} \rightarrow \boxed{\nabla \mathbf{v} = 0}$$

$$\text{disc : } \frac{P^{(n+1)} - P^{(n)}}{\Delta t} = - \left[\nabla(P\mathbf{v}) \right]^{(n+\frac{1}{2})} = 0$$

$$\text{pred : } \frac{P^{(n+1,*)} - P^{(n)}}{\Delta t} = - \left[\nabla(P\mathbf{v}) \right]^{(n+\frac{1}{2},*)}$$

Finite Volume Projection Method

Zero Mach-number variable density equations – predictor step

$$\text{mass : } \frac{d}{dt} \int_{\Omega} \rho dV = - \int_{\partial\Omega} (P \mathbf{v} \cdot \mathbf{n}) \left(\frac{1}{\theta} \right) dS$$

$$\text{spec : } \frac{d}{dt} \int_{\Omega} \rho Y_s dV = - \int_{\partial\Omega} (P \mathbf{v} \cdot \mathbf{n}) \left(\frac{Y_s}{\theta} \right) dS$$

$$\text{mom : } \frac{d}{dt} \int_{\Omega} \rho \mathbf{v} dV = - \int_{\partial\Omega} (P \mathbf{v} \cdot \mathbf{n}) \left(\frac{\mathbf{v}}{\theta} \right) dS - \int_{\partial\Omega} \rho^{(2)} \mathbf{n} dS + \int_{\Omega} \rho \mathbf{g} dV$$

$$\text{energ : } \frac{d}{dt} \int_{\Omega} (\rho\theta) dV = - \int_{\partial\Omega} (P \mathbf{v} \cdot \mathbf{n}) dS$$

Finite Volume Projection Method

Zero Mach-number variable density equations – 1st correction step

Projection scheme – MAC-projection

Advection velocity correction (at cell interfaces) due to use of $\rho^{(2),n}$ as predictor pressure $\Rightarrow \delta\pi = \rho^{(2),n+1} - \rho^{(2),n}$

$$\mathbf{v}^{n+\frac{1}{2}} = \mathbf{v}^{n+\frac{1}{2},*} - \frac{\Delta t}{2} \left(\frac{1}{\rho}\right)^{n+\frac{1}{2},*} \nabla \delta\pi$$

$$(\mathbf{P}\mathbf{v})^{n+\frac{1}{2}} = (\mathbf{P}\mathbf{v})^{n+\frac{1}{2},*} - \frac{\Delta t}{2} \left(\frac{P}{\rho}\right)^{n+\frac{1}{2},*} \nabla \delta\pi$$

$$0 = \nabla \left[(\mathbf{P}\mathbf{v})^{n+\frac{1}{2}} \right] = \nabla \left[(\mathbf{P}\mathbf{v})^{n+\frac{1}{2},*} \right] - \nabla \left[\frac{\Delta t}{2} \left(\frac{P}{\rho}\right)^{n+\frac{1}{2},*} \nabla \delta\pi \right]$$

$$\nabla \left[\frac{\Delta t}{2} \left(\frac{P}{\rho}\right)^{n+\frac{1}{2},*} \nabla \delta\pi \right] = \nabla \left[(\mathbf{P}\mathbf{v})^{n+\frac{1}{2},*} \right] \quad \text{var. coeff. Poisson eq.}$$

Finite Volume Projection Method

Zero Mach-number variable density equations – 1st correction step

Post-correction of all advective flux contributions

$$\underbrace{\frac{\bar{p}^{(n+1)} - \bar{p}^{(n)}}{\Delta t}}_{=0} = \underbrace{\frac{\bar{p}^{(n+1,*)} - \bar{p}^{(n)}}{\Delta t}}_{\Delta \bar{P}^*} + \underbrace{\frac{\bar{p}^{(n+1)} - \bar{p}^{(n+1,*)}}{\Delta t}}_{\Delta \tilde{P} = -\Delta \bar{P}^*}$$

$$\Delta \tilde{P} = -\frac{1}{\Delta V} \int_{\partial \Omega} \underbrace{\left(- \left[\frac{\Delta t}{2} \left(\frac{P}{\rho} \right)^{n+\frac{1}{2},*} \nabla \delta \pi \right] \cdot \mathbf{n} \right)}_{\tilde{F}(P) = P \partial \tilde{\mathbf{v}} \cdot \mathbf{n}} dS$$

Finite Volume Projection Method

Zero Mach-number variable density equations – 1st correction step

Post-correction of all advective flux contributions

$$\text{mass :} \quad \bar{\rho}^{n+1} = \bar{\rho}^{n+1,*} - \frac{\Delta t}{\Delta V} \int_{\partial\Omega} (P \partial \tilde{\mathbf{v}} \cdot \mathbf{n}) \left(\frac{1}{\theta} \right) dS$$

$$\text{spec :} \quad \rho \bar{Y}_s^{n+1} = \rho \bar{Y}_s^{n+1,*} - \frac{\Delta t}{\Delta V} \int_{\partial\Omega} (P \partial \tilde{\mathbf{v}} \cdot \mathbf{n}) \left(\frac{Y_s}{\theta} \right) dS$$

$$\text{mom :} \quad \rho \bar{\mathbf{v}}^{n+1,**} = \rho \bar{\mathbf{v}}^{n+1,*} - \frac{\Delta t}{\Delta V} \int_{\partial\Omega} (P \partial \tilde{\mathbf{v}} \cdot \mathbf{n}) \left(\frac{\mathbf{v}}{\theta} \right) dS$$

$$\text{energ :} \quad \bar{P}^{n+1} = \bar{P}^n = \bar{P}^{n+1,*} - \frac{\Delta t}{\Delta V} \int_{\partial\Omega} (P \partial \tilde{\mathbf{v}} \cdot \mathbf{n}) dS$$

Finite Volume Projection Method

Zero Mach-number variable density equations – 2nd correction step

Post-correction of pressure term in momentum equation

$$(\bar{\rho}\bar{\mathbf{v}})^{n+1} = (\bar{\rho}\bar{\mathbf{v}})^{n+1,**} - \frac{\Delta t}{\Delta V} \int_{\partial\Omega} \mathbf{J} \partial p^{(2)} \cdot \mathbf{n} dS$$

$$(\rho\mathbf{v})^{n+1} = (\rho\mathbf{v})^{n+1,**} - \Delta t \nabla \partial p^{(2)}$$

$$\mathbf{v}^{n+1} = \mathbf{v}^{n+1,**} - \frac{\Delta t}{\rho^{n+1}} \nabla \partial p^{(2)}$$

Finite Volume Projection Method

Zero Mach-number variable density equations – 2nd correction step

Post-correction of pressure term in momentum equation

$$(\rho \bar{\mathbf{v}})^{n+1} = (\rho \bar{\mathbf{v}})^{n+1,**} - \frac{\Delta t}{\Delta V} \int_{\partial \Omega} \mathbf{J} \partial p^{(2)} \cdot \mathbf{n} dS$$

$$(\rho \mathbf{v})^{n+1} = (\rho \mathbf{v})^{n+1,**} - \Delta t \nabla \partial p^{(2)}$$

$$0 = \nabla \mathbf{v}^{n+1} = \nabla \mathbf{v}^{n+1,**} - \nabla \frac{\Delta t}{\rho^{n+1}} \nabla \partial p^{(2)}$$

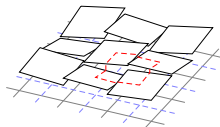
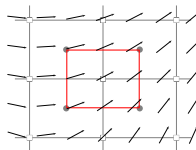
$$\nabla \frac{\Delta t}{\rho^{n+1}} \nabla \partial p^{(2)} = \Delta t \nabla \mathbf{v}^{n+1,**} \quad \text{var. coeff. Poisson eq.}$$

Finite Volume Projection Method

Inf-sup stable cell-centered **exact** projection

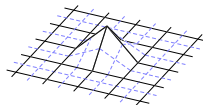
(Vater, Klein, Num. Math, 2009)

Exact control of divergence
on **dual cells**



Piecewise linear, discontinuous ansatz functions for momentum on primary cells

Bi-/trilinear ansatz functions for the pressure



Finite Volume Projection Method

(Some) features:

- ▶ conservative
- ▶ variable density flows,
ratio up to $\left(\rho_1(\mathbf{x}, t)/\rho_2(\mathbf{x}, t)\right) = \mathcal{O}(10^3)$
- ▶ monotonicity preserving 2nd order version
- ▶ interface representation via
 - ▶ levelsets
 - ▶ mass-preserving combined levelset-VOF approach

Finite Volume Projection Method

Next Steps

- ▶ optimize present code
- ▶ convergence study
⇒ proof 2^{nd} order accuracy of implementation
- ▶ complete AMR capability of **Poisson solvers**
- ▶ include diffusive terms into flow solver
- ▶ couple **levelset** with flow solver ⇒ interface
- ▶ cut-cell method ⇒ sharp interface representation

- ▶ discretization of surface tension forces
- ▶ solution of the surface surfactant equation
- ▶ surfactant dependent variable surface tension

Level set method

Interface tracking not as natural Lagrangian problem but as an Eulerian problem

- ▶ two steps involved:
 - ▶ solving transport pde $\frac{\partial \phi}{\partial t} + \mathbf{u}_{levelset} \cdot \nabla \phi = 0$
 - ▶ reinitialization: reset the interface by forcing $|\nabla \phi| = 1$
- ▶ pde solution via high order ode solver and hyperbolic advection schemes (WENO)
- ▶ reinitialization with fixed ϕ_0
- ▶ signed distance function which allows easy distinction between Ω^+ and Ω^-

Level set method - level set transport

local discretization: third order upstream central convection scheme

$$\frac{1}{6\Delta x} (\pm\phi_{i\mp 2,j,k} \mp 6\phi_{i\mp 1,j,k} \pm 3\phi_{i,j,k} \pm 2\phi_{i\pm 1,j,k})$$

temporal discretization: third order Runge Kutta scheme

$$\begin{aligned}u^{(1)} &= u^n + \Delta t L(u^n) \\u^{(2)} &= \frac{3}{4}u^n + \frac{1}{4}u^{(1)} + \frac{1}{4}\Delta t L(u^{(1)}) \\u^{n+1} &= \frac{1}{3}u^n + \frac{2}{3}u^{(2)} + \frac{2}{3}\Delta t L(u^{(2)})\end{aligned}$$

Level set method

Implementation of a constrained reinitialization routine by
D. Hartmann

Base idea: dividing the narrow band into two sets

- ▶ points close to the zero level (Gamma field)
- ▶ points adjacent to the Gamma field (given by the width of the narrow band)

different reinitialization equations for Gamma field /
narrow band

$$\frac{\partial \phi^\nu}{\partial \tau} + \mathbf{S}(\tilde{\phi}) (|\nabla \phi^\nu| - 1) = \beta \mathbf{F}^\nu$$

$$\mathbf{S}(\tilde{\phi}) = \frac{\tilde{\phi}}{\sqrt{\tilde{\phi}^2 + \Delta x^2}} \quad \text{with } \tilde{\phi} \text{ level set before reinitialization}$$

Level set method - constrained approach

- ▶ source term only active for Gamma field and ensures minimized zero level displacement

$$F_{i,j,k}^{\nu} = \frac{1}{\Delta x} \left(\tilde{r}^{i,j,k} \sum_{\alpha=1}^{M_{i,j,k}} \phi_{(i,j,k)\alpha}^{\nu} - \phi_{i,j,k}^{\nu} \right)$$

$\tilde{r}^{i,j,k}$ is calculated once before the reinitialization through

$$\tilde{r}^{i,j,k} = \tilde{\phi}_{i,j,k} \left(\sum_{\alpha=1}^{M_{i,j,k}} \tilde{\phi}_{(i,j,k)\alpha} \right)^{-1}$$

Level set example - moving circle

circle with 2 m diameter

iso-level for $\phi = 0$ shown with narrow band

Level set example - slotted disk

slotted disk with 2.3 m diameter
iso-level for $\phi = 0$ shown with narrow band

Work package 2:

Sharp Interface
Poisson solver for arbitrary ratio of
coefficients

Variable density Poisson solver

Finite volume formulation

$$\int_{\partial\Omega} \beta \nabla u \cdot \mathbf{n} \, dS = \int_{\partial\Omega} \nabla \cdot \mathbf{v} \, dS$$

with

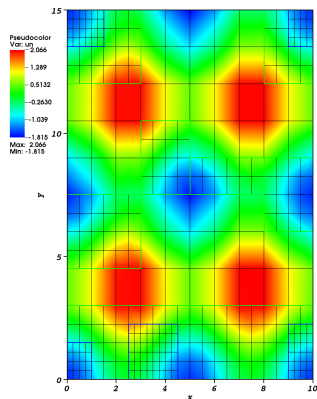
$$\nabla u \cdot \mathbf{n} = u_n \text{ on } \partial\Omega$$

- ▶ cell-centered Poisson solver: standard 5-/7-point stencil (2D/3D)
- ▶ node-centered Poisson solver: 9-/27-point stencil (bi-/tri-linear ansatz functions on primary cells)
- ▶ BiCGSTAB + AMG preconditioner (hypre library, LLNL)

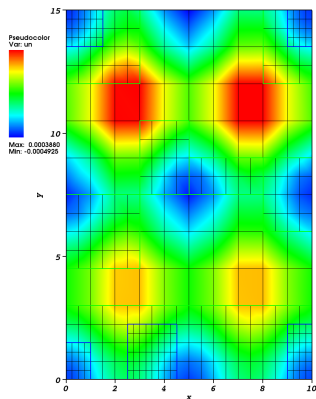
Variable density Poisson solver

2D - example node centered solver

$$v = \sin(4\pi x/x_{max}), \Delta x : \Delta y = 2 : 3$$



$$\beta = 1$$

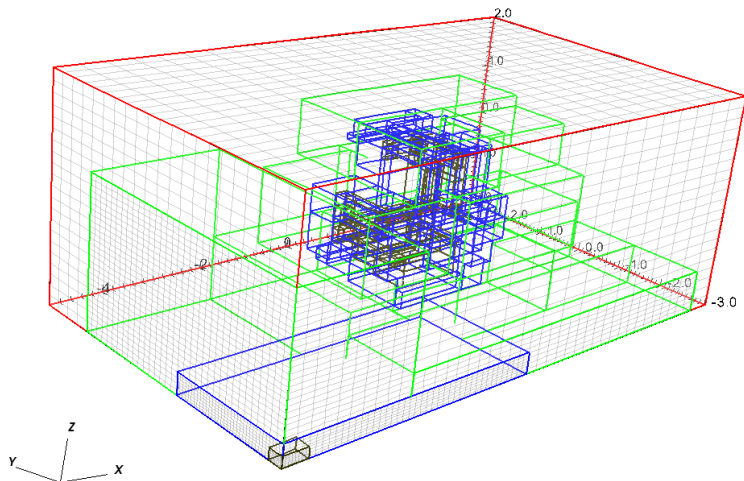


$$\beta = 5e3 + 1e3 \sin(2\pi x/x_{max})$$

Variable density Poisson solver

3D - example cell centered solver

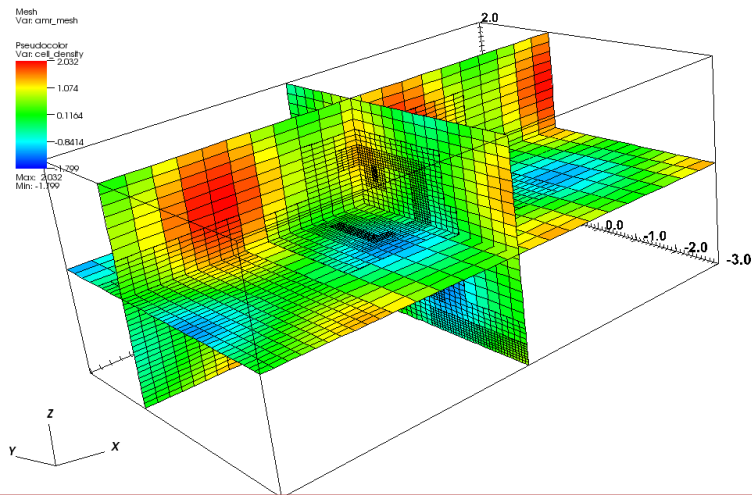
$$\mathbf{v} = \cos(\mathbf{x} \pi/2), \beta = 10 + x + y + z, \Delta x : \Delta y : \Delta z = 5 : 3 : 2$$



Variable density Poisson solver

3D - example cell centered solver

$$\mathbf{v} = \cos(\mathbf{x} \pi/2), \beta = 10 + x + y + z, \Delta x : \Delta y : \Delta z = 5 : 3 : 2$$



Poisson solver for arbitrary ratio of coefficients

Problem:

- ▶ large ratio of coefficients (e.g. ρ, μ, D)
- ▶ non-symmetric matrix

On each side of the interface we have

$$\nabla \cdot (\beta^+ \nabla u^+(\mathbf{x})) = f^+(\mathbf{x}), \quad \mathbf{x} \in \Omega^+$$

$$\nabla \cdot (\beta^- \nabla u^-(\mathbf{x})) = f^-(\mathbf{x}), \quad \mathbf{x} \in \Omega^-$$

with interface jump conditions

$$[[u]]_{\Gamma} = g(\mathbf{x}_{\Gamma})$$

$$[[\beta u_n]]_{\Gamma} = h(\mathbf{x}_{\Gamma})$$

Poisson solver for arbitrary ratio of coefficients

We are interested in small ratios

$$\beta^- / \beta^+ = \varepsilon \ll 1$$

and write

$$\begin{aligned}\nabla \cdot (\varepsilon^{-1} \beta^- \nabla u^+(\mathbf{x})) &= f^+(\mathbf{x}), & \mathbf{x} \in \Omega^+ \\ \nabla \cdot (\beta^- \nabla u^-(\mathbf{x})) &= f^-(\mathbf{x}), & \mathbf{x} \in \Omega^-\end{aligned}$$

Introducing the asymptotic expansion

$$\begin{aligned}u^+(\mathbf{x}) &= u^{(0,+)}(\mathbf{x}) + \varepsilon u^{(1,+)}(\mathbf{x}) \\ u^-(\mathbf{x}) &= u^{(0,-)}(\mathbf{x}) + \varepsilon u^{(1,-)}(\mathbf{x})\end{aligned}$$

Poisson solver for arbitrary ratio of coefficients

Solution strategie for the perturbation equations

1. Solve

$$\nabla \cdot (\beta^- \nabla u^{(0,-)}(\mathbf{x})) = f^-(\mathbf{x})$$

in Ω^- with boundary condition $u_n^{(0,-)} = u_{n,w}^-$ on $\partial\Omega^- \setminus \Gamma$
and interface condition $u^{(0,-)} = -g$ on Γ .

2. Solve the coupled problem

$$\nabla \cdot (\beta^- \nabla u^{(1,+)}(\mathbf{x})) = f^+(\mathbf{x}), \quad \mathbf{x} \in \Omega^+$$

$$\nabla \cdot (\beta^- \nabla u^{(1,-)}(\mathbf{x})) = 0, \quad \mathbf{x} \in \Omega^-$$

with

$$\llbracket u^{(1)} \rrbracket_{\Gamma} = u^{(1,+)} - u^{(1,-)} = 0,$$

$$\beta^- u_n^{(1,+)} - \varepsilon \beta^- u_n^{(1,-)} = h + \beta^- u_n^{(0,-)} \text{ on } \Gamma$$

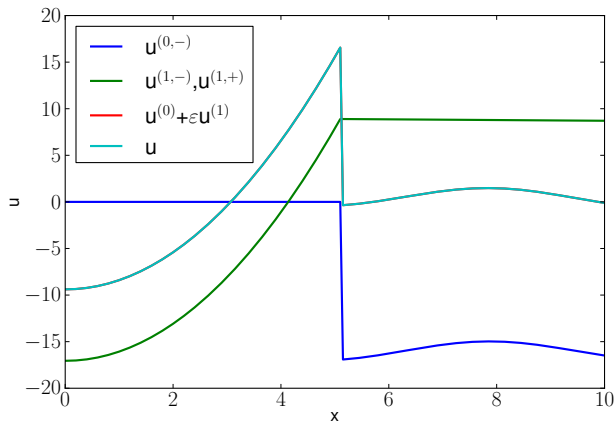
$$u_n^{(1,-)} = 0, \quad u_n^{(1,+)} = \varepsilon^{-1} u_{n,w}^+ \text{ on } \partial\Omega.$$

Poisson solver for arbitrary ratio of coefficients

1D example:

$$u^+ = x^2, \quad x \in (0, 5.14]$$

$$u^- = 10 + \sin(x), \quad x \in [5.14, 10)$$



Poisson solver for arbitrary ratio of coefficients

1D example:

$\varepsilon = \beta^- / \beta^+$	condition number		
	$u^{(0,-)}$	$u^{(1)}$	u (single step)
1	3.9e3	8.2e4	8.2e4
1e-3	3.9e3	6.3e4	6.3e7
1e-6	3.9e3	6.3e4	6.3e10
1e-9	3.9e3	6.3e4	6.3e13

Poisson solver for arbitrary ratio of coefficients

Perturbation equations

$$\begin{aligned}\varepsilon^{-1} & : \nabla \cdot (\beta^- \nabla \mathbf{u}^{(0,+)}(\mathbf{x})) & = & \mathbf{0} \\ \varepsilon^0 & : \nabla \cdot (\beta^- \nabla \mathbf{u}^{(1,+)}(\mathbf{x})) & = & \mathbf{f}^+(\mathbf{x}) \\ & : \nabla \cdot (\beta^- \nabla \mathbf{u}^{(0,-)}(\mathbf{x})) & = & \mathbf{f}^-(\mathbf{x}) \\ \varepsilon^n, n \geq 1 & : \nabla \cdot (\beta^- \nabla \mathbf{u}^{(n+1,+)}(\mathbf{x})) & = & \mathbf{0} \\ & : \nabla \cdot (\beta^- \nabla \mathbf{u}^{(n,-)}(\mathbf{x})) & = & \mathbf{0}\end{aligned}$$

Interface jump conditions

$$\begin{aligned}\varepsilon^0 & : \llbracket \mathbf{u} \rrbracket_{\Gamma}^{(0)} & = & \mathbf{u}^{(0,+)} - \mathbf{u}^{(0,-)} = \mathbf{g} \\ \varepsilon^n, n \geq 1 & : \llbracket \mathbf{u} \rrbracket_{\Gamma}^{(n)} & = & \mathbf{u}^{(n,+)} - \mathbf{u}^{(n,-)} = \mathbf{0} \\ \varepsilon^{-1} & : \llbracket \beta \mathbf{u}_n \rrbracket_{\Gamma}^{(0)} & = & \beta^- \mathbf{u}_n^{(0,+)} = \mathbf{0} \\ \varepsilon^0 & : \llbracket \beta \mathbf{u}_n \rrbracket_{\Gamma}^{(1)} & = & \beta^- \mathbf{u}_n^{(1,+)} - \beta^- \mathbf{u}_n^{(0,-)} = \mathbf{h} \\ \varepsilon^1 & : \llbracket \beta \mathbf{u}_n \rrbracket_{\Gamma}^{(1)} & = & -\beta^- \mathbf{u}_n^{(1,-)} = \mathbf{0}\end{aligned}$$