

Notation: map  $\cong$  continuous map,  $I = [0, 1]$

Def (Homotopy): let  $f_0, f_1: X \rightarrow Y$  continuous maps. They are homotopic if there exists a homotopy  $F$  between them, i.e. a continuous map  $F: X \times I \rightarrow Y$  s.t.  $f_0 = F(-, 0)$  and  $f_1 = F(-, 1)$ . We write  $f_0 \cong f_1$ .

Ex (0) Let  $X = [0, 2]^2$ ,  $Y = [0, 2]$ ,  $f_0: X \rightarrow [0, 2]: (x_1, x_2) \mapsto x_1$ , and  $f_1: X \rightarrow [0, 2]: (x_1, x_2) \mapsto x_2$ . Then  $f_0 \cong f_1$ .  
Indeed,  $F: [0, 2]^2 \times [0, 1] \rightarrow [0, 2]: ((x_1, x_2), t) \mapsto tx_2 + (1-t)x_1$  is the homotopy between  $f_0$  and  $f_1$ .

Def (Retraction). A retraction of  $X$  onto  $A$  is a map  $r: X \rightarrow X$  s.t.  $r(X) = A$  and  $r|_A = id_A$ .

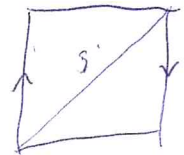
Def (Deformation retraction). A strong deformation retraction of  $X$  onto a subspace  $A \subset X$  is a homotopy  $F: X \times I \rightarrow X$  connecting  $id_X$  and a retraction  $r: X \rightarrow A$ .  
We say that it is strong if  $f_t|_A = id_A \quad \forall t \in I$ .

ex (1) Möbius band and  $S^1$ .

Let  $M = [0, 1]^2 / (0, x) \sim (1, 1-x)$  be the Möbius band, and

let  $S^1 := \{[(x_1, x_2)] \in M \mid x_1 = x_2\}$  be a circle.

Then there  $\exists$  strong deformation retraction of  $M$  onto  $S^1$ .



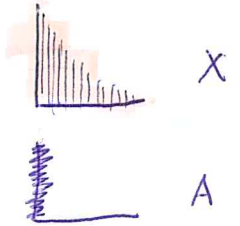
Indeed, let  $F: M \times [0, 1] \rightarrow M: ((x_1, x_2), t) \mapsto (x_1, tx_1 + (1-t)x_2)$

$f_0 \cong id_M$ ,  $f_1 = r: M \rightarrow S^1$  retraction onto  $S^1$ .

(2) Consider the space  $X := [0,1] \times \{0\} \cup \bigcup_{q \in \mathbb{Q} \cap [0,1]} \{q\} \times [0,1-q]$ ,

and the subspace  $A \subset X = A := [0,1] \times \{0\}$ .

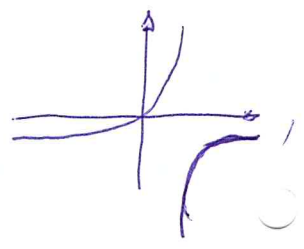
We construct a deformation retraction of  $X$  onto  $A$ .



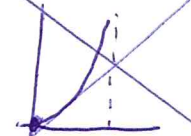
Define first, for  $t \in [0,1)$ ,  $\alpha_t(x)$ :

$$\alpha_t : [1,2] \rightarrow [0,1] : x \mapsto \alpha_t(x) = (2-x) \cdot \frac{1}{x^{t/(1-t)}}$$

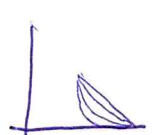
Don't panic: from high-school,  $\frac{t}{1-t}$  is something like



so in  $[0,1)$  we have



$$\frac{t}{1-t} \rightarrow \infty \text{ as } t \rightarrow 1.$$



Then,  $\alpha_t(x) \xrightarrow{t \rightarrow 1} 0 \quad \forall x > 1$ , and  $\alpha_t(1) = 1 \quad \forall t \in [0,1)$ .

Define  $\alpha_1 : [1,2] \rightarrow [0,1]$  as  $\alpha_1(x) = \begin{cases} 1 & \text{if } x=1 \\ 0 & \text{else} \end{cases}$

Then  $A : [1,2] \times I \rightarrow [0,1] : A(x,t) = \alpha_t(x)$  is a homotopy connecting  $\alpha_0 : x \mapsto (2-x)$  and  $\alpha_1$ .

Now we can define the deformation retraction:

$$F : X \times I \rightarrow X : ((x_1, x_2), t) \mapsto \begin{cases} (x_1, x_2) & \text{if } x_2 \leq \alpha_t(1+x_1) \\ (x_1, \alpha_t(1+x_1)) & \text{else} \end{cases}$$

Def.

(Homotopy equivalence). A homotopy equiv. between  $X$  and  $Y$  is a map  $f : X \rightarrow Y$  s.t. there exists  $g : Y \rightarrow X$  with  $g \circ f \simeq \text{id}_X$ ,  $f \circ g \simeq \text{id}_Y$ . We denote  $X \simeq Y$ .

Rem (1) If  $X$  deformation retracts onto  $A$ , then  $r \circ i = \text{id}_A$  and  $i \circ r \simeq \text{id}_X$ . Hence,  $X \simeq A$ .

Thm. If  $X \simeq Y \Rightarrow H_n(X) \cong H_n(Y) \quad \forall n$ .

Here we prove a smaller result:

Prop. If  $A$  is a retract of  $X$ , then the maps  $H_n(A) \rightarrow H_n(X)$  are injective.

Pf.  $H_n(-)$  is a functor <sup>Marcel's remark!</sup>  $\text{in } \mathcal{A}$ . Hence,  $\text{id}_{H_n(A)} = H_n(\text{id}_A) = H_n(r \circ i) = H_n(r) \circ H_n(i) \Rightarrow H_n(i): H_n(A) \rightarrow H_n(X)$  inj.  $\square$

Def (Contractibility). Let  $X$  be a space,  $x_0 \in X$ . We say that  $X$  is contractible if  $X \simeq \{x_0\}$ . Equivalently,  $\text{id}_X$  is homotopic to  $X \rightarrow x_0 \hookrightarrow X$ .

Rem (2)  $X$  contractible  $\Rightarrow X$  path-connected. Indeed, let  $F: X \times I \rightarrow X$  be the homotopy connecting  $\text{id}_X$  and the constant map  $x_0$ .

Let  $\tilde{x} \in X$ . Then  $F(\tilde{x}, -): I \rightarrow X: t \mapsto f_t(\tilde{x})$  is a path from  $\tilde{x}$  to  $x_0$ .

Ex (3)  $X$  path-connected  $\not\Rightarrow X$  contractible! '\$'.

Ex (3) A segment is trivially contractible. Therefore, the space  $X$  from (2) is contractible, since  $\mathbb{I} \simeq L \simeq \cdot$  (point).

~~If  $X$  has a (strong) deformation retract onto a point, by definition  $X$  is contractible (see Rem. (1)). We ask ourselves if the converse is  $X$  (strong) def. retr. onto a point  $\Rightarrow$  contractible  $\Leftarrow$ ?~~

The answer is no. Before we see a counterexample, we prove the following theorem.

Theorem  $\rightarrow$  Before the proof, write application!

(3)

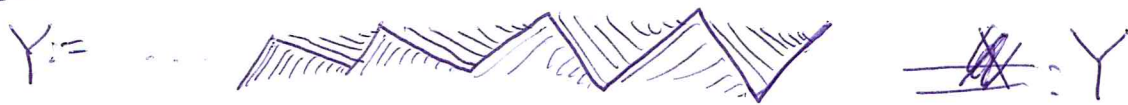
Thm. If a space  $X$  has a strong def. retract onto  $x_0 \in X$ ,  
 $\forall$  then  $\forall U \subseteq_{\text{op.}} X, x_0 \in U, \exists V \subseteq_{\text{op.}} U, x_0 \in V$  s.t.  
the inclusion  $i: V \hookrightarrow U$  is homotopic to a constant map  $\#$   
 $x_0: V \rightarrow U: V \mapsto x_0$ .

Ex. (4). Thm  $\Rightarrow$   $X = \bigcup_{i=1}^{\infty} U_i$  doesn't have a <sup>strong</sup> def.  
retract onto  $(x_1, x_2)$  if  $x_2 \neq 0$ , since ~~every~~  $\exists \epsilon_0 > 0$  s.t.  
 $\forall B_\epsilon(x_0), 0 < \epsilon < \epsilon_0, B_\epsilon(x_0) \cap X$  is not path-connected (indeed,  
 $\infty$ -many connected components!!).

Pf [

Ex (5) Contractible ~~is~~ <sup>strong</sup> deformation retract onto a point.

Consider



As ~~is~~ Similarly as in example (2),



and a line is obviously contractible. Therefore  $Y$  is contractible.

But! If it had a strong def. retract onto  $y_0 \in Y$ ,

then  $\forall U \ni y_0, \exists V \subset U$  s.t.  $V$  is contractible.

But given  $y_0 \in Y, \exists \epsilon_0 > 0$  s.t.  $B_\epsilon(y_0)$  ~~is~~ is not path-connected  $\forall 0 < \epsilon < \epsilon_0$   $\nexists$ .